# Fast Algorithms for (Capacitated) Continuous Pricing with Discrete Choice Demand Models 

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## Outline

- Introduction
- Methodology
- Experimental Results
- Conclusions

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## The Continuous Pricing Problem (CPP)

## CPP

- Supplier offers J products for sale. Goal: determine optimal price for each product to maximize total profit.
- There always exists an opt-out option (competition, etc).
- Demand for each product is modeled using a discrete choice model (DCM).


## The Continuous Pricing Problem (CPP)

Pre-estimated DCM

- Utility of alternative $i$ for customer $n$ :

$$
U_{i n}=V_{i n}+\beta_{i n}^{p} p_{i}+\varepsilon_{i n}
$$

- $V_{i n}$ : deterministic utility (exogenous)
- $\beta_{\text {in }}^{p}$ : price sensitivity parameter (exogenous)
- $p_{i}$ : price of alternative $i$ (endogenous)
- $\varepsilon_{\text {in }}$ : stochastic error term

Objective function

- maximize expected revenue $=\sum_{n} \sum_{i} P_{n}(i) p_{i}$


## The Continuous Pricing Problem (CPP)

- Probability that customer $n$ chooses alternative $i$ :

$$
P_{n}(i)=\mathbb{P}\left(U_{i n} \geqslant U_{j n} \forall j \in J\right)
$$

- Logit $\left(\varepsilon_{i n} \sim\right.$ i.i.d. $\left.\operatorname{Gumbel}(0,1)\right)$ :

$$
P_{n}(i)=\frac{e^{V_{i n}}}{\sum_{j \in C_{n}} e^{V_{j n}}}
$$

- Mixed Logit (Logit $+\beta_{k} \sim F\left(\beta_{k} \mid \theta\right)$ ):

$$
P_{n}(i)=\int \frac{e^{V_{i n}\left(\beta_{k n}\right)}}{\sum_{j \in C_{n}} e^{V_{j n}\left(\beta_{k n}\right)}} f\left(\beta_{k} \mid \theta\right) d \beta_{k}
$$

## Literature

Integrating Logit into...

- Revenue Management [Shen and Su, 2007, Korfmann, 2018]

Integrating Nested Logit into...

- Toll setting [Wu et al., 2012]
- Pricing [Gallego and Wang, 2014, Müller et al., 2021]

Integrating Mixed Logit into...

- Toll setting [Gilbert et al., 2014]
- Pricing [Marandi and Lurkin, 2020, van de Geer and den Boer, 2022]


## Literature

Integrating general DCM into optimization problems

- Formulation as a mixed-integer-linear program (MILP) using Monte-Carlo simulation [Paneque et al., 2021]
- Heuristic based on Lagrangian decomposition and grouping of scenarios [Paneque et al., 2022]
- Exact method based on spatial Branch-and-Benders decomposition (B\&BD) + low-dimensional polynomial algorithm (BEA) (without capacity constraints) [Haering et al., 2023]


## New contribution:

- Extend BEA to deal with capacity constraints, develop heuristic (with and without capacities) to handle higher dimensions, use it to speed up B\&BD.


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## Base layer: Monte Carlo Simulation

- Simulate $R$ scenarios (draws), each with deterministic utilities $U_{i n r}$ :

$$
\begin{aligned}
U_{i n r} & =V_{i n}+\beta_{i n r}^{p} p_{i}+\varepsilon_{i n r} & & \forall n \in \mathcal{N}, i \in C_{n}, r \in \mathcal{R} \\
& =c_{i n r}+\beta_{i n r}^{p} p_{i} & & \forall n \in \mathcal{N}, i \in C_{n}, r \in \mathcal{R}
\end{aligned}
$$

## Breakpoints: Illustration

- $\mathbf{1}$ customer, $\mathbf{1}$ controlled price + opt-out
- Breakpoint $\bar{p}_{1}$ :

$$
U_{0}=U_{1} \quad \Longrightarrow \quad U_{0}=c_{1}+\beta_{1}^{p} \bar{p}_{1} \quad \Longrightarrow \quad \bar{p}_{1}=\frac{U_{0}-c_{1}}{\beta_{1}^{p}} .
$$



## Breakpoints: Illustration

- 3 customers, 1 controlled price + opt-out
- Numbers: how many customers are captured



## Breakpoint Exact Algorithm (BEA) [Haering et al., 2023]



## Adding capacity constraints

- Evaluating the objective function is not more difficult (assume exogenous priority queue).
- Need to compute breakpoints from not only the utility of the best alternative so far but from all alternative's utilities, due to people no longer always choosing highest utility alternative.
$\Longrightarrow$ Customers may switch from any of the previously introduced alternatives.


## Breakpoint Exact Algorithm with Capacities (BEAC)



## Breakpoint Heuristic Algorithm (BHA)

## Coordinate descent



## BHA extended via dynamic line search (DLS)

## Escape local optima



## Guiding an exact method using the heuristic solution

- Goal is to improve exact spatial Branch \& Benders algorithm.
- Main way to speed up a Branch and Bound algorithm is to improve the bounds.
- Heuristic solution provides strong upper bound (initial feasible solution) $\rightarrow$ Reduces the number of nodes in the tree.
- Improve lower bounds: Valid inequalities.


## Valid inequalities

Breakpoints only work if everything but one price is fixed. But...

For each simulated customer ( $n, r$ ):

- minimal breakpoint $\check{p}_{i}^{n r}$ (assuming strongest competition)
- maximal breakpoint $\hat{p}_{i}^{n r}$ (assuming weakest competition)

$$
\begin{array}{lll}
p_{i} \leqslant \check{p}_{i}^{n r} & \Longrightarrow(n, r) \text { is guaranteed to select } i & \Longrightarrow \omega_{i n r} \geqslant 1 \\
p_{i} \geqslant \hat{p}_{i}^{n r} & \Longrightarrow(n, r) \text { is guaranteed to not select } i & \Longrightarrow \omega_{i n r} \leqslant 0, \eta_{i n r} \leqslant 0
\end{array}
$$

Improving bounds on prices

We can consider:

$$
\begin{aligned}
& \check{p}_{i}:=\min _{n, r} \check{p}_{i}^{n r} \\
& \hat{p}_{i}:=\max _{n, r} \hat{p}_{i}^{n r}
\end{aligned}
$$

knowing that:

$$
\begin{gathered}
p_{i}>\hat{p}_{i} \Longrightarrow \text { no one chooses alternative } i \\
p_{i}<\check{p}_{i} \Longrightarrow \begin{array}{c}
\text { everyone chooses alternative } i \\
\text { (if it is in their choice set) }
\end{array}
\end{gathered}
$$

## Improving bounds on prices

We can also say:
$p_{i}>m$-th highest $\hat{p}_{i}^{n r} \Longrightarrow$ at most $m$ simulated customers choose alternative $i$
$p_{i}<m$-th lowest $\check{p}_{i}^{n r} \Longrightarrow$ at least $m$ simulated customers choose alternative $i$

- Allows to adapt bounds to aim at specific outcomes.
- We will assume that for each product there should be at least one customer/scenario in which a product is chosen, as else it could be removed from the set of offered products.
- $\Longrightarrow$ Replace $p_{i}^{U}$ by $\hat{p}_{i}$ whenever $\hat{p}_{i}<p_{i}^{U}$.


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## Case Study

Parking space operator [lbeas et al., 2014]

- Alternatives: Paid-Street-Parking (PSP), Paid-Underground-Parking (PUP) and Free-Street-Parking (FSP).
- Optimize prices for PSP and PUP, FSP is the opt-out alternative.
- Socio-economic characteristics: trip origin, vehicle age, driver income, residence area.
- Product attributes: access time to parking, access time to destination, and parking fee (price).
- Add more alternatives by increasing access time to destination.
- Choice model is a Mixed Logit, $\beta_{\text {fee }}, \beta_{\text {time_parking }} \sim \mathcal{N}(\mu, \sigma)$.


## Results

Table 1: MILP vs. BEAC in the capacitated case

|  |  |  | MILP |  |  | BEAC |  |  |
| ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| $N$ | $n$ | $J$ |  | Time (s) | Profit |  | Time (s) | Profit |
| 50 | 2 | 2 | 4.17 | 27.61 |  | 0.43 | 27.61 |  |
| 50 | 5 | 2 |  | 46.95 | 26.51 |  | 1.72 | 26.51 |
| 50 | 10 | 2 |  | 180.85 | 27.06 |  | 11.42 | 27.06 |
| 50 | 25 | 2 |  | 3119.66 | 27.08 |  | 169.08 | 27.08 |
| 50 | 50 | 2 | $>5$ hours | $\geqslant 25.15$ |  | 1272.68 | 26.85 |  |
| 50 | 100 | 2 | $>25$ hours | $\geqslant 25.11$ |  | 9928.57 | 26.85 |  |
| 50 | 250 | 2 | $>45$ hours | $\geqslant 23.45$ |  | $>45$ hours | $\geqslant 25.00$ |  |

## Results

Table 2: BHA and DLS vs. MILP and BEAC in the capacitated case

|  |  |  | MILP |  |  | BEAC |  |  | BHA |  |  |  |
| ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |

## Results

| $N$ | $R$ | $J$ | BHA (s) |
| :--- | :--- | :--- | :--- |
| 50 | 1000 | 2 | 15093 |
| 50 | 1000 | 3 | 25326 |
| 50 | 1000 | 4 | 69134 |
| 50 | 1000 | 5 | 112042 |
| 50 | 1000 | 6 | 178923 |
| 50 | 2000 | 2 | 51637 |
| 50 | 2000 | 3 | 84231 |
| 50 | 2000 | 4 | 150132 |
| 50 | 2000 | 5 | 193233 |
| 50 | 3000 | 2 | 164922 |
| 50 | 3000 | 3 | 184293 |
| 50 | 3000 | 4 | $>259200$ |

## Results

Table 3: BHA and DLS vs. B\&BD and BEA in the uncapacitated case

| $N$ | $R$ | $J$ | B\&BD |  | BEA |  | BHA |  | DLS |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Time (s) | Profit | Time (s) | Profit | Time (s) | Profit | Time (s) | Profit |
| 50 | 200 | 1 | 19 | 23.96 | 0 | 23.96 | 0.00 | 23.96 | 0.02 | 23.96 |
| 50 | 200 | 2 | 1413 | 26.99 | 12 | 26.99 | 0.00 | 26.99 | 0.03 | 26.99 |
| 50 | 200 | 3 | 34340 | 26.54 | 39,636 | 26.54 | 0.01 | 26.54 | 0.05 | 26.54 |
| 20 | 100 | 4 | 12478 | 10.40 | $>24$ hours | $\geqslant 9.81$ | 0.00 | 10.40 | 0.14 | 10.40 |
| 20 | 200 | 4 | 29213 | 10.40 | $>24$ hours | $\geqslant 10.40$ | 0.01 | 10.40 | 0.41 | 10.40 |
| 20 | 300 | 4 | $>24$ hours | $\geqslant 10.38$ | $>24$ hours | $\geqslant 10.13$ | 0.02 | 10.24 | 0.64 | 10.24 |
| 20 | 400 | 4 | $>24$ hours | $\geqslant 9.81$ | $>24$ hours | $\geqslant 9.42$ | 0.05 | 10.26 | 0.78 | 10.26 |
| 20 | 500 | 4 | $>24$ hours | $\geqslant 10.01$ | $>24$ hours | $\geq 9.67$ | 0.13 | 10.24 | 1.37 | 10.24 |

## Results

Table 4: BHA vs. B\&BD solution quality

| $N$ | $R$ | $J$ | BHA | B\&BD | Gap (\%) |
| :--- | :--- | :--- | :--- | :--- | :--- |
| 20 | 20 | 3 | 10.281 | 10.281 | 0 |
| 20 | 20 | 4 | 10.271 | 10.28 | 0.09 |
| 20 | 20 | 5 | 10.283 | 10.294 | 0.11 |
| 20 | 20 | 6 | 10.290 | 10.302 | 0.12 |
| 20 | 20 | 7 | 10.292 | 10.306 | 0.14 |
| 20 | 20 | 8 | 10.330 | 10.336 | 0.06 |
| 20 | 20 | 9 | 10.329 | 10.335 | 0.06 |
| 20 | 20 | 10 | 10.293 | 10.300 | 0.07 |

## Results

| $N$ | $R$ | $J$ | BHA (s) |
| :--- | :--- | :--- | :--- |
| 50 | 500000 | 2 | 56.19 |
| 50 | 500000 | 3 | 77.46 |
| 50 | 500000 | 4 | 187.41 |
| 50 | 500000 | 5 | 163.23 |
| 50 | 500000 | 6 | 194.24 |
| 50 | 1000000 | 2 | 68.24 |
| 50 | 1000000 | 3 | 132.98 |
| 50 | 1000000 | 4 | 312.43 |
| 50 | 1000000 | 5 | 300.40 |
| 50 | 1000000 | 6 | 412.53 |

## Results

Table 5: B\&BD with Guidance - 10\% gap

| $N$ | $R$ | J | normal w/out VIs (s) | $\begin{gathered} \text { normal } \\ \text { w VIs (s) } \end{gathered}$ | Guided w/out VIs (s) | Guided w VIs (s) | Speedup from just VIs (\%) | Add. Speedup from Sol. (\%) | Total speedup (\%) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 50 | 1000 | 3 | 987 | 1132 | 731 | 816 | -14.69 | 27.92 | 17.33 |
| 50 | 2000 | 3 | 2878 | 3490 | 2513 | 2693 | -21.26 | 22.84 | 6.43 |
| 50 | 3500 | 3 | 10325 | 12919 | 6390 | 7454 | -25.12 | 42.3 | 27.81 |
| 50 | 1000 | 4 | 4662 | 3311 | 3705 | 2472 | 28.98 | 25.34 | 46.98 |
| 50 | 2000 | 4 | 17599 | 12068 | 10868 | 8288 | 31.43 | 31.32 | 52.91 |
| 50 | 3500 | 4 | 48445 | 31210 | 40061 | 29504 | 35.58 | 5.47 | 39.1 |
| 50 | 1000 | 5 | 8242 | 5428 | 5664 | 3914 | 34.14 | 27.89 | 52.51 |
| 50 | 2000 | 5 | 25842 | 16641 | 17420 | 12268 | 35.6 | 26.28 | 52.53 |
| 50 | 3500 | 5 | 114216 | 81826 | 85083 | 58754 | 28.36 | 28.2 | 48.56 |

## Results

Table 6: B\&BD with Guidance - $5 \%$ gap

| $N$ | $R$ | $J$ | normal w/out VIs (s) | normal w VIs (s) | Guided w/out VIs (s) | Guided w VIs (s) | Speedup from just VIs (\%) | Add. Speedup from Sol. (\%) | Total speedup (\%) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 50 | 1000 | 3 | 2372 | 2454 | 1933 | 2245 | -3.46 | 8.52 | 5.35 |
| 50 | 2000 | 3 | 7883 | 8359 | 7106 | 7342 | -6.04 | 12.17 | 6.86 |
| 50 | 3500 | 3 | 51964 | 57229 | 42991 | 47282 | -10.13 | 17.38 | 9.01 |
| 50 | 1000 | 4 | 12062 | 10668 | 10490 | 8934 | 11.56 | 16.25 | 25.93 |
| 50 | 2000 | 4 | 43829 | 36524 | 36222 | 32929 | 16.67 | 9.84 | 24.87 |
| 50 | 3500 | 4 | 259200 | 240767 | 238777 | 198981 | 7.11 | 17.36 | 23.23 |
| 50 | 1000 | 5 | 24371 | 20590 | 19519 | 16930 | 15.51 | 17.78 | 30.53 |
| 50 | 2000 | 5 | 84104 | 60814 | 70676 | 48541 | 27.69 | 20.18 | 42.28 |
| 50 | 3500 | 5 | 259200 | 259200 | 259200 | 247944 | , | - | - |

## Results

Table 7: $\mathrm{B} \& \mathrm{BD}$ with Guidance - $1 \%$ gap

| $N$ | $R$ | $J$ | normal <br> w/out VIs (s) | normal <br> w VIs (s) | Guided <br> w/out VIs (s) | Guided <br> w VIs (s) | Speedup <br> from just VIs (\%) | Add. Speedup <br> from Sol. (\%) | Total <br> speedup (\%) |
| ---: | ---: | ---: | ---: | ---: | :---: | ---: | ---: | ---: | ---: |
| 50 | 1000 | 3 | 15840 | 16933 | 13239 | 14594 | -6.9 | 13.81 | 7.87 |
| 50 | 2000 | 3 | 42261 | 45223 | 35882 | 37137 | -7.01 | 17.88 | 12.12 |
| 50 | 3500 | 3 | 183696 | 195743 | 152833 | 162594 | -6.56 | 16.93 | 11.49 |
| 50 | 500 | 4 | 47101 | 46719 | 47963 | 43190 | 0.81 | 7.55 | 8.3 |
| 50 | 1000 | 4 | 13122 | 135564 | 107288 | 105596 | -3.39 | 22.11 | 19.47 |
| 50 | 1500 | 4 | 229620 | 230187 | 203348 | 202560 | -0.25 | 12 | 11.78 |
| 50 | 2000 | 4 | 259200 | 259200 | 259200 | 259200 | - | - | - |
| 50 | 500 | 5 | 139618 | 125755 | 115783 | 109084 | 9.93 | 13.26 | 21.87 |
| 50 | 1000 | 5 | 259200 | 259200 | 259200 | 259200 | - | - | - |

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## Conclusions

With capacity constraints

- Exact: BEAC $\approx 20$ times faster than MILP (for two prices or less).
- Heuristic: BHA up to 1000x times faster than BEAC (especially in high dim).

Without capacity constraints

- Heuristic: BHA outspeeds other approaches by factors $\geqslant \mathbf{1 0}^{\mathbf{6}}$ but can get stuck in locally.
- Exact: Using the solution of the BHA together with valid inequalities, we can speed up the exact spatial $B \& B D$ algorithm by $\approx \mathbf{2 0 \%}$ (more in the beginning).

Future work

## Pricing

- Assortment optimization on top of pricing.
- Could add any constraints for BEA / BHA since they only evaluate objective function.
- Improve escaping local optima.

Extension to other optimization problems

- Facility location, Airline scheduling and fleet assignment.
- Maximum likelihood estimation (utility depending on multiple parameters)
- B\&BD
- BEA X
- BHA $\checkmark \rightarrow$ Tradeoff between large $R$ and optimality gap. Does not require linearity in $\beta$.

Appendix - Utility parameters reported in [lbeas et al., 2014]

| Parameter | Value |
| :--- | ---: |
| ASC FSP | 0.0 |
| ASCPSP | 32.0 |
| ASC PUP | 34.0 |
| Fee ( $€$ ) | $\sim \mathcal{N}(-32.328,14.168)$ |
| Fee PSP - low income $(€)$ | -10.995 |
| Fee PUP - low income ( $€$ ) | -13.729 |
| Fee PSP - resident $(€)$ | -11.440 |
| Fee PUP - resident $(€)$ | -10.668 |
| Access time to parking $(\min )$ | $\sim \mathcal{N}(-0.788,1.06)$ |
| Access time to destination $(\min )$ | -0.612 |
| Age of vehicle $(1 / 0)$ | 4.037 |
| Origin $(1 / 0)$ | -5.762 |

## MILP formulation [Paneque et al., 2021]

$$
\begin{equation*}
\max _{p, \omega, U, h} \frac{1}{R} \sum_{r \in \mathcal{R}} \sum_{n \in \mathcal{N}} \sum_{i \in C_{n}} p_{i} \omega_{i n r} \tag{o}
\end{equation*}
$$

s.t.

$$
\begin{aligned}
& \sum_{i \in C_{n} \cup\{0\}} \omega_{i n r}=1 \\
& h_{n r}=c_{0 n r} \omega_{0 n r}+\sum_{i \in C_{n}} U_{i n r} \omega_{i n r} \\
& h_{n r} \geqslant c_{0 n r} \\
& h_{n r} \geqslant U_{i n r} \\
& U_{i n r}=c_{i n r}+\beta_{p}^{i n} p_{i} \\
& \omega \in\{0,1\}^{(J+1) N R} \\
& p \in\left[p_{1}^{L}, p_{1}^{U}\right] \times \ldots \times\left[p_{J}^{L}, p_{J}^{U}\right] \\
& U, h \in \mathbb{R}^{J N R}, \mathbb{R}^{N R}
\end{aligned}
$$

## Results BEA

| $N$ | $R$ | $J$ | BEA (s) |
| :--- | :--- | :--- | :--- |
| 50 | 500 | 3 | 117167 |
| 50 | 1000 | 3 | 259200 |
| 50 | 1500 | 3 | 259200 |
| 50 | 2000 | 3 | 259200 |
| 50 | 2500 | 3 | 259200 |
| 50 | 3000 | 3 | 259200 |
| 50 | 3500 | 3 | 259200 |

## Breakpoint Exact Algorithm (BEA) [Haering et al., 2023]

```
Result: optimal solution \(p^{*}\) and profit \(o^{*}\) for CPP.
```

```
p
```

p
o*}\leftarrow
o*}\leftarrow
for s in S do
for s in S do
$p_{s_{j}} \leftarrow 0 \quad \forall j \in\{1, \ldots, J\}$
$h_{n r}^{s_{1}} \leftarrow c_{0 n r} \quad \forall(n, r) \in \mathcal{N} \times \mathcal{R}$
$\eta_{n r} \leftarrow 0 \quad \forall(n, r) \in \mathcal{N} \times \mathcal{R}$
$(\hat{p}, \hat{o}) \leftarrow$ enumerate $\left(s, p, h^{s_{1}}, \eta, 1\right)$
if $\hat{o}>o^{*}$ then
$p^{*} \leftarrow \hat{p} ;$
$o^{*} \leftarrow \hat{o} ;$
end
end

```
Algorithm 1: Breakpoint Exact Algorithm (BEA) to solve the CPP

\section*{Capacity constraints}
\[
\begin{array}{lr}
\omega_{i n r} \leqslant y_{i n r} & \forall i \in C_{n}, \in \mathcal{N}, r \in \mathcal{R} \\
\sum_{m=1}^{n} \omega_{i m r} \leqslant \underset{\substack{\left(c_{i}-1\right) y_{i n r}+\\
(n-1)\left(1-y_{i n r}\right)}}{ } & \forall i \in C_{n}, n>c_{i} \in \mathcal{N}, r \in \mathcal{R} \\
\sum_{m=1}^{n} \omega_{i m r} \geqslant c_{i}\left(1-y_{i n r}\right) & \forall i \in C_{n}, n>1 \in \mathcal{N}, r \in \mathcal{R}
\end{array}
\]

\section*{Compute Objective Value with Priority Queue}
```

Function compute_objective_value_with_priority_queue( }p,c,\mathrm{ prio_queue):
\varsigma\leftarrow(0) i\inC
for idx f prio_queue do
u\leftarrow[UUidx for i\inC]
a}\leftarrow\operatorname{sort(}(u,\mathrm{ descending)
\varphi \leftarrow false
j\leftarrow1
while j\leqslantC-1 and ! }\varphi\mathrm{ do
if }\mp@subsup{\varsigma}{\mp@subsup{a}{j}{}}{}\leqslant\mp@subsup{c}{\mp@subsup{a}{j}{}}{}-1\mathrm{ then
\varsigma}\mp@subsup{\}{j}{}+=
\varphi \leftarrow true
end
else
j+=1
end
end
end
o}\leftarrow\mp@subsup{\sum}{i\inC}{}\mp@subsup{\varsigma}{i}{}\cdot\mp@subsup{p}{i}{
return o
end

```

\section*{Compute Objective Value with Capacities (profit max/min)}
```

Function compute_objective_value_with_capacities ( $p, c ; \max$ ):
$s \leftarrow \operatorname{sortperm}(p)$
$\varsigma \leftarrow(0)_{i \in C}$
$A \leftarrow\}$
for $i d x \in \mathcal{N} \times \mathcal{R}$ do
$u \leftarrow\left[U_{i d x}^{i}\right.$ for $\left.i \in C\right]$
$a \leftarrow \operatorname{sort}(u$, descending)
$A \leftarrow A \cup\{a\}$
if max then
$A \leftarrow \operatorname{sort}(A$, ascending $)$
else
$L A \leftarrow \operatorname{sort}(A$, descending $)$
while $|A| \geqslant 1$ do
$\pi \leftarrow A_{11}$
$A \leftarrow A \backslash\left\{A_{1}\right\}$
if $\pi \geqslant 1$ then
$\varsigma_{s_{\text {next_pref }}}+=1$
if $\varsigma_{S_{\text {next_pref }}}=c_{s_{\text {next_pree }}}$ then
Remove all entries $\pi$ from $A$
if $\max$ then
$A \leftarrow \operatorname{sort}(A$, ascending $)$
else
$A \leftarrow \operatorname{sort}(A$, descending $)$

```

\section*{Results}

Table 8: Test 2: Priority queue vs. Max profit vs. Robust Optimization
\begin{tabular}{|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{\(N\)} & \multirow[b]{2}{*}{\(R\)} & \multirow[b]{2}{*}{\(J\)} & \multicolumn{2}{|l|}{BEAC} & \multicolumn{2}{|l|}{BEAC-M} & \multicolumn{2}{|l|}{BEAC-R} \\
\hline & & & Time (s) & Profit & Time (s) & Profit & Time (s) & Profit \\
\hline 50 & 2 & 2 & 0.43 & 27.61 & 0.44 & 28.81 & 0.45 & 27.61 \\
\hline 50 & 5 & 2 & 1.72 & 26.51 & 1.78 & 28.44 & 1.82 & 26.46 \\
\hline 50 & 10 & 2 & 11.42 & 27.06 & 12.88 & 28.3 & 12.98 & 27.01 \\
\hline 50 & 25 & 2 & 169.08 & 27.08 & 197.23 & 28.58 & 189.28 & 27.06 \\
\hline 50 & 50 & 2 & 1272.68 & 26.85 & 1513.44 & 28.61 & 1523.89 & 26.85 \\
\hline 50 & 100 & 2 & 9928.57 & 26.85 & 12093.8 & 28.57 & 12494.13 & 26.85 \\
\hline 50 & 250 & 2 & \(>45\) hours & \(\geqslant 25.00\) & \(>45\) hours & \(\geqslant 26.63\) & \(>45\) hours & \(\geqslant 24.34\) \\
\hline
\end{tabular}

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