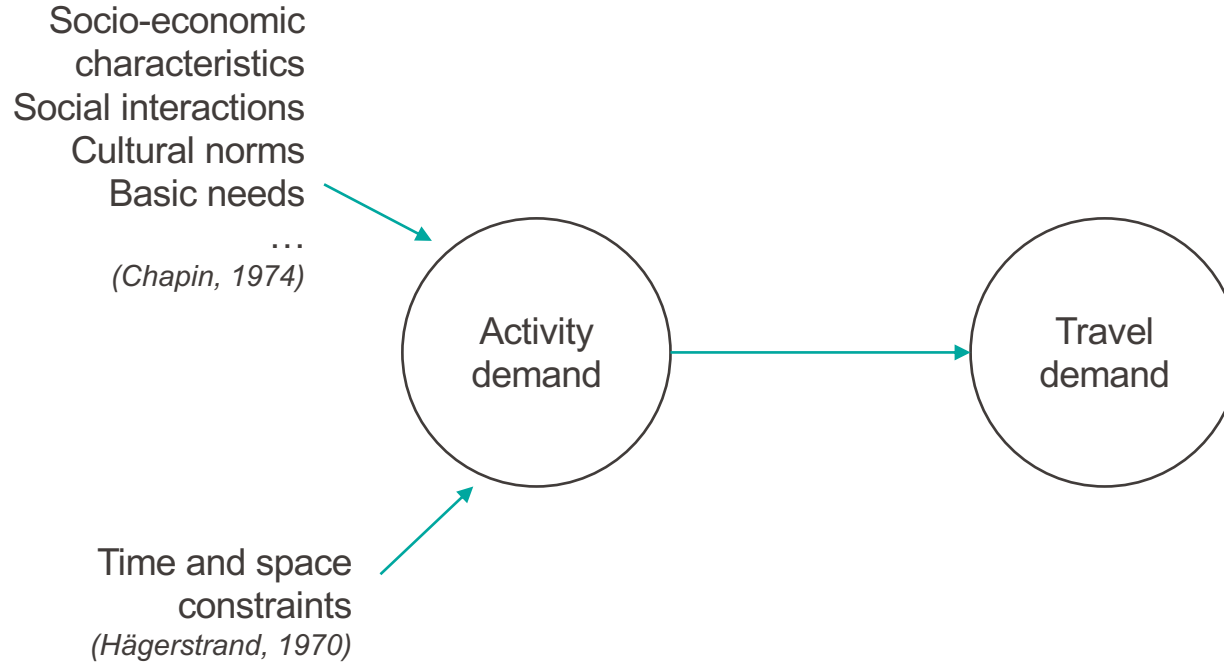




Parameter estimation for activity-based models

Janody Pougala · Tim Hillel · Michel Bierlaire

Introduction



Utility-based models

Decision is made by maximizing utility derived from activities

e.g.

Bowman & Ben-Akiva, 2001
Bhat et al, 2004
Pougala et al, 2021

Rule-based models

Decision is made by considering context-dependent rules

e.g.

Gollegde et al., 1994
Arentze & Timmermans 2000

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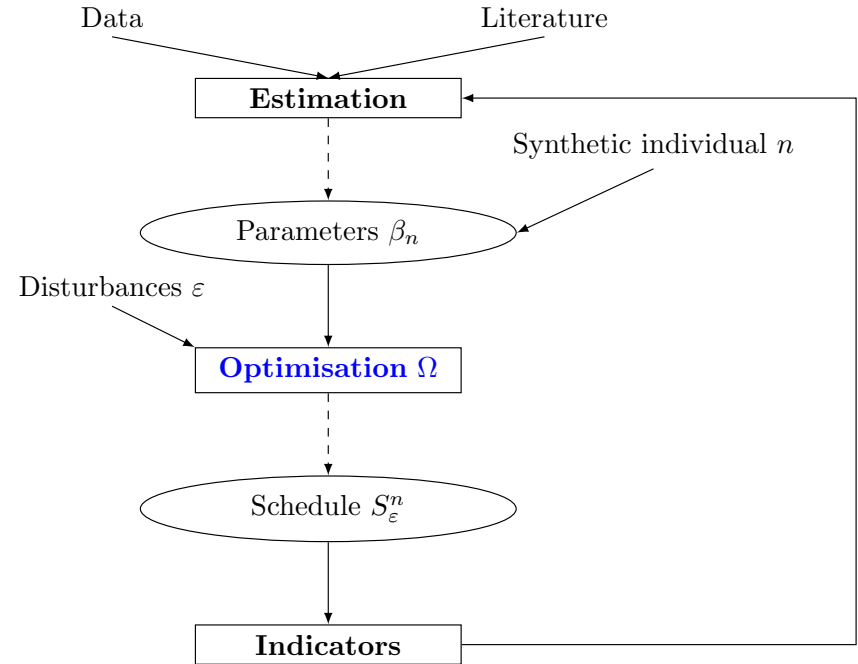
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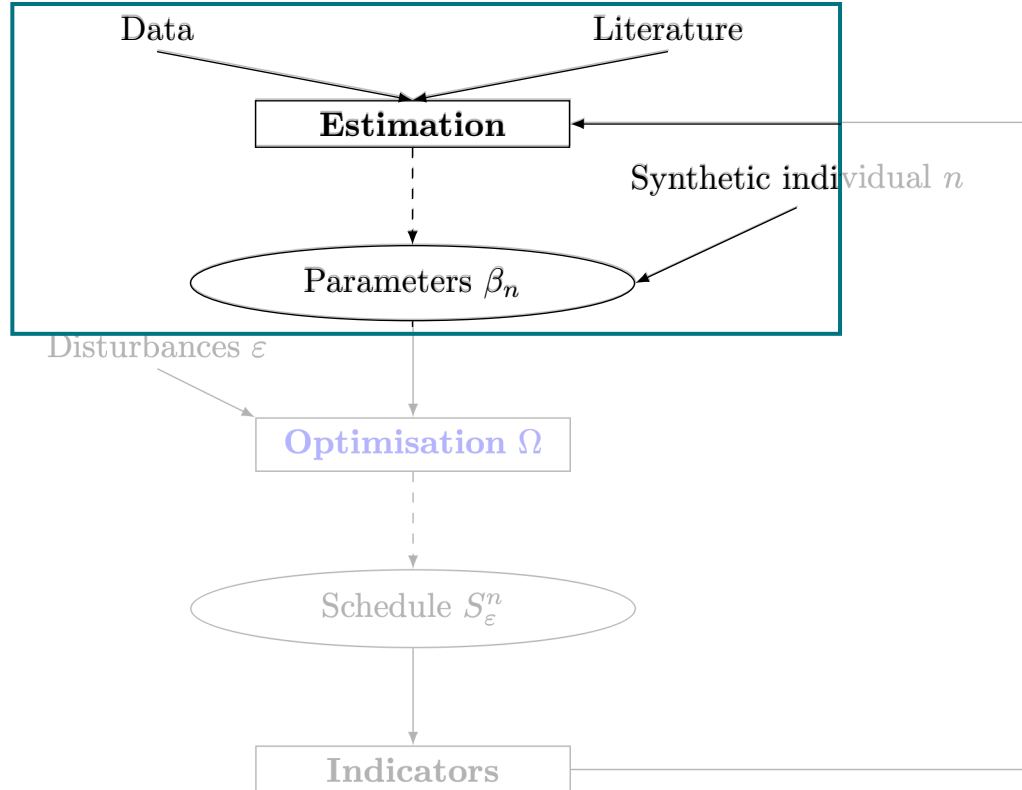
Background

- Optimisation-based simulation framework for activity-based models
 - Pougala et al, 2022
- Joint estimation
 - Activity participation
 - Activity scheduling
 - Mode choice
 - Location choice



Parameter estimation

Parameter estimation



Parameter estimation

- Maximum likelihood estimation (MLE) of parameters in DCM:

$$\hat{\theta} = \arg \max L_n(\theta)$$

$$L_n = \prod_{n=1}^N \prod_{i \in C_n} P_n(i)^{y_{in}}$$

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Enumeration over choice set C_n

- Common assumptions on choice set:
 - Universal across population
 - Fully observed or observable

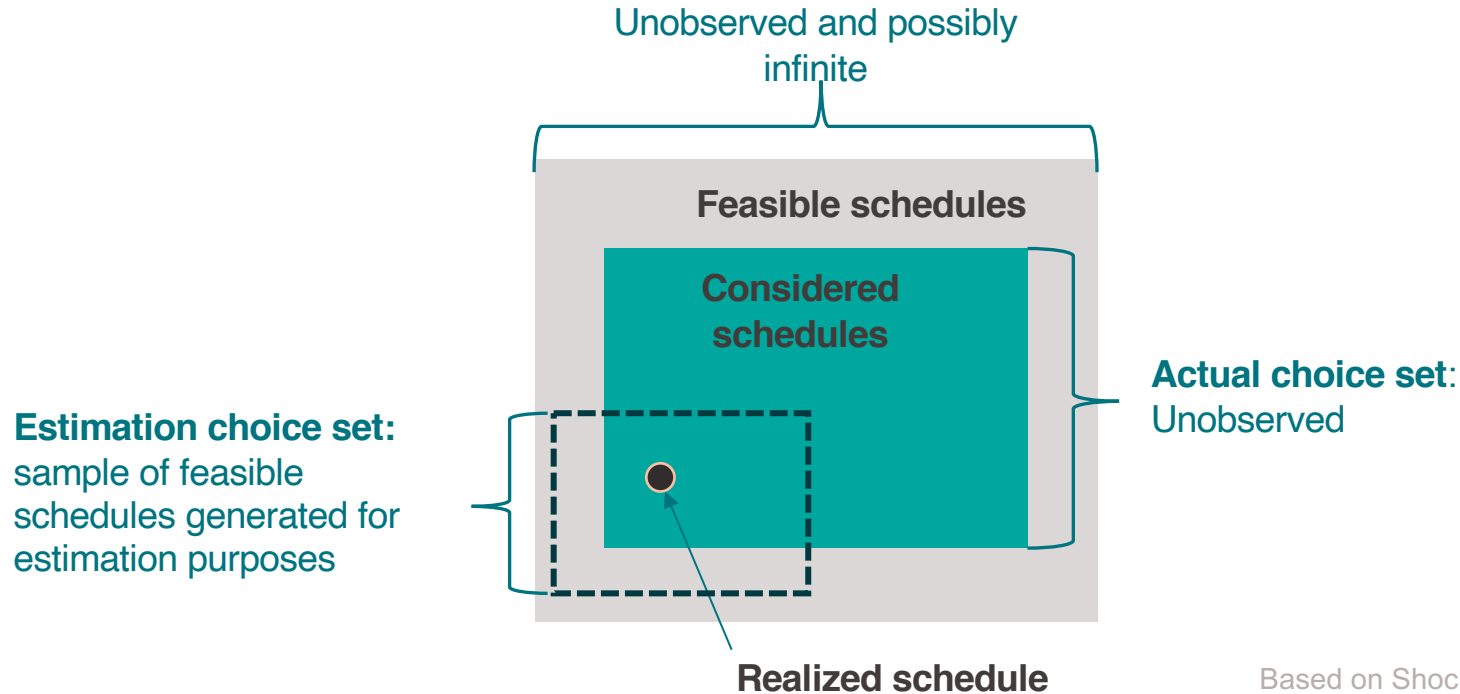
Parameter estimation

- Maximum likelihood estimation (MLE) of parameters in DCM:

$$\hat{\theta} = \arg \max L_n(\theta)$$
$$L_n = \prod_{n=1}^N \prod_{i \in \mathcal{C}_n^*} P_n(i | \mathcal{C}_n^*)^{y_{in}}$$

- **Sample of alternatives $\mathcal{C}_n^* \subset \mathcal{C}_n$:**
 - Correction of the choice probabilities (Ben-Akiva & Lerman, 1985)

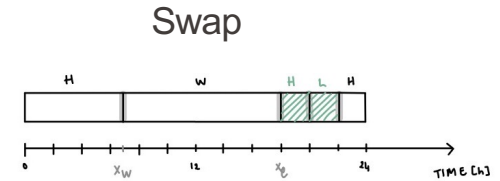
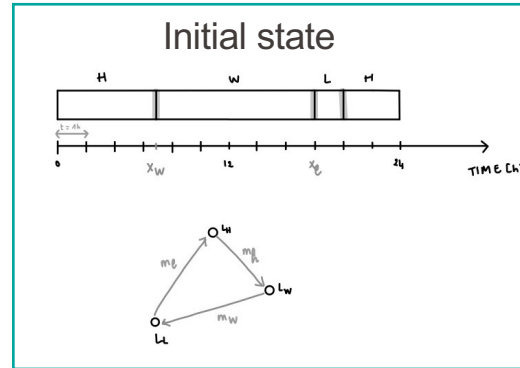
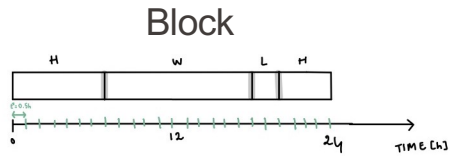
Choice set



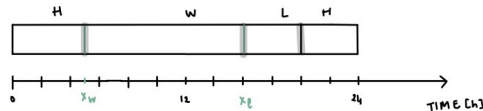
Based on Shocker (1991)

Choice set

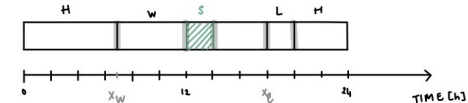
- **Choice set generation**
 - Metropolis-Hastings sampling of feasible schedules
 - STRC 2021



Inflate/Deflate



Assign



Parameters

○ Utility of a schedule: $U_n = \sum_a U_{an}$

- For an individual n considering an activity a with a flexibility k :

$$U_{an} = U_{const} + \boxed{U_{early} + U_{late}} + \boxed{U_{long} + U_{short}} + U_{travel} + \varepsilon_{an}$$

Start time deviations:

$$U_{early} = \theta_{ek} \max(0, x_a^* - x_a)$$

$$U_{late} = \theta_{lk} \max(0, x_a - x_a^*)$$

Duration deviations:

$$U_{short} = \theta_{dsk} \max(0, \tau_a^* - \tau_a)$$

$$U_{long} = \theta_{dlk} \max(0, \tau_a - \tau_a^*)$$

Case study

○ Lausanne population, MTMC 2015 (BFS & ARE, 2017)

• 3 samples:

- S1: Students (236 individuals)
- S2: Workers (618 individuals)
- S3: All occupations (1118 individuals)



• Choice set sizes:

- N = 10 alternatives for S1, S2
- N = 100 for S3

Model 1 (14 parameters):

- Activity-specific constants
- Aggregated penalties (flexible vs. Non flexible)

Model 2 (30 parameters):

- Activity-specific constants
- Activity specific penalties

Results

○ Model 1, Workers: constants

- Reference: ASC Home = 0
- $\bar{\rho}^2 = 0.77$
- Runtime: 1.36 s

Parameter	Param. estimate	Rob. Std error	Statistical significance ($p < 0.05$)
ASC Education	10.8	2.50	Significant
ASC Errands	7.63	1.28	
ASC Escort	9.79	1.45	
ASC Leisure	15.3	1.38	
ASC Shopping	12.5	1.38	
ASC Work	18.5	2.00	

Results

○ Model 1, Workers: penalties

- Flexible (F): errands, leisure, shopping
- Non-Flexible (NF): work, education, escort

Parameter	Param. estimate	Rob. Std error	Statistical significance ($p < 0.05$)
F: early	-0.813	0.160	Significant
F: late	-1.12	0.138	
<i>F: short*</i>	<i>0*</i>	- *	<i>Not significant</i>
F: long	-0.569	0.165	Significant
NF: early	-0.827	0.160	
NF: late	-1.26	0.236	
NF: short	-3.24	0.555	
NF: long	-0.789	0.229	

Summary

- Estimated ABM parameters using sampled choice sets
- Expected signs, ratios and significance

- Further work:
 - Complex model specifications (logit mixtures, non-linear parameters...)
 - Investigate stability (increasing N)
 - Application on synthetic population for validation

Thank you!

janody.pougala@epfl.ch

tim.hillel@ucl.ac.uk

michel.bierlaire@epfl.ch

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