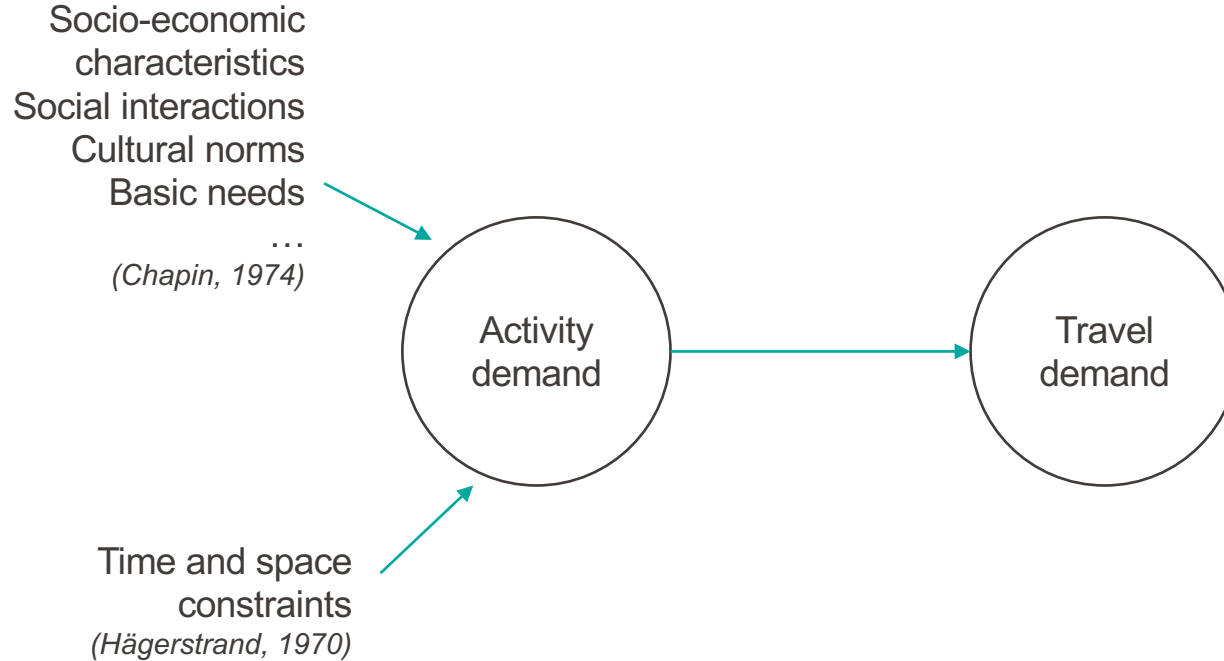




## Choice set generation for activity-based models

Janody Pougala · Tim Hillel · Michel Bierlaire

# Introduction



## Utility-based models

*Decision is made by maximizing  
utility derived from activities*

e.g.

Bowman & Ben-Akiva, 2001  
Bhat et al, 2004  
Pougala et al, 2021

## Rule-based models

*Decision is made by considering  
context-dependent rules*

e.g.

Gollegde et al., 1994  
Arentze & Timmermans 2000

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# Parameter estimation

- Maximum likelihood estimation (MLE) of parameters in DCM:

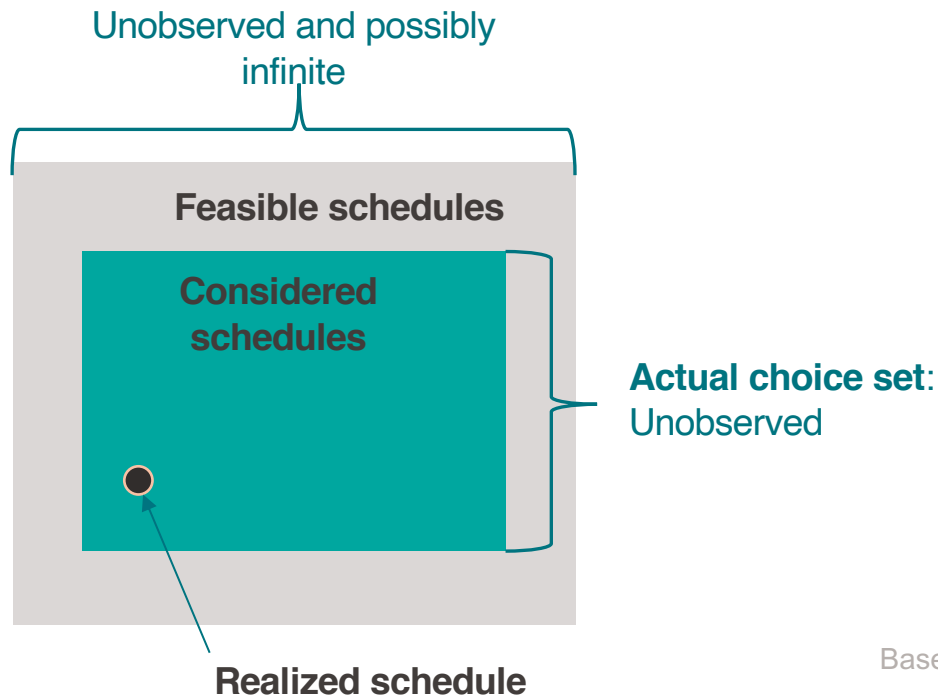
$$\hat{\theta} = \arg \max L_n(\theta)$$

$$L_n = \prod_{n=1}^N \prod_{i \in C_n} P_n(i)^{y_{in}}$$

Enumeration over choice set  $C_n$

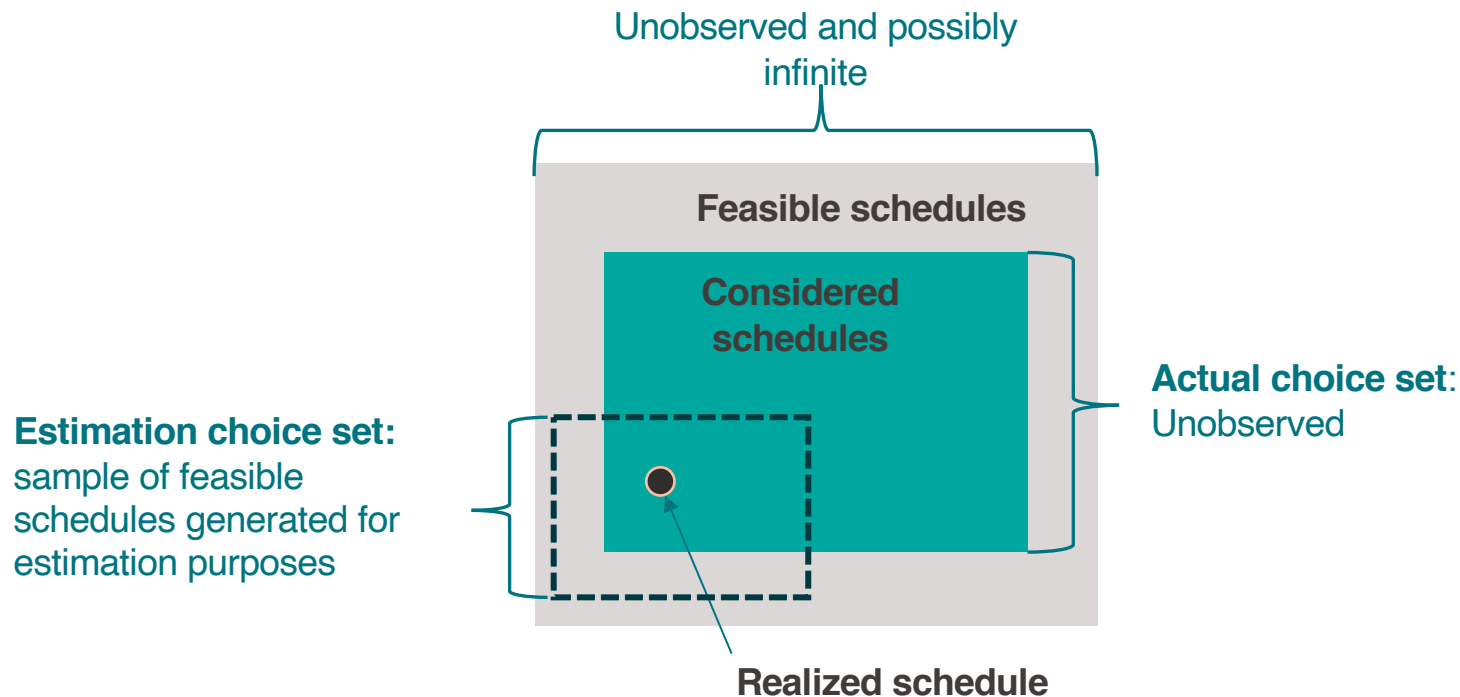
- Common assumptions on choice set:
  - Universal across population
  - Fully observed or observable

# Choice set



Based on Shocker (1991)

# Choice set



- Generate choice set of **considered** schedules for **estimation** purposes
- Efficient exploration of solution space:
  - High probability alternatives to ensure **robust parameters estimates** (Frejinger & Bierlaire, 2009)
  - Low probability alternatives to **reduce parameter bias** (Krüger & Bierlaire, 2020)
- Avoid full enumeration of alternatives



## ○ Flötterod & Bierlaire 2013:

- Importance sampling in route choice context
- Metropolis-Hastings algorithm used to draw from a distribution of path
- Candidate states generated with operators (shuffle, splice)

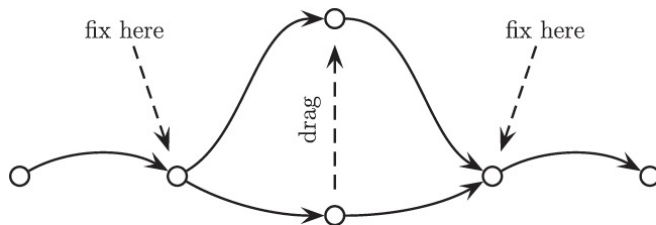
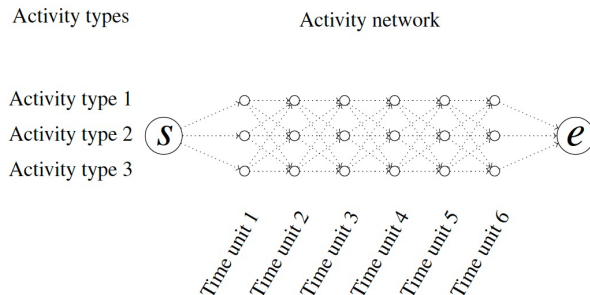


Fig. 1. "Rubber band"-like variation of a path.

## ○ Danalet & Bierlaire 2015:

- Importance sampling in the activity-based modelling context
- Activity schedules represented as paths in spatio-temporal network
- Shuffle/splice operators to generate new candidates



# Proposed methodology

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- Extend previous works to include **multiple choice dimensions**:
  - Activity participation
  - Activity scheduling
  - Location
  - Mode of transportation

# Proposed methodology

$n \leftarrow 0$ , initialise state with random schedule  $X_n \leftarrow S_0$

**while**  $n \leq n_{iter}$  **do**

    Choose operator  $\omega$

    With probability  $P_\omega$ ,  $X^* \leftarrow \mathbf{Operator}(X_n)$

    Compute acceptance probability  $\alpha(X_n, X^*) = \min\left(\frac{b(X^*)q(X_n|X^*)}{b(X_n)q(X^*|X_n)}\right)$

    With probability  $\alpha(X_n, X^*)$ ,  $X_{n+1} \leftarrow X^*$ , else  $X_{n+1} \leftarrow X_n$

**end while**

# Proposed methodology

$n \leftarrow 0$ , initialise state with random schedule  $X_n \leftarrow S_0$

**while**  $n \leq n_{iter}$  **do**

Choose operator  $\omega$

With probability  $P_\omega$ ,  $X^* \leftarrow \mathbf{Operator}(X_n)$

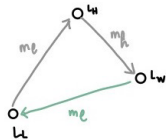
Compute acceptance probability  $\alpha(X_n, X^*) = \min\left(\frac{b(X^*)q(X_n|X^*)}{b(X_n)q(X^*|X_n)}\right)$

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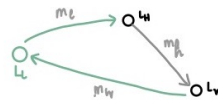
**end while**

# Operators

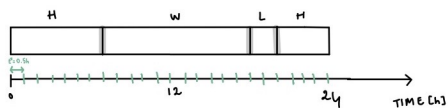
Mode



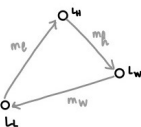
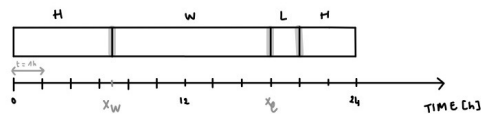
Location



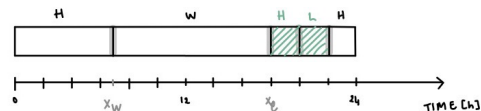
Block



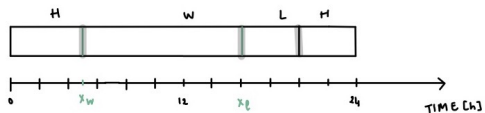
Initial state



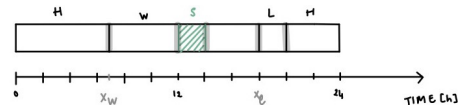
Swap



Inflate/Deflate



Assign



# Proposed methodology

$n \leftarrow 0$ , initialise state with random schedule  $X_n \leftarrow S_0$

**while**  $n \leq n_{iter}$  **do**

    Choose operator  $\omega$

    With probability  $P_\omega$ ,  $X^* \leftarrow \mathbf{Operator}(X_n)$

    Compute acceptance probability  $\alpha(X_n, X^*) = \min\left(\frac{b(X^*)q(X_n|X^*)}{b(X_n)q(X^*|X_n)}\right)$

    With probability  $\alpha(X_n, X^*)$ ,  $X_{n+1} \leftarrow X^*$ , else  $X_{n+1} \leftarrow X_n$

**end while**

# Target distribution

- Unnormalized target weights:  $b(X_t) = U(X_t) = \sum_{a \in A_{X_t}} U_a$
- E.g. Utility function of a schedule (Pougala et al, 2021)
  - For an individual  $n$  considering an activity  $a$  with a flexibility  $k$ :

$$U_{an} = U_{const} + \boxed{U_{early} + U_{late}} + \boxed{U_{long} + U_{short}} + U_{travel} + \varepsilon_{an}$$

Start time deviations:

$$\begin{aligned} U_{early} &= \theta_{ek} \max(0, \mathbf{x}_a^* - x_a) \\ U_{late} &= \theta_{lk} \max(0, x_a - \mathbf{x}_a^*) \end{aligned}$$

Duration deviations:

$$\begin{aligned} U_{short} &= \theta_{dsk} \max(0, \tau_a^* - \tau_a) \\ U_{long} &= \theta_{dlk} \max(0, \tau_a - \tau_a^*) \end{aligned}$$



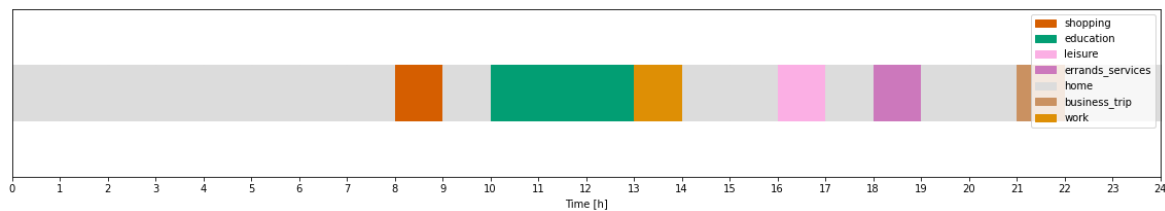
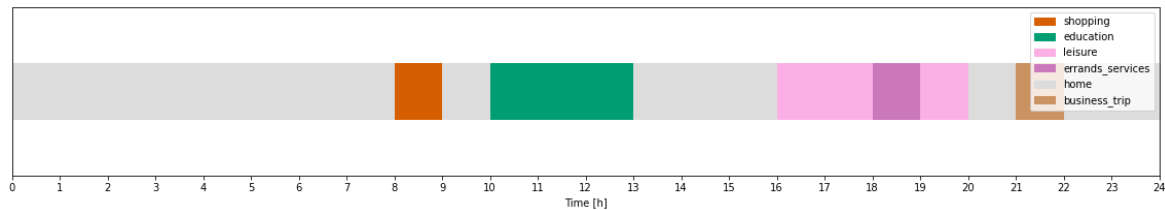
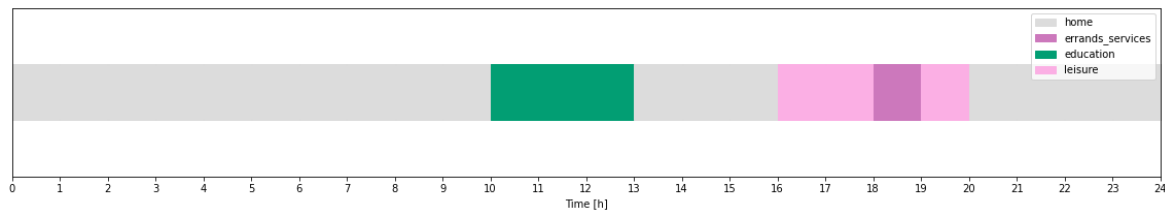
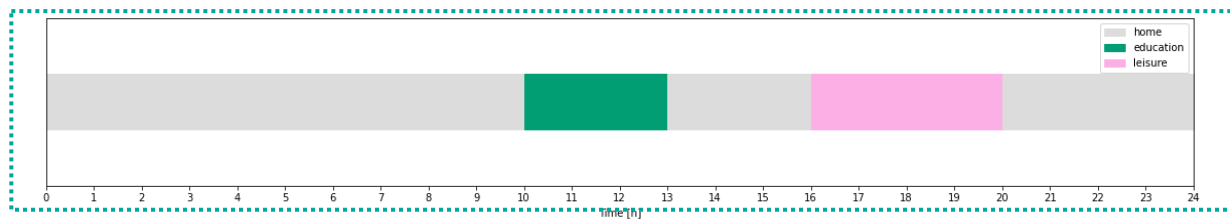
# Example

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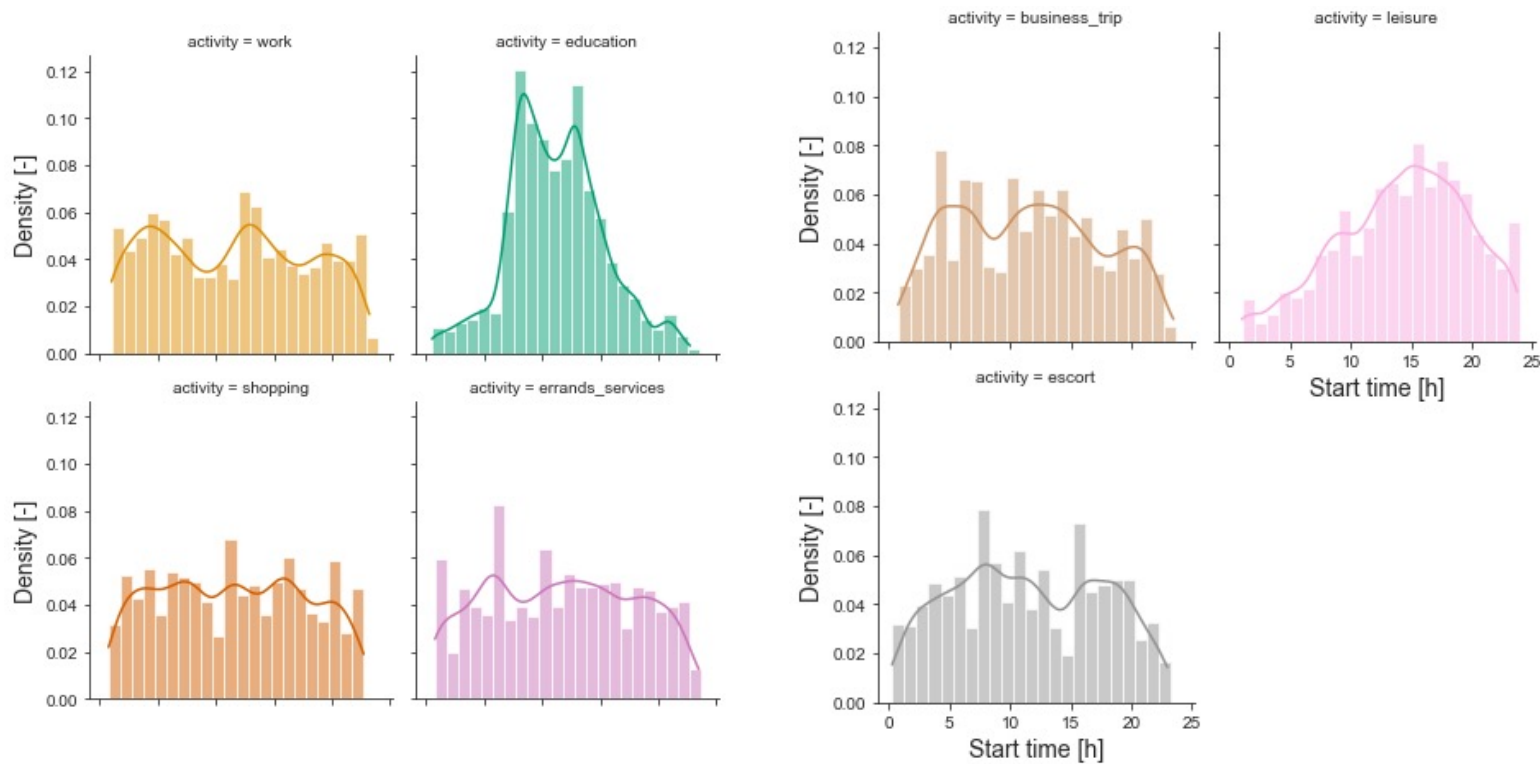
- Sample data:
  - 2015 Mobility and Transport microcensus (BFS & ARE)
  - Student population of Lausanne (236 individuals)
- MH set-up:
  - 10'000 iterations (5'000 warm-up)
  - Initial state: observed schedule from dataset
  - Operators: block, assign, swap, inflate/deflate, combo
  - Initial parameters for target weights: estimated on random choice set

# Example

Initial  
schedule

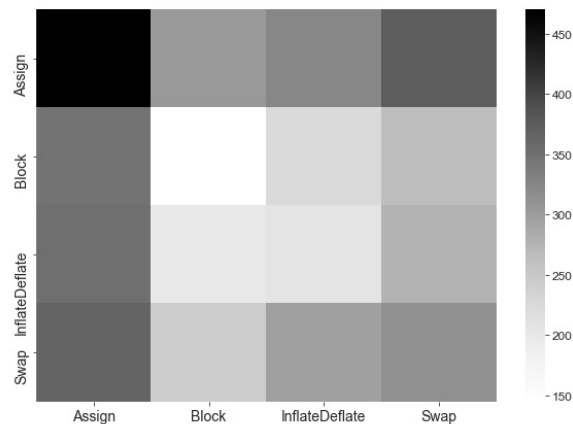
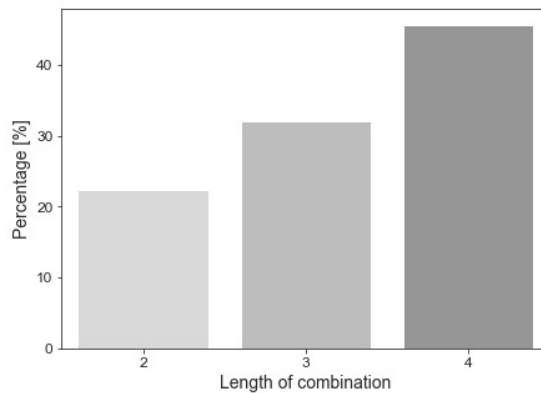
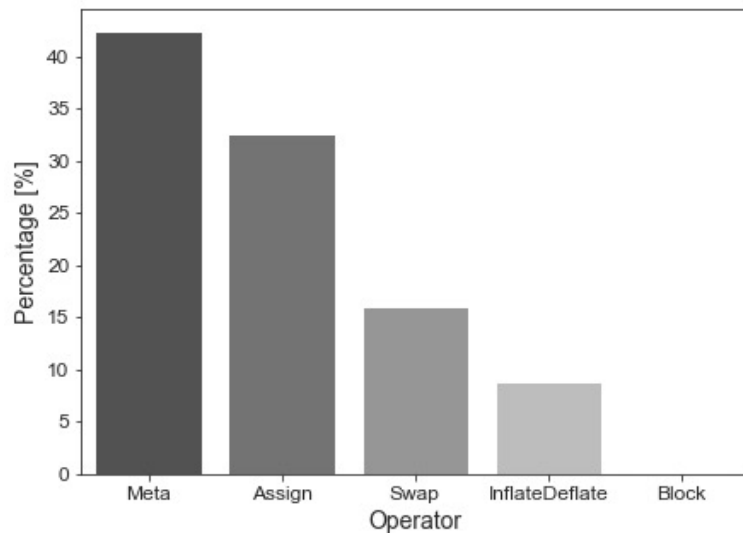


# Example



Activity start times across choice set

# Example



Frequency of accepted operator changes

Typology of accepted combinations

# Discussion & future work

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- Validation:
  - Compare estimated parameters with MH sampled and random choice set
  - Use synthetic population to evaluate param. with control values
- Sensitivity analysis:
  - Probability of selecting operators
  - Different utility specifications for target weights
- Performance:
  - Convergence analysis
  - Optimal size of choice set

# Thank you!

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