

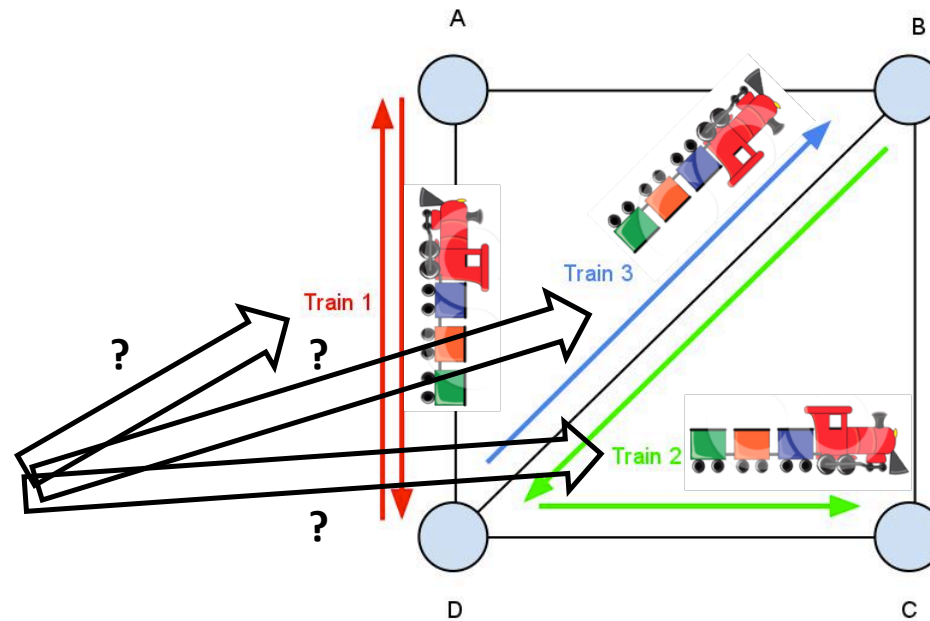
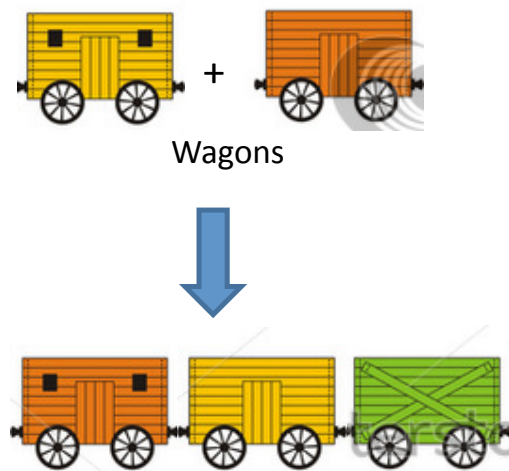
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# Cost Optimization for the Capacitated Railroad Blocking and Train Design Problem

*Michel Bierlaire  
and*

*Burak Boyacı, Viswanathan Prem Kumar, Stefan Binder*

# Terminology and Problem Definition



Which trains to run?

Which blocks to be assigned to which trains?

# Problem Objectives

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- Blocking Problem
    - Combining shipments to form one unit (*block*)
  - Train Design Problem
    - Decide trains origins, destinations and paths
    - Crew segment constraint is also considered
  - Block-to-Train Assignment (BTA)
    - Determine which block is assigned to which train
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- For our problem, the composition of the blocks are known.

# Problem Description

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- Model: directed graph
  - Nodes -> train stations
  - The graph is not necessarily complete.

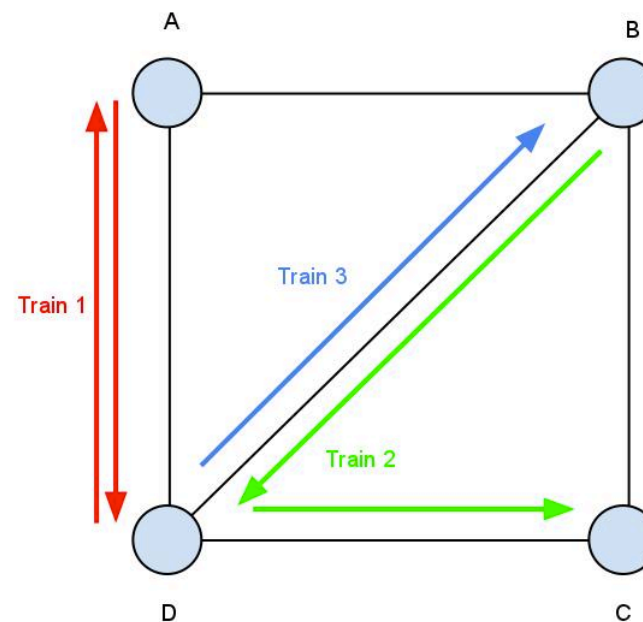
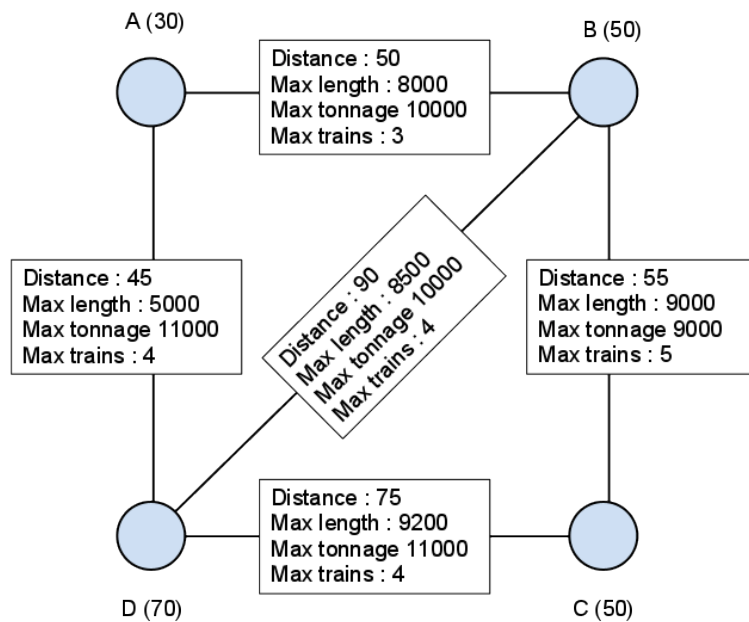
## Constraints

- Number of blocks per train
- Number of block swaps per block
- Number of work events per train
- Length and tonnage restrictions on arcs
- Number of trains per arc
- Crew segments

## Cost Components

- Fixed setup and travel costs
- Marginal cost per wagon
- Work event cost
- Block swap cost
- Train imbalance cost
- Crew imbalance cost
- Unsatisfied demand

# Toy Problem



Block	Origin	Destination	# of cars	Total length	Total tonnage
1	A	C	50	3000	2500
2	A	D	25	1500	1250
3	B	D	40	2400	2000
4	D	A	28	1680	1400
5	D	B	16	960	800

# Literature - Motivation

- R.K. Ahuja, K.C. Jha, and J. Liu (2007). *Solving real-life railroad blocking problems.*
  - MIP formulation of the railroad blocking problem
- K.C. Jha, R.K. Ahuja, and G. Sahin (2008). *New approaches for Solving the Block-to-Train assignment Problem.*
  - Arc-based and path-based formulation of the block-to-train assignment problem
- Literature assumes that train design (with crew constraints) is given and blocking and BTA are solved separately.
- INFORMS RAS 2011 Competition Problem (with real data)

# Cost Breakup

Train start cost	\$400.00
Train travel cost (per mile)	\$10.00
Railcar travel cost (per mile)	\$0.75
Work event cost	\$350.00
Block swap cost	\$40.00 – \$100.00
Crew imbalance penalty	\$600.00
Train imbalance penalty	\$1,000.00
Missed railcar penalty	\$5,000.00

Has highest influence on cost, should be minimized with priority



Should be avoided if possible (isolated shipment and/or network capacity)

IDEA:

For each shipment, find path from origin to destination which minimizes travel cost. If no constraints exist, this is the shortest path.

Constraints:

- Length and tonnage restrictions on arcs
- Crew segments

# Methodological framework

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- Travel cost is the most discriminating cost component
- Crew constraints are the most complex
- Three-step process
  - Identify the shortest path for each block, under constraints
  - Guarantee feasibility wrt crew constraint with pre-preprocessing
  - Solve a MIP



# Step 1: Constrained shortest path

$$\begin{aligned} \text{Min } & \sum_{a \in A} \sum_{b \in B} c_{car} \cdot DistArc_a \cdot NumCar_b \cdot x_{ab} \\ & + \sum_{a \in A} (c_{train} \cdot DistArc_a + TrainStartCost) \cdot y_a \end{aligned} \quad (1)$$

subject to

$$\sum_{a \in A_{O_b}^+} x_{ab} = 1 \quad \forall b \in B \quad (2)$$

$$\sum_{a \in A_{O_b}^-} x_{ab} = 0 \quad \forall b \in B \quad (3)$$

$$\sum_{a \in A_{D_b}^-} x_{ab} = 1 \quad \forall b \in B \quad (4)$$

$$\sum_{a \in A_n^+} x_{ab} = \sum_{a \in A_n^-} x_{ab} \quad \forall n \in N \setminus \{D_b, O_b\}, \forall b \in B \quad (5)$$

$$\sum_{b \in B} Ton_b \cdot x_{ab} \leq y_a \cdot MaxTon_a \quad \forall a \in A \quad (6)$$

$$\sum_{b \in B} Len_b \cdot x_{ab} \leq y_a \cdot MaxLen_a \quad \forall a \in A \quad (7)$$

$$y_a \leq MaxNumTrains_a \quad \forall a \in A \quad (8)$$

$$x_{ab} \leq y_a \quad \forall a \in A, \forall b \in B \quad (9)$$

$$x_{ab} \in \{0, 1\}, y_a \in \mathbb{N} \quad \forall a \in A, \forall b \in B \quad (10)$$

# Step 1: Constrained shortest path

$$\begin{aligned}
 & \text{Min } \sum_{a \in A} \sum_{b \in B} c_{car} \cdot DistArc_a \cdot NumCar_b \cdot x_{ab} \quad \text{if block } b \text{ is carried on arc } a \text{ or not} \\
 & + \sum_{a \in A} (c_{train} \cdot DistArc_a + TrainStartCost) \cdot y_a \quad \text{number of trains running on arc } a \\
 & \text{subject to} \\
 & \sum_{a \in A_{O_b}^+} x_{ab} = 1 \quad \forall b \in B \quad (2) \quad \text{shipment leaves its origin} \\
 & \sum_{a \in A_{O_b}^-} x_{ab} = 0 \quad \forall b \in B \quad (3) \quad \text{subtour elimination constraint} \\
 & \sum_{a \in A_{D_b}^-} x_{ab} = 1 \quad \forall b \in B \quad (4) \quad \text{shipment reaches its destination} \\
 & \sum_{a \in A_n^+} x_{ab} = \sum_{a \in A_n^-} x_{ab} \quad \forall n \in N \setminus \{D_b, O_b\}, \forall b \in B \quad (5) \quad \text{shipment leaves the node that it enters} \\
 & \sum_{b \in B} Ton_b \cdot x_{ab} \leq y_a \cdot MaxTon_a \quad \forall a \in A \quad (6) \quad \text{maximum tonnage constraint on arcs} \\
 & \sum_{b \in B} Len_b \cdot x_{ab} \leq y_a \cdot MaxLen_a \quad \forall a \in A \quad (7) \quad \text{maximum length constraint on arcs} \\
 & y_a \leq MaxNumTrains_a \quad \forall a \in A \quad (8) \quad \text{maximum number of trains constraint on arcs} \\
 & x_{ab} \leq y_a \quad \forall a \in A, \forall b \in B \quad (9) \\
 & x_{ab} \in \{0, 1\}, y_a \in \mathbb{N} \quad \forall a \in A, \forall b \in B \quad (10)
 \end{aligned}$$

# Shipment and Train Path Generation

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- Step 1: Resource constraint shortest path problem for shipments
  - Does not take care of crew segments
  - Find shortest crew segment covering for the paths if the shortest path is not on crew segments
- Step 2: Train Path Generation (preprocessing)
  - Assign one train per crew segment
  - It guarantees feasibility wrt crew constraints
  - Assign more trains to sequences of crew segments to increase flexibility
  - We duplicate trains to meet capacity constraints
  - Next, we decide which of these many trains will be actually operated.

## Step 3: MIP

$$\begin{aligned}
 \text{Min } & \sum_{t \in T} (\text{TrainStartCost} + \text{TrainTravelCostPerMile} \cdot \text{TrainPathLength}_t) \cdot z_t \\
 & + \sum_{t \in T} \sum_{a \in A} \text{CostPerWorkEvent} \cdot w_t^a + \sum_{b \in B} \sum_{a \in A} \text{BlockSwapCost}_a \cdot u_b^a \\
 & + \sum_{n \in N} \text{TrainImbalancePenalty} \cdot s_n + \sum_{i \in C} \text{CrewImbalancePenalty} \cdot c_i \\
 & + \sum_{b \in B} (1 - k_b) \cdot \text{MissedRailcarPenalty} \cdot \text{NumCar}_b
 \end{aligned} \tag{1}$$

subject to

$$\sum_{\{t \in T: a \in I_{bt}\}} x_{bt}^a = k_b \quad \forall b \in B, \forall a \in R_b \tag{2}$$

$$x_{bt}^a \leq y_{bt} \quad \forall b \in B, \forall t \in T, \forall a \in I_{bt} \tag{3}$$

$$x_{bt}^a \leq z_t \quad \forall b \in B, \forall t \in T, \forall a \in I_{bt} \tag{4}$$

$$x_{bt}^a - x_{bt}^{N_t^a} \leq w_t^a, \quad x_{bt}^{N_t^a} - x_{bt}^a \leq w_t^a \quad \forall b \in B, \forall t \in T, \forall a \in I_{bt} \setminus \{a_{t1}, a_{t|P_t|}\} \tag{5}$$

$$\sum_{a \in P_t} w_t^a \leq \max \text{NbWorkEvents}_t \quad \forall t \in T \tag{6}$$

# Mathematical Model (cont.)

$$x_{bt}^a - x_{bt}^{N_b^a} \leq u_b^a, \quad x_{bt}^{N_b^a} - x_{bt}^a \leq u_b^a \quad \forall b \in B, \forall t \in T, \forall a \in I_{bt} \setminus \{a_{b1}, a_{b|R_b|}\} \quad (7)$$

$$\sum_{a \in R_b} u_b^a \leq \text{maxNbBlockSwaps}_b \quad \forall b \in B \quad (8)$$

$$\sum_{\{t \in T: n=O_t\}} z_t - \sum_{\{t \in T: n=D_t\}} z_t \leq s_n \quad \forall n \in N \quad (9)$$

$$\sum_{\{t \in T: n=D_t\}} z_t - \sum_{\{t \in T: n=O_t\}} z_t \leq s_n \quad \forall n \in N \quad (10)$$

$$\sum_{t \in T} CrSeg_t \cdot z_t - \sum_{t \in T} OpCrSeg_t \cdot z_t \leq c_i \quad \forall i \in C \quad (11)$$

$$\sum_{t \in T} OpCrSeg_t \cdot z_t - \sum_{t \in T} CrSeg_t \cdot z_t \leq c_i \quad \forall i \in C \quad (12)$$

$$\sum_{b \in B} y_{bt} \leq \text{maxNbBlocksPerTrain} \quad \forall t \in T, \forall b \in B \quad (13)$$

$$x_{bt}^a, y_{bt}, z_t, w_t^a, u_b^a, k_b \in \{0, 1\} \quad \forall b \in B, \forall t \in T, \forall a \in A \quad (14)$$

$$s_n, c_i \in \mathbb{N} \quad \forall n \in N, \forall i \in C \quad (15)$$

# Mathematical Model

$$\text{Min} \sum_{t \in T} (\text{TrainStartCost} + \text{TrainTravelCostPerMile} \cdot \text{TrainPathLength}_t) \cdot z_t$$

$t \in T$  → set of trains

$$+ \sum_{t \in T} \sum_{a \in A} \text{CostPerWorkEvent} \cdot w_t^a + \sum_{b \in B} \sum_{a \in A} \text{BlockSwapCost}_a \cdot u_b^a$$

$$+ \sum_{n \in N} \text{TrainImbalancePenalty} \cdot s_n + \sum_{i \in C} \text{CrewImbalancePenalty} \cdot c_i$$

$n \in N$  → set of nodes

$i \in C$  → set of crew segments

$$+ \sum_{b \in B} (1 - k_b) \cdot \text{MissedRailcarPenalty} \cdot \text{NumCar}_b$$

if block  $b$  is carried properly or not

common arcs of path of block  $b$  and train  $t$

subject to

$$\sum_{\{t \in T: a \in I_{bt}\}} x_{bt}^a = k_b$$

if block  $b$  is carried by train  $t$  on arc  $a$  or not

$$x_{bt}^a \leq y_{bt}$$

if block  $b$  is carried by train  $t$  at least once or not

$$x_{bt}^a \leq z_t$$

if train  $t$  is used or not

$$x_{bt}^a - x_{bt}^{N_t^a} \leq w_t^a, \quad x_{bt}^{N_t^a} - x_{bt}^a \leq w_t^a$$

$$\sum_{a \in P_t} w_t^a \leq \text{maxNbWorkEvents}_t$$

if train  $t$  has a work event after arc  $a$  or not

(1) all costs and penalties

ordered path of block  $b$

$$\forall b \in B, \forall a \in R_b$$

(2) checks if block is missing or not

$$\forall b \in B, \forall t \in T, \forall a \in I_{bt}$$

(3) connect

$$\forall b \in B, \forall t \in T, \forall a \in I_{bt}$$

(4) variables

$$\forall b \in B, \forall t \in T, \forall a \in I_{bt} \setminus \{a_t\}$$

(5)

first arc of train  $t$

last arc of train  $t$

$$\forall t \in T$$

(6) work event

# Mathematical Model (cont.)

$$\begin{aligned}
 & x_{bt}^a - x_{bt}^{N_b^a} \leq \textcircled{u_b^a} \quad x_{bt}^{N_b^a} - x_{bt}^a \leq u_b^a \quad \forall b \in B, \forall t \in T, \forall a \in I_{bt} \setminus \{\textcircled{a_{b1}}, \textcircled{a_{b|R_b}}\} \quad (7) \\
 & \sum_{a \in R_b} u_b^a \leq \text{maxNbBlockSwaps}_b \quad \begin{array}{l} \text{if block } b \text{ has a block} \\ \text{swap after arc } a \text{ or not} \end{array} \quad \forall b \in B \quad (8) \quad \left. \begin{array}{l} \text{first arc} \\ \text{of block } b \end{array} \right\} \text{block swap} \\
 & \sum_{\{t \in T: n=O_t\}} z_t - \sum_{\{t \in T: n=D_t\}} z_t \leq \textcircled{s_n} \quad \text{train imbalance in node } n \quad \forall n \in N \quad (9) \\
 & \sum_{\{t \in T: n=D_t\}} z_t - \sum_{\{t \in T: n=O_t\}} z_t \leq s_n \quad \forall n \in N \quad (10) \quad \left. \begin{array}{l} \text{train} \\ \text{imbalance} \end{array} \right\} \\
 & \sum_{t \in T} \text{CrSeg}_t \cdot z_t - \sum_{t \in T} \text{OpCrSeg}_t \cdot z_t \leq \textcircled{c_i} \quad \text{imbalance for crew segment } i \quad \forall i \in C \quad (11) \\
 & \sum_{t \in T} \text{OpCrSeg}_t \cdot z_t - \sum_{t \in T} \text{CrSeg}_t \cdot z_t \leq c_i \quad \forall i \in C \quad (12) \quad \left. \begin{array}{l} \text{crew} \\ \text{imbalance} \end{array} \right\} \\
 & \sum_{b \in B} y_{bt} \leq \text{maxNbBlocksPerTrain} \quad \forall t \in T, \forall b \in B \quad (13) \quad \text{max number of} \\
 & x_{bt}^a, y_{bt}, z_t, w_t^a, u_b^a, k_b \in \{0, 1\} \quad \forall b \in B, \forall t \in T, \forall a \in A \quad (14) \\
 & s_n, c_i \in \mathbb{N} \quad \forall n \in N, \forall i \in C \quad (15)
 \end{aligned}$$

# Data Sets: CSX - railroad company in the US

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## Data 1

- 134 arcs
- 94 nodes
- 239 shipments (1-12 arcs)
- 154 crew segments (1-4 arcs)



- 534 candidate trains

## Data 2

- 294 arcs
- 221 nodes
- 369 shipments (1-17 arcs)
- 154 crew segments (1-7 arcs)



- 575 candidate trains



# Results

Objective Function Component	Data 1		Data 2	
	Cost (\$)	%	Cost (\$)	%
Train Start Cost	23600	1.2	33600	1.1
Train Travel Cost	238692	12.6	267989	8.9
Railcar Travel Cost	1566012.38	82.5	219517.5	72.8
Work Event Cost	47600	2.6	73150	2.4
Block Swap Cost	4050	0.2	5860	0.2
Crew Imbalance Cost	7200	0.4	13800	0.5
Train Imbalance Cost	12000	0.6	4000	0.1
Missed Railcars Cost	0	0	420000	14.0
Total Cost	1899154.38	100	3008556.5	100

# Findings

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- Integrated problem can be solved on real instances
- Crew constraints are the most complex → processed first
- We exploit the cost structure → shortest paths followed by MIP

# Ongoing Research

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- Relax the strong relation with the cost structure
- E.g. combining shipment path generation algorithm with the shipment to train assignment
  - Multioptional shipment paths (e.g. k-shortest paths)
  - Online train generation (column generation)
- Include uncertainty in the model (robust optimization, recovery)
- Include a time dimension (scheduling)