#### Modelling shared e-scooters: A spatial regression approach

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Keywords: shared e-scooters, micromobility, transport demand modelling, spatial regression

- 28 Introduction
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Shared e-scooters have surprised many with their sudden and plentiful appearance. In 2018, just one year after their introduction, ridership in the US alone already surpassed 38M (NACTO 2019). Despite the popularity these numbers indicate, shared e-scooters have sparked heated debates between citizens, municipal governments and suppliers about road and curb use, safety and social equity.

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Research to guide policy-making, however, is still in its infancy. This holds particularly true for spatial aspects of shared e-scooter trips: Where, how and why are they being used? Providing rigorous answers to these questions can support transport planning and regulation in various ways, such as informing the extensions of bikeway networks, identifying suitable locations for parking corrals and predicting future

- 39 demand.
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In this paper, we first review the extant literature on the spatio-temporal use of shared e-scooters. We then analyze spatial drivers of demand using a Negative Binomial-distributed generalized linear mixed model (GLMM) with a random effect following a conditional autoregressive (CAR) correlation model on e-scooter trip destination count data in Louisville (KY). We close with a discussion of our findings

- 45 in the context of the broader literature on bike sharing to identify similarities and differences.
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47 Our contributions are twofold. First, we identify spatial drivers of demand using a dataset that has not yet been used before, thus offering lessons on the generalizability of results in comparison to previous 48 studies. Second, we estimate and compare several Negative Binomial-distributed non-spatial and spatial 49 50 generalized linear (mixed) models. This is novel as most previous papers modeling spatial demand of 51 shared e-scooters either focus on descriptive analyses (Espinoza et al., 2020; McKenzie, 2019), use 52 (non-spatial) linear regression models (Bai and Jiao, 2020; Hawa et al., 2020) or spatial linear regression 53 models assuming normally distributed residuals (Arnell et al., 2020; Caspi et al., 2020; Zuniga-Garcia 54 and Machemehl, 2020) – an assumption that does not hold for (non-negative) count data.

## 56 Literature review

Several authors have started to analyze spatial drivers of shared e-scooter demand using a variety of
methods. In this Section, we review these contributions grouped by method. First, we summarize studies
giving descriptive overviews only. We proceed with studies using (non-spatial) linear regression models
and finally summarize studies using spatial linear regression models.

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63 McKenzie (2019) analyzed the spatio-temporal use of shared e-scooters in Washington, D.C. Using 3<sup>1</sup>/<sub>2</sub> 64 months of trip data accessed at a 5-min temporal resolution from the openly accessible API, he found 65 shared e-scooter trips to exhibit a mid-day peak and a (slight) morning peak. He further analyzed trip 66 starts by land use type finding that  $\sim 41\%$  of all trips originated in areas of recreational or public land 67 use, ~36% in areas of commercial land use and ~23% in areas of residential land use. He concluded by 68 reiterating Noland's (2019) hypothesis that a substantial share of e-scooter trips may be of recreational 69 use. Espinoza et al. (2020) used data accessed at a 10-min temporal resolution from Bird in the city of 70 Atlanta (GA). They created buffers around origins and destinations of e-scooter trips and counted points 71 of interests (POIs) within those buffers. Interestingly and in contrast to McKenzie (2019), they found 72 POIs associated with their 'business' category (corresponding to the Google Maps API categories 73 Accounting, Banks, Business, Car Rental, Embassy, Insurance Agency, Lawyer, Local Government 74 Office, Real Estate, School) to appear most frequent near trip origins and destinations. Parking, food

75 (Bakery, Cafe, Restaurant, Supermarket) and recreation (Aquarium, Bar, Casino, Library, Museum,

Park, Place of Worship, Stadium) POIs also appeared frequently near trip origins and destinations while public transit stops only showed low counts. One limitation of this study is the missing link between the number of POIs in a specific category and their *relative* impact on e-scooter trips. This is addressed by the studies using regression models surveyed next.

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81 Bai and Jiao (2020) analyzed e-scooter booking data from Austin (TX) and Minneapolis (MN) using a 82 (non-spatial) negative binomial regression model on spatially aggregated trip data. They found the CBD 83 and university campuses to be hotspots in both cities while temporal usage patterns differed (rides per 84 weekday in Austin showed a peak on Saturdays while they were more evenly distributed in 85 Minneapolis). Hawa et al. (2020) analyzed e-scooter data from Washington, D.C. using a (non-spatial) 86 linear regression model on hourly counts of spatially aggregated data. They also found proximity to the 87 CBD to be an important predictor of demand for shared e-scooters, while it was also positively 88 correlated with higher population densities and bikeways. Despite yielding first insights, these analyses 89 have the methodological shortcoming of not accounting for spatial autocorrelation. The independence 90 condition of explanatory variables is likely violated due to the existence of spatial clusters (i.e., 91 employment centers, shopping centers, residential areas) or spatial correlation of unobserved effects, 92 which suggest the use of spatial regression models as employed in the studies surveyed next.

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94 Arnell et al. (2020) analyzed e-scooter trip origin counts aggregated by spatial bins (500m diameter) 95 from Nashville (TN) and San Diego (CA) using a spatial lag regression model. They found the most important predictor of trip starts to be rebalancing points (or e-scooter supply). With increasing distance 96 97 from the CBD, origin counts in Nashville decreased (San Diego showed the opposite, yet a much weaker 98 and less significant effect) and transit stops had a positive influence on origin counts in Nashville (San 99 Diego, again, showed the opposite, yet a non-significant effect). Caspi et al. (2020) analyzed e-scooter 100 trip data from Austin (TX) using a spatial lag regression model on spatially aggregated count data. 101 Methodologically, they removed most cells with zero counts, added one to each dependent variable and 102 took the natural logarithm of the value to approximate normally distributed residuals. They found most 103 trips to be conducted in central Austin and to be associated with areas of denser employment and bicycle 104 infrastructure. Finally, Zuniga-Garcia and Machemehl (2020) used the same dataset from Austin (TX) 105 to apply a spatial error regression model on e-scooter trip origins and destinations. They found the 106 University of Texas at Austin to be the strongest and most significant spatial driver of demand (both 107 for origins and destinations, weekdays and weekends). Population density also had a positive and 108 significant influence on e-scooter stops and origins as did employment density (yet with a much smaller 109 coefficient). Most transit-related variables (no. of boardings and alightings, stop density, bus frequency) 110 had a significant and negative, yet not substantial effect on e-scooter trip stops and origins.

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112 The latter three studies (Arnell et al., 2020; Caspi et al., 2020; Zuniga-Garcia and Machemehl, 2020) 113 all employ spatial lag / error linear regression models on count data. Yet, one of the main assumptions 114 of this type of models is the Normal distribution of residuals which does not hold for count data as it is 115 non-negative. Transforming the counts (Arnell et al., 2020; Caspi et al., 2020) is one way to address 116 this limitation. Another way, which has not been explored until now to the knowledge of the authors 117 yet appears promising, is to use the family of generalized linear (mixed) models which allows for more 118 flexibility on the distributional assumptions of the residuals, i.e. a Poisson or Negative Binomial 119 distribution. Using such a model, a transformation of the dependent variable becomes unnecessary.

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In the following, we introduce our data, specify and estimate a conditionally autoregressive (CAR)
 generalized linear mixed model (GLMM) using a Negative Binomial (NB) distribution.

#### 124 Data

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We use 15 months (Aug/2018 - Oct/2019) of openly accessible shared e-scooter trip data from 126 Louisville (KY) (Louisville Metro Government, 2019). Four e-scooter companies are operating within 127 a 68 mi<sup>2</sup> service area: Bird (since Aug/2018), Lime (since Nov/2018), Bolt (since Jul/2019) and Spin 128 129 (since Aug/2019).

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131 The initial number of e-scooter trips in the dataset was 434,582. Several data cleaning steps were 132 necessary to exclude unrealistic or non-informative trips, such as trips with a distance of 0 or more than

133 25 miles, durations of 0 or more than 12 hours and average speeds of more than 30 mi/h. 351,514 trips remained.

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136 We aggregated trip stops by US census blocks within the service area (5'942 blocks) and combined 137 them with the latest-available block-level census information on population (2010) and employment (2015), and Open Street Maps (OSM) data on locations for bus stops, The University of Louisville, 138 139 restaurants, hotels, stadiums and length of bikeways using QGIS. We further included the area (square 140 miles) of each block as a control variable as census blocks substantially differ in size. Table 1 shows an

- 141 overview of basic statistics for the dependent and independent variables.
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#### 143 Table 1

144 Summary of dependent and independent variables per US Census Block used in the regression models. 145

Variable	Unit	Min	1 st Quartile	Median	Mean	3rd Quartile	Max
E-scooter trip stops	Count	0.000	1.000	3.000	57.980	20.000	18'203.000
Restaurants	Count	0.000	0.000	0.000	0.064	0.000	15.000
Bus stops	Count	0.000	0.000	0.000	0.183	0.000	7.000
University of Louisville	Count	0.000	0.000	0.000	0.013	0.000	2.000
Hotels	Count	0.000	0.000	0.000	0.007	0.000	5.000
Stadiums	Count	0.000	0.000	0.000	0.003	0.000	3.000
Population	Count (thousands)	0.000	0.004	0.029	0.045	0.057	2.269
Jobs	Count (thousands)	0.000	0.000	0.000	0.032	0.004	13.636
Bikeways	Miles	0.000	0.000	0.000	0.046	0.058	4.083
Area	Square miles	0.000	0.003	0.005	0.011	0.010	1.082

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Figure 1 displays descriptive analyses of the dataset. Shared e-scooter trip starts show clear afternoon 148 peaks both for weekdays and weekends (Figures 1a, 1b). Many trips are short. The median distance is 149 150  $\sim 0.8$  mi (Figure 1c) and the median trip duration is 9 min (Figure 1d). The share of rentals per weekday reveals a peak on Saturdays (Figure 1e) and the distribution of number of e-scooter trip stops per block 151

152 shows a high share (~24%) of zero observations (Figure 1f).

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#### 155 Figure 1

156 Descriptive analyses of shared e-scooter trips in Louisville (KY).

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Figure 2 displays a map of Louisville with blocks colored by number of e-scooter trip stops. First hot spots (dark blue, top to bottom) such as the CBD, the Louisville Loop / city-end of the Big Four (Pedestrian) Bridge, Cave Hill National Cemetery, the University of Louisville and Cardinal Stadium can be observed.

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#### 166 Figure 2

- Map of Louisville (KY) with census blocks colored by number of e-scooter trip stops and resulting hotspots.
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### 172 Methods

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174 The integrated and aggregated census block-level dataset includes a substantial number of blocks with 175 0 observed e-scooter trip stops ( $\sim 24\%$ ) and overdispersion (var/mean  $\sim 2'310$ ) which suggests using a 176 Negative Binomial distribution instead of a Poisson distribution. Consequently, we first estimate a 177 generalized linear model (GLM) and a generalized linear mixed model (GLMM) using the Negative 178 Binomial distribution (for estimates and summary statistics, see Table 2) in R (packages MASS and 179 lme4, respectively) using Maximum Likelihood and log link functions. While the GLM already indicates reasonable explanatory power (Naegelkerke  $R^2$ : 0.39), the model fit improves substantially by 180 181 introducing random effects (AIC GLM: 44633, AIC GLMM: 44078). Yet, the model still exhibits a 182 significant level of spatial autocorrelation (Moran's I statistic on GLMM residuals = 0.55, p = 0.001).

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184 Spatial autocorrelation can be accounted for by including spatial lags or spatial errors. The rational for

modeling spatial lags is the assumption of a diffusion process (i.e., events in one place increase the likelihood of similar events in neighboring places) while the rationale for modeling spatial errors is the

assumption of spatial correlation in the error terms (which, in turn, is indicative for omitted spatial

variables). As Arnell *et al.* (2020) have shown (and intuition suggests), e-scooter drop-off locations ("rebalancing points") are an important predictor of e-scooter trip origins. As vehicle IDs are not reported in the Louisville dataset and only realized trips are included, we cannot identify 'juicing-trips' (to reload the vehicles' batteries) and rebalancing points, and thus have to treat supply as part of the (spatially correlated) unobserved error. This suggests the use of a spatial error model.

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Spatial error terms can be modeled using a conditional (CAR) or simultaneous (SAR) autoregressive correlation model. CAR-type models (originally introduced by Besag, 1974) account for local spatial autocorrelation (i.e., only the influence of direct neighbors), while SAR-type models account for global spatial autocorrelation. As it is reasonable to assume that users will park their e-scooter not much further than a census block from their final destination, we continue using a Negative Binomial-distributed GLMM with a random effect following a conditional autoregressive (CAR) correlation model ('Spatial GLMM') of the form

 $ln(y) = \alpha + \beta X + u$ 

Here, y denotes the number of e-scooter stops in the 15 months period per census block,  $\beta$  X the coefficients and vector of fixed effects as shown in Table 1, followed by the random effect u with a CAR-type covariance matrix of the form  $\lambda (I - \rho N)^{-1}$  where N is an adjacency matrix between the census blocks (i.e., a matrix with elements 1 if the blocks are adjacent and 0 otherwise). We estimate the model in R (package spaMM) using Maximum Likelihood and an ln link function.

### 210 Results

212 The estimated spatial GLMM model as well as results for the non-spatial GLM and GLMM models are 213 shown in Table 2. The spatial correlation structure of the random effect further improves the model fit 214 from the non-spatial GLMM (AIC: 44'078) to the spatial GLMM (AIC: 38'981). In the following, we 215 thus focus on the results of the spatial GLMM. It becomes apparent that the area of a census block has 216 a strong influence (11.28) of the number of e-scooter stops in it (cf. Fig. 2), which was expected. 217 Population size has the second strongest effect (2.29) on number of e-scooter stops, interestingly much 218 stronger than the number of jobs (0.33) in a census block. This indicates that a substantial share of users 219 drive shared e-scooters to their inner-city homes. The length of bikeways in/adjacent to a block has the 220 third-strongest effect (1.43). Though bikeways may not be destinations per se, this does show that e-221 scooters are parked substantially more near where they are established. In terms of points of interests, 222 the University of Louisville is the strongest attractor of shared e-scooters (0.98). Interestingly, hotels 223 appear to be attractors (0.36), too, indicating that tourists may be form a substantive share of e-scooter 224 users in Louisville. Restaurants and bus stops also show significant, yet less substantive positive effects 225 on e-scooter trip stops (0.18 and 0.21, respectively).

#### 228 Table 2

Estimations results for shared e-scooter trip stops. See Table 1 for a description of the variables.

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		GLM			GLMM			Spatial GLMM		
Variable	Unit	Estimate	SE	z-value	Estimate	SE	z-value	Estimate	SE	t-value
(Intercept)		2.91	0.03	94.62	1.04	0.04	27.03	0.51	0.05	9.54
Restaurants	Count	0.93	0.06	15.86	0.70	0.07	10.52	0.18	0.05	3.50
Bus stops	Count	0.41	0.05	8.86	0.39	0.05	7.22	0.21	0.05	4.66
University of Louisville	Count	1.22	0.19	6.46	2.20	0.21	10.31	0.98	0.25	3.92
Hotels	Count	1.15	0.21	5.45	0.84	0.24	3.53	0.36	0.18	1.97
Stadiums	Count	0.97	0.33	2.90	1.42	0.38	3.78	0.19	0.28	0.70
Population	Count (thousands)	-0.16	0.36	-0.43	0.66	0.43	1.55	2.29	0.36	6.41
Jobs	Count (thousands)	1.98	0.09	20.95	0.75	0.11	7.02	0.33	0.08	4.00
Bikeways	Miles	5.21	0.26	20.14	2.82	0.30	9.44	1.43	0.24	5.84
Area	Square miles	1.20	1.08	1.11	-1.58	1.22	-1.30	11.28	1.10	10.26
ρ								0.12		
λ								2.25		
n		5'942			5'942			5'942		
AIC		44'633			44'078			38'981		
Naegelkerke R <sup>2</sup>		0.39								
Marginal log-likelihood		-22'306			-22'027			-19'478		

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#### 233 Discussion

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235 Our results largely confirm previous results on spatial drivers of shared e-scooter demand and thus add further evidence to their generalizability. For Louisville, we find that population and bikeways have 236 237 particularly strong effects on shared e-scooter stops. This confirms previous findings for Washington 238 D.C. (Hawa et al., 2020) and Austin (TX) (Caspi et al., 2020; Zuniga-Garcia and Machemehl, 2020). 239 University campuses have also previously been found to have a substantially positive effect in Austin 240 (TX) and Minneapolis (MN) (Bai and Jiao, 2020; Zuniga-Garcia and Machemehl, 2020). Interestingly, 241 this was not true for Washington D.C. (Hawa et al., 2020) which may have to do with its more 242 diversified city center. We also find bus stops to have a significantly positive, yet less substantial effect 243 on e-scooter stops than other POIs. Previous studies show mixed evidence for this relationship 244 suggesting first/last mile usage with positive effects found for Nashville (TN) (Arnell et al., 2020) and 245 negative effects found for Austin (TX) (Zuniga-Garcia and Machemehl, 2020) and San Diego (CA) 246 (Arnell et al., 2020). Our results extend previous results by suggesting that tourism (i.e., hotels, 247 restaurants) may be a driver of e-scooter demand. This appears plausible given the mobility demand of 248 tourists and the fact that most e-scooter companies allow their users to rent e-scooters in different cities. 249

The direction of the effects are further comparable to the effects observed in bicycle-sharing demand models. Previous literature on bicycle-sharing demand also reported positive effects of population, workplaces, proximity to central locations (such as university campuses and central business districts), restaurants and cycling infrastructure (Guidon *et al.*, 2019; Noland *et al.*, 2016; Shen *et al.*, 2018). While aggregate effects are usually consistent, the effect of population and workplaces can vary in disaggregate models for specific hours of the day or the weekend (Noland et al., 2016).

#### 257 Conclusion

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258 259 This paper reports on spatial drivers of shared e-scooter trip destinations in Louisville (KY). Our 260 results largely confirm previous studies in that population density, the presence of bikeways and 261 university campuses have the strongest positive effect on counts of shared e-scooter trip destinations.

262 We find a significant, yet less substantial positive effect of bus stops suggesting some first/last mile

use. Our results extend previous literature in that they suggest that tourists may be an overlooked, yetimportant segment in shared e-scooter demand.

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We suggest future research to further explore the potential link between tourism and shared e-scooter demand, which can be done through targeted surveys or spatial regression models. For the latter, we see a particular need for comparative case studies estimating the same models on similar data for multiple cities.

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