

Multi-class speed-density relationship for pedestrian traffic

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Outline

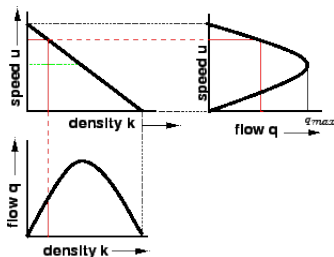
- 1 Introduction
- 2 Methodology
- 3 Case study
 - Model specification
 - Model estimation and performance analysis
- 4 Conclusion and future work

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Fundamental relationships

- Play an important role in the field: design and planning; model input or calibration criterion
- Modeling assumption: the traffic system is at equilibrium - homogenous and stationary



Speed-density relationships for pedestrian traffic

Deterministic approach

- Empirically derived models [Older, 1968; Tregenza, 1976; Weidmann, 1993; Rastogi et al., 2013]
- Simulation-based models [Blue and Adler, 1998]
- Theory-based models [Flötteröd and Lämmel, 2015]

Empirical observations

- Scatter: violation of the equilibrium assumptions

Probabilistic approach

- Data-driven PedProb-vk [Nikolić et al., 2016]
- Superior compared to deterministic approaches from the literature

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Behavioral approach

Assumptions

- Pedestrian population is heterogeneous (e.g. trip purpose, age, gender, etc.)
- Heterogeneity leads to the existence of multiple pedestrian classes
- Classes are characterized by different types of behavior
- Latent class modeling approach to capture unobserved heterogeneity



Multi-class speed-density relationship (MC-vk)

Model structure

$$P(v_i|k_i) = \sum_{c=1}^C P(v_i|k_i, c)P(c|X_i)$$

$P(v_i|k_i, c)$: class-specific model

$P(c|X_i)$: class membership model

i : pedestrian identifier, $i = 1, \dots, N$

v_i : speed of pedestrian i

k_i : density for pedestrian i

c : class identifier, C - number of classes

X_i : characteristics associated to pedestrian i

Class-specific speed-density relationship

Social Force Model

$$\vec{a}_i = \frac{\vec{v}_i^f - \vec{v}_i}{\tau_i} - C_i \sum_j \exp\left(-\frac{R_{ij}}{B_i}\right) \vec{n}_{ij} \left(\lambda_i + (1 - \lambda_i) \frac{1 + \cos(\phi_{ij})}{2}\right)$$

[Helbing and Molnar, 1995]



Class-specific speed-density relationship

Isotropy ($\lambda_i = 1$)

$$a_i = \frac{v_i^f - v_i}{\tau_i} - C_i \sum_j \exp\left(-\frac{R_{ij}}{B_i}\right) = \frac{v_i^f - v_i}{\tau_i} - C_i k_i$$

Stationarity ($a_i = 0$)

$$v_i = v_i^f - \gamma_i k_i$$

Homogeneity (all pedestrians have the same movement parameters)

$$v_i = v = v_f - \gamma k_i$$

Class membership model

- It cannot be deterministically identified to which class a pedestrian belongs
- Probability that a pedestrian i , associated with characteristics X_i (e.g. trip purpose, age, gender, etc.), belong to a latent class c : for each pedestrian there is a utility associated to each class c

Specification of utilities

$$U_i^c = \underbrace{ASC^c + \beta^c X_i}_{V_i^c} + \xi_i^c$$

V_i^c : deterministic part of utilities

ξ_i^c : error term

Multi-class speed-density relationship (MC-vk)

Class-specific model: $P(v_i|k_i, c)$

$$v_i^c = v_f^c - \gamma^c k_i + \epsilon_i^c$$

$P(v_i|k_i, c)$ is determined by ϵ_i^c

Class membership model: $P(c|X_i)$

$$U_i^c = \underbrace{ASC^c + \beta^c X_i}_{V_i^c} + \xi_i^c$$

$P(c|X_i)$ is determined by ξ_i^c

Likelihood of the sample

$$\mathcal{L} = \prod_{i=1}^N P(v_i|k_i) = \prod_{i=1}^N \sum_{c=1}^C P(v_i|k_i, c) P(c|X_i)$$

Outline

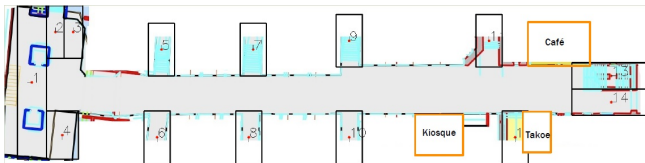
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Lausanne railway station



Pedestrian underpass West

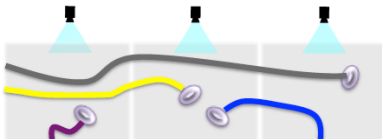
- 1: South entrance, 3: Coop Pronto Supermarket
- 2 - 4: Stairs (resp. ramp) to platform 9
- 5 - 6: Stairs (resp. ramp) to platform 7 and 8
- 7 - 8: Stairs (resp. ramp) to platform 5 and 6
- 9 - 10: Stairs (resp. ramp) to platform 3 and 4
- 11: Stairs to platform 1 and out of the station
- 12: Access ramp
- 13: Stairs to or out of the train station and to buses
- 14: Pathway leading to buses and metro (M2)



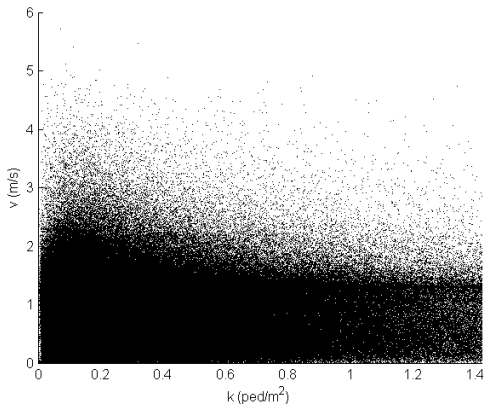
Data set

Pedestrian underpass

- A large-scale network of smart sensors: a sparsity driven tracking framework [Alahi et al., 2014]
- Dataset: 25,603 trajectories, collected between 07:00 and 08:00 on February 12, 13, 14, 15 and 18, 2013
- The average length of the trajectories: 78 meters
- The duration of a pedestrians' stay: from 15 seconds to 2.2 minutes



Speed-density relationship



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Specification issues

Panel data

- Data collected over multiple time periods for the same sample of individuals

Serial correlation

- The observations across time for a single pedestrian are likely to be correlated, due to the unobserved factors related to a pedestrian that exist over time
- $\epsilon_{i(t-1)}^C$ cannot be assumed independent from ϵ_{it}^C
- If ignored - consistent but not efficient estimators

Multi-class speed-density relationship (MC-vk)

Class-specific model: $P(v_i|k_i, c)$

$$v_{it}^c = v_f^c - \gamma^c k_{it} + \alpha_i^c + \epsilon_{it}^c$$

$P(v_i|k_i, c)$ is determined by ϵ_{it}^c , α_i^c is an agent effect

Class membership model: $P(c|X_i)$

$$U_i^c = \underbrace{ASC^c + \beta^c X_i}_{V_i^c} + \xi_i^c$$

$P(c|X_i)$ is determined by ξ_i^c

Likelihood of the sample

$$\mathcal{L} = \prod_{i=1}^N \sum_{c=1}^C \left\{ \frac{1}{R} \sum_r \exp\left(\sum_{t=1}^T \log P(v_i|k_i, c, \alpha_r^c)\right) \right\} P(c|X_i)$$

Assumptions

Number of classes

1. Pedestrians sensitive to congestion
2. Pedestrians non-sensitive to congestion

Class specific model

- The same functional form of v-k for each class
- $\epsilon'_{it}{}^c \sim \text{Rayleigh distribution}$
- $\alpha'_i{}^c \sim \text{Rayleigh distribution}$

Class membership model

- Logit model
- Explanatory variables: type of pedestrian, time to departure, OD distance, peak periods

Pedestrian types

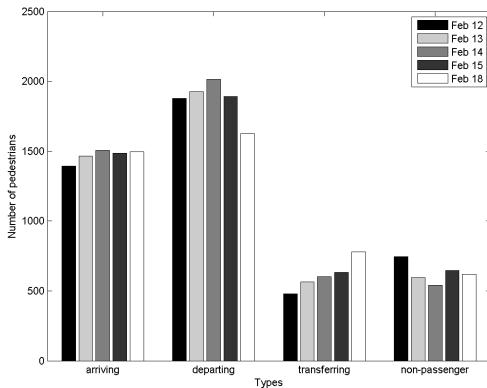
Classification based on origins and destinations

- 1: Arriving passenger - pedestrians originating from a platform and exiting the station
- 2: Departing passenger - pedestrians walking to a platform to embark on their trains
- 3: Transferring passenger - pedestrians whose origin and destination are different platforms
- 4: Non-passenger - pedestrians whose origin and destination are different from a platform (e.g. pedestrians that go shopping in the station)



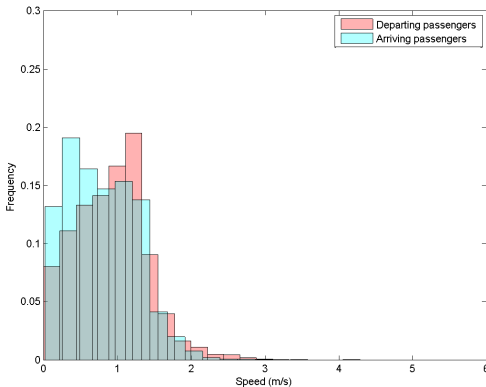
Pedestrian types

Number of pedestrians per pedestrian type



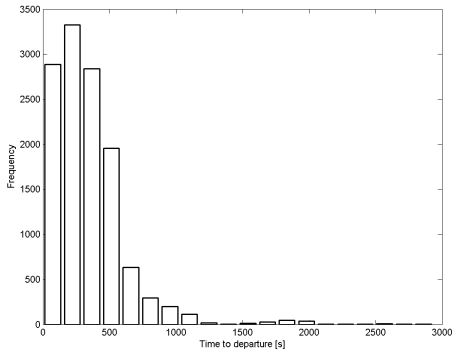
Pedestrian types

Speed distribution per pedestrian type

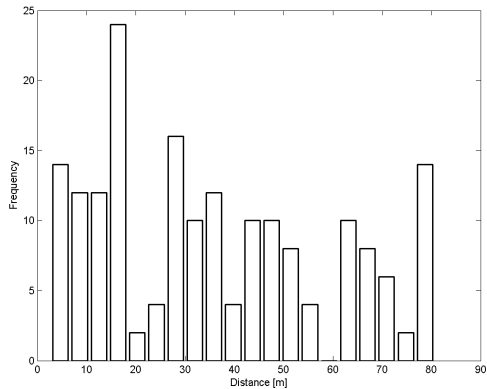


Train timetable

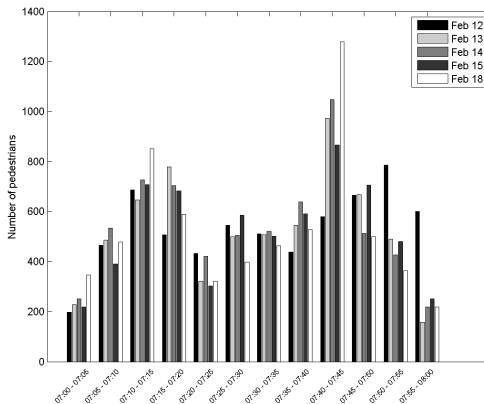
Time to departure



OD distance



Peak periods



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Estimation results

Class membership model

Parameter	Value	Std.err.
ASC^{NS}	-0.258	$5.18e^{-06}$
$\beta_{Arriving\ pass.}^{NS}$	-0.641	$1.03e^{-05}$
$\beta_{Departing\ pass.}^{NS}$	58.5	$2.11e^{-05}$
$\beta_{Transferring\ pass.}^{NS}$	63.5	$1.73e^{-05}$
$\beta_{Time\ to\ departure}^S$	0.236	$1.57e^{-05}$
$\beta_{Peak\ period}^S$	0.125	$1.54e^{-05}$
$\beta_{OD\ distance}^S$	0.0328	$1.93e^{-05}$

Class specific model

Parameter	Value	Std.err.
v_f^{NS}	1.13	$1.32e^{-05}$
γ^{NS}	0.0812	$1.73e^{-05}$
v_f^S	0.949	$9.37e^{-05}$
γ^S	0.178	$1.28e^{-05}$
η^{NS}	0.0104	$2.67e^{-05}$
η^S	0.102	$1.66e^{-05}$

S - Pedestrians sensitive to congestion

NS - Pedestrians non-sensitive to congestion

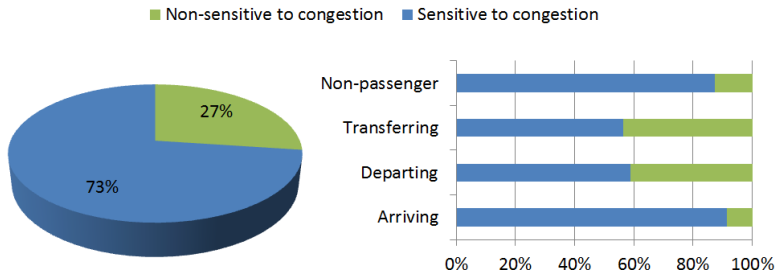
How many classes?

Bayesian information criterion - *BIC*

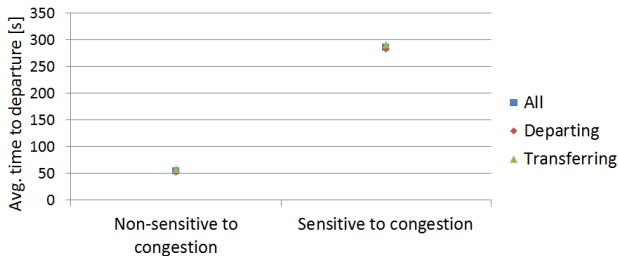
Model	1 class	2 classes	3 classes
$\log \mathcal{L}$	-527491.289	-524094.577	-523726.125
<i>#observations</i>	747385	747385	747385
<i>#parameters</i>	3	13	23
<i>BIC</i>	1055023.152	1048364.971	1047763.309



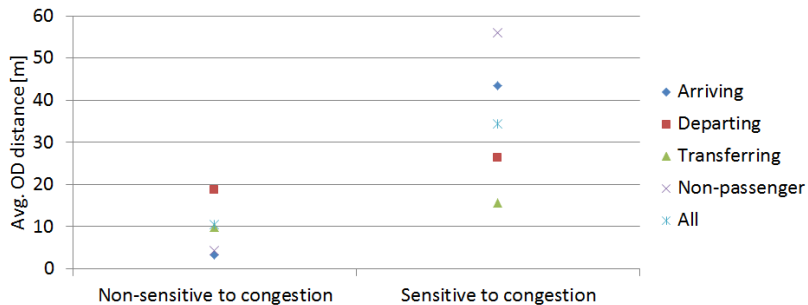
Shares



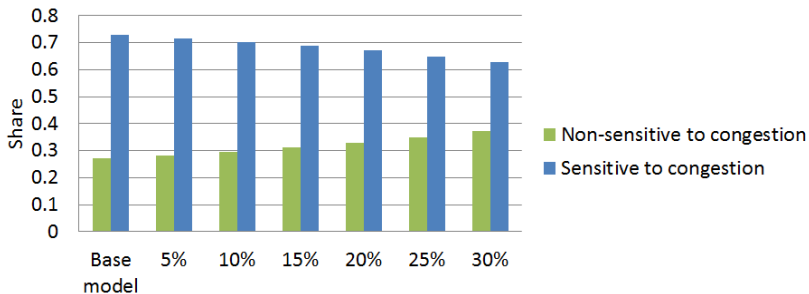
Average time to departure



Average OD distance



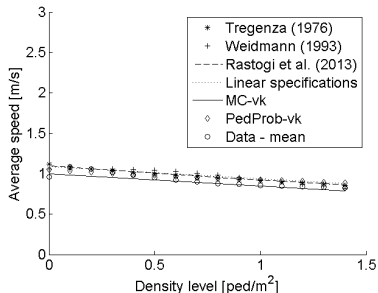
Scenario: time table change (decrease of the time to departure)



Model comparison

Average behavior

$$\bar{v}_{MC-vk} = \sum_{c=1}^C \left\{ \frac{1}{N} \sum_{i=1}^N P(c|X_i; \beta^c) v^c(k; \theta^c) \right\}$$



Model	Weidmann	Tregenza	Rastogi	Linear	<i>PedProb-vk</i>	<i>MC-vk</i>
<i>MSE</i>	$4.81e^{-03}$	$3.63e^{-03}$	$3.95e^{-03}$	$4.99e^{-03}$	$3.17e^{-03}$	$2.12e^{-03}$
\bar{R}^2	$2.64e^{-01}$	$4.45e^{-01}$	$3.96e^{-01}$	$2.37e^{-01}$	$5.16e^{-01}$	$6.76e^{-01}$

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Conclusion and future work

Conclusion

- MC-vk: latent class modeling approach to capture heterogeneity in pedestrian population
- Satisfying behavioral interpretation
- Good performance at the aggregate level

Future work

- Additional factors: walking in groups, attractiveness of origins/destinations
- Additional scenarios: train reallocation
- Accounting for dynamics

Thank you

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