

CIVIL-557

Decision-aid methodologies in transportation

**Lecture 3:
Logistic regression and probabilistic metrics**

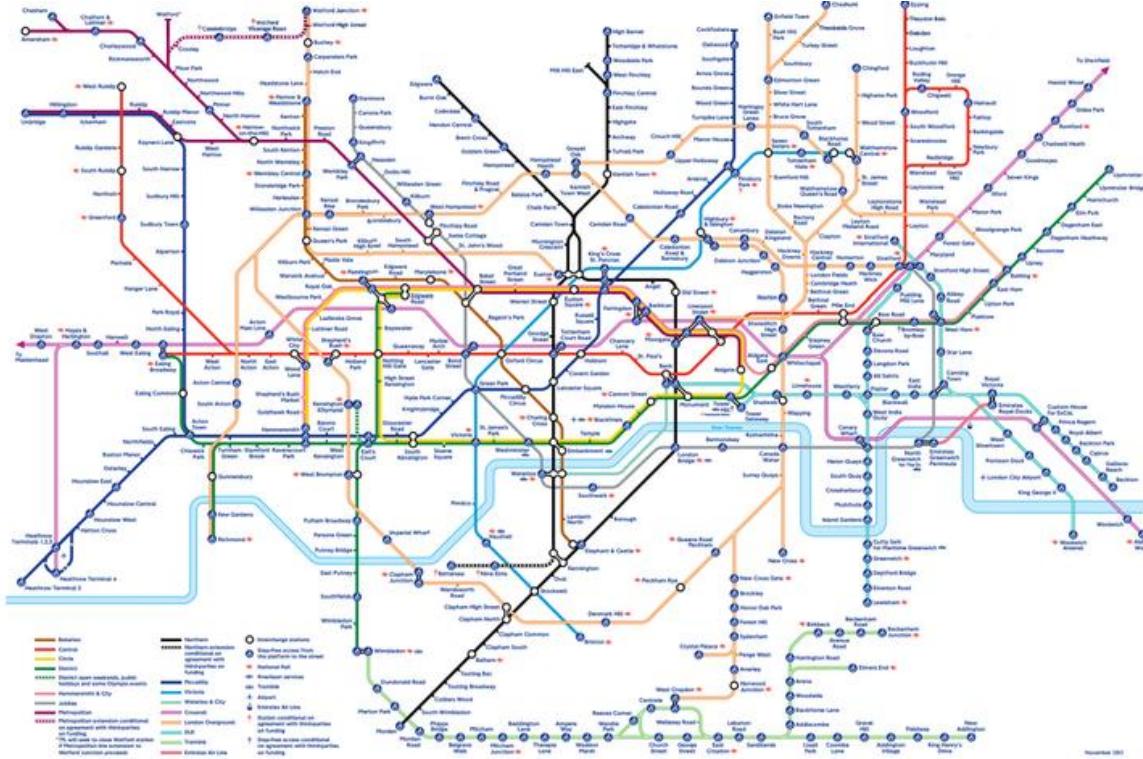
Tim Hillel

**Transport and Mobility Laboratory TRANSP-OR
École Polytechnique Fédérale de Lausanne EPFL**

Case study

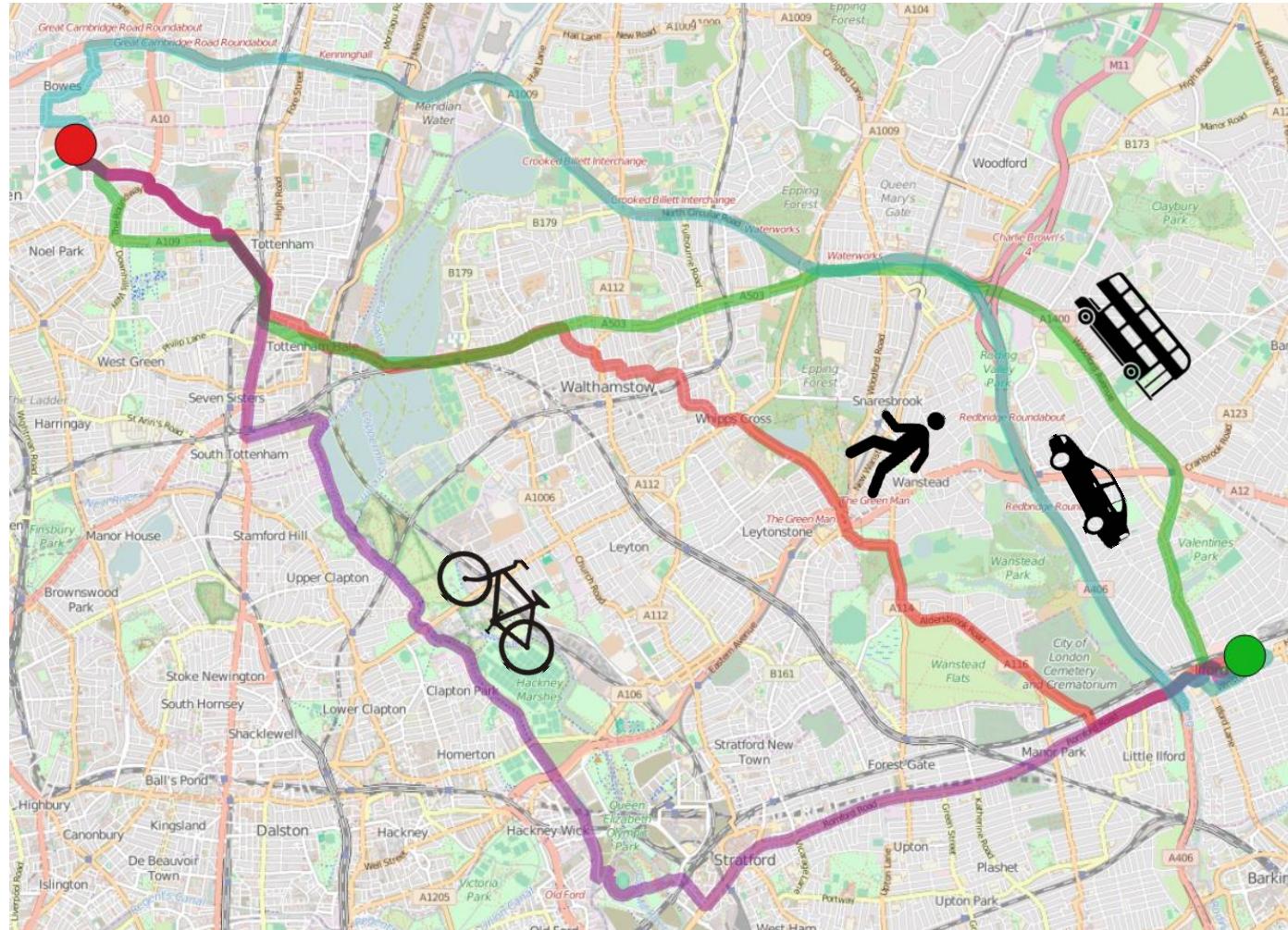


Transport for London



November 2011

Mode choice



TRANSP-OR

EPFL

Last week

- Data science process
- Dataset
- Deterministic methods
 - K-Nearest Neighbours (KNN)
 - Decision Tree (DT)
- Discrete metrics

Today

- Theory of probabilistic classification
- Probabilistic metrics
- Probabilistic classifiers
 - Logistic regression

But first...

...a bit more **feature processing**

Feature processing

- Last week - scaling
 - Crucial when algorithms consider **distance**
 - *Standard scaling* – zero-mean unit-variance
- What about missing values?
- And categorical data?

Missing values

	start_time_linear	age	female	driving_license	car_ownership	distance
20679	10.000000	46	0	1.0	0	5410
7276	7.500000	68	1	0.0	0	7725
11816	10.250000	37	0	NaN	1	2939
66175	8.750000	18	0	1.0	2	20205
73216	10.750000	44	1	NaN	1	12646
33259	15.333333	19	1	0.0	0	11436
27837	17.666667	62	1	1.0	1	1425
56018	21.500000	48	0	1.0	1	8820

Missing values

Possible solutions?

- Remove **rows** (instances)
- Remove **columns** (features)
- Assume **default value**
 - Zero
 - Mean
 - Random value
 - Other?

Missing values

- Removing rows – can introduce **sampling bias!**
- Removing columns – reduces available features
- Default value – needs to make sense

Categorical variables

	travel_mode	purpose	fueltype	faretype	bus_scale	survey_year
20679	pt	B	Average_Car	full	1.0	1
7276	pt	B	Average_Car	free	0.0	1
11816	drive	HBO	Petrol_Car	full	1.0	1
66175	drive	NHBO	Petrol_Car	dis	0.0	3
73216	pt	HBE	Diesel_Car	full	1.0	3
33259	pt	HBO	Average_Car	full	0.0	2
27837	drive	HBO	Diesel_Car	free	0.0	2
56018	drive	HBO	Petrol_Car	full	1.0	3

Categorical data

All data must be numerical – possible solutions?

- Numerical encoding
- Binary encoding
- Remove feature?

Numerical encoding

Blue

Silver

Red

Implies **order**:

Blue < Silver < Red

and **distance**:

Red – Silver = Silver - Blue

Binary encoding

Blue

Silver

Red

Car	Colour:Blue	Colour:Silver	Colour:Red
1	0	1	0
2	1	0	0
3	0	0	1
4	1	0	0
...

A lot more features!

Validation schemes

Train-test split:



Test set must be **unseen data**.

- How to sample test set?
- How to test model hyperparameters?

Sampling test set

Previously used **random sampling**

- Assumes data is **independent**
- Not always a good assumption
 - Sampling bias/recording errors
 - Hierarchical data

Instead, use **external validation**

- Validate the model on data **sampled separately** from the training data (e.g. separate year)

Testing model hyperparameters

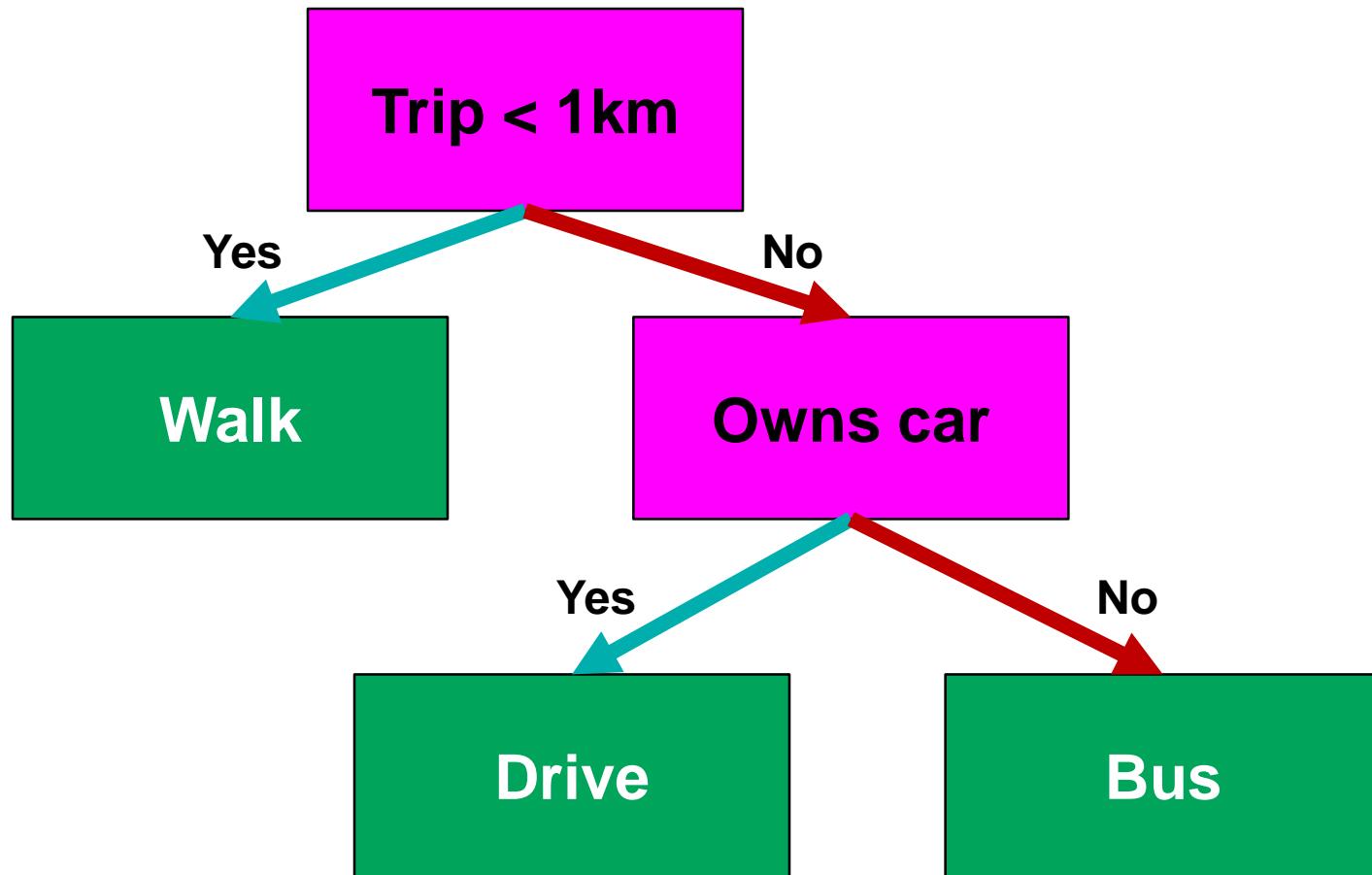
Can only be performed on the training data

Possible solution – split again:

Train-validate-test



Decision trees



DT Metrics

GINI Impurity:

$$G(p) = \sum_{i=1}^J p_i(1 - p_i) = 1 - \sum_{i=1}^J p_i^2$$

Entropy:

$$H(p) = - \sum_{i=1}^J p_i \log_2 p_i$$

where p_i is the proportion of class i

Decision trees

Remember: Decision trees only see ranking of feature values....

...therefore **scaling** does not need to be applied!

Notebook I: Categorical features

Probabilistic classification

- Previously considered **deterministic classifiers**
 - Classifier predicts discrete class \hat{y}
- Now consider **probabilistic classification**
 - Classifier predicts continuous probability for each class

Notation

- Dataset D contains N elements
- J classes
- Each element n associated with:
 - Feature vector x_n of k real features
 - ◆ $x_n \in \mathbb{R}^k$
 - Set of class indicators $y_n \in \{0,1\}^J$:
 - ◆ $\sum_{j=1}^J y_{jn} = 1$
- Selected class (ground-truth)
 - $i_n = \sum_{i=1}^J i y_{in}$

Notation continued

- Classifier P maps feature vector x_n to probability distribution across J classes
 - $P: \mathbb{R}^k \rightarrow [0,1]^J$
- Probability for each class i :
 - $P(i|x_n) > 0$
 - $\sum_{i=1}^J P(i|x_n) = 1$
- Therefore, probability for **selected** (ground-truth) class:
 - $P(i_n|x_n)$

Example

- Four modes (*walk, cycle, pt, drive*)
 - $J = 4$
- For *pt* trip:
 - $y_n = (0, 0, 1, 0)$
 - $i_n = 3$
- Predicted probabilities for arbitrary classifier P
 - $P(x_n) = (0.1, 0.2, 0.4, 0.3)$
 - $P(i_n|x_n) = 0.4$

Likelihood

n	i_n	$P(1 x_n)$	$P(2 x_n)$	$P(3 x_n)$	$P(4 x_n)$	$P(i_n x_n)$
1	2	0.11	0.84	0.03	0.02	0.84
2	1	0.82	0.04	0.06	0.08	0.82
3	4	0.11	0.18	0.05	0.66	0.66
4	1	0.57	0.22	0.12	0.09	0.57
5	3	0.10	0.03	0.75	0.12	0.75

□ Likelihood:

- $= \prod_{n=1}^N P(i_n|x_n)$
- $= 0.84 \times 0.82 \times 0.66 \times 0.57 \times 0.75$
- $= 0.2036$

Likelihood

n	i_n	$P(1 x_n)$	$P(2 x_n)$	$P(3 x_n)$	$P(4 x_n)$	$P(i_n x_n)$
1	4	0.11	0.84	0.03	0.02	0.02
2	1	0.82	0.04	0.06	0.08	0.82
3	4	0.11	0.18	0.05	0.66	0.66
4	1	0.57	0.22	0.12	0.09	0.57
5	3	0.10	0.03	0.75	0.12	0.75

□ Likelihood:

- $= \prod_{n=1}^N P(i_n|x_n)$
- $= 0.02 \times 0.82 \times 0.66 \times 0.57 \times 0.75$
- $= 0.0046$

Log-likelihood

- Likelihood bound between 0 and 1
- Tends to 0 as N increases
 - Computational issues with small numbers
- Use *log-likelihood*:
 - $= \ln(\prod_{n=1}^N P(i_n | x_n))$
 - $= \sum_{n=1}^N \ln P(i_n | x_n)$

Log-likelihood

n	i_n	$P(1 x_n)$	$P(2 x_n)$	$P(3 x_n)$	$P(4 x_n)$	$P(i_n x_n)$
1	2	0.11	0.84	0.03	0.02	0.84
2	1	0.82	0.04	0.06	0.08	0.82
3	4	0.11	0.18	0.05	0.66	0.66
4	1	0.57	0.22	0.12	0.09	0.57
5	3	0.10	0.03	0.75	0.12	0.75

□ Log-likelihood:

- $= \sum_{n=1}^N \ln P(i_n|x_n)$
- $= \ln(0.84 \times 0.82 \times 0.66 \times 0.57 \times 0.75)$
- $= -1.638$

Log-likelihood

n	i_n	$P(1 x_n)$	$P(2 x_n)$	$P(3 x_n)$	$P(4 x_n)$	$P(i_n x_n)$
1	4	0.11	0.84	0.03	0.02	0.02
2	1	0.82	0.04	0.06	0.08	0.82
3	4	0.11	0.18	0.05	0.66	0.66
4	1	0.57	0.22	0.12	0.09	0.57
5	3	0.10	0.03	0.75	0.12	0.75

□ Log-likelihood:

- $= \sum_{n=1}^N \ln P(i_n|x_n)$
- $= \ln(0.02 \times 0.82 \times 0.66 \times 0.57 \times 0.75)$
- $= -5.376$

Cross-entropy loss

- Log-likelihood bound between $-\infty$ and 0
 - Tends to $-\infty$ as N increases
- Can't compare between different dataset sizes
 - Normalize (divide by N) to get cross-entropy loss (CEL) H
 - Typically take negative

$$L = \frac{-1}{n} \sum_{n=1}^N \ln P(i_n | x_n)$$

Cross-entropy loss

- Can also derive from **Shannon's cross entropy** $H(p, q)$ (hence name)
- Minimising cross-entropy loss equivalent to **maximising likelihood of data under the model**
 - Maximum likelihood estimation (MLE)
- Other metrics exist e.g. Brier score (MSE), but CEL is *golden standard*

Probabilistic classifiers

- Need a model which generates multiclass probability distribution from feature vector x_n
- Lot's of possibilities!
- Today, **logistic regression**

Linear regression

- Logistic regression is an extension of **linear regression**
 - Often called *linear models*

$$f(x) = \sum_{k=1}^K \beta_k x_k + \beta_0$$

- Find parameters (β) using **gradient descent**
 - Typically minimise MSE

Logistic regression

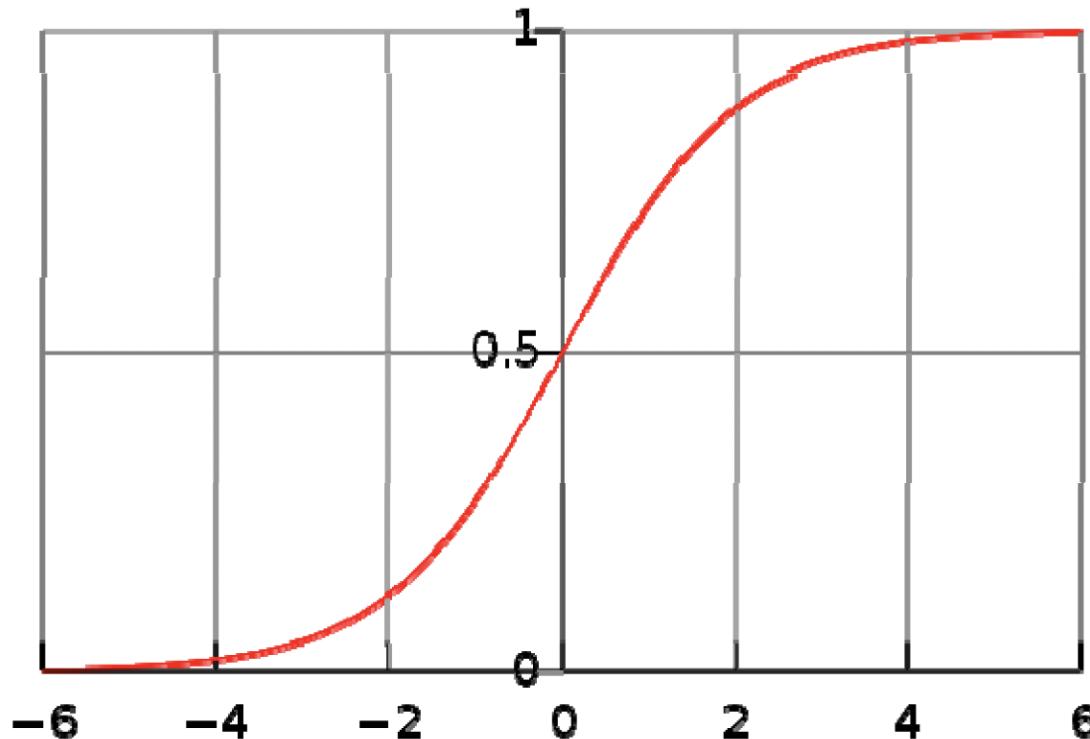
- Pass linear regression through function σ

$$f(x) = \sigma\left(\sum_{k=1}^K \beta_k x_k + \beta_0\right)$$

- σ needs to take real value and return value in $[0,1]$
 - $\sigma(z) \in [0,1] \quad \forall x \in \mathbb{R}$

Binary case – sigmoid function

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$



Multinomial case – softmax function

$$\sigma(z)_i = \frac{e^{z_i}}{\sum_{j=1}^J e^{z_j}}$$

Logistic regression

- Separate set of parameters (β) for each class i
 - Normalised to zero for one class
- Separate value z for each class
 - *Utilities in Discrete Choice Models*
- Minimise cross-entropy loss (MLE)
- Solve using gradient descent for parameters
 - $\beta^* = \arg \min_{\beta} L_{\beta}$

Issues

- Overconfidence
 - Linearly separable data – parameters tend to infinity (unrealistic probability estimates)
- Outliers
 - Outliers can have disproportionate effect on parameters (high variance)
- Multi-collinearity
 - If features are highly correlated, can cause numerical instability

Solution: Regularisation

- Penalise model for large parameter values
 - Reduces variance (therefore *overfitting*)
- Regularisation
 - $\beta^* = \arg \min_{\beta} \{L_{\beta} + C \times f(\beta)\}$
- Two candidates for f
 - L1 normalisation (LASSO)
 - ◆ $\sum_i |\beta_i|$ (similar to Manhattan distance)
 - L2 normalisation (Ridge)
 - ◆ $\sum_i \beta^2$ (similar to Euclidean distance)

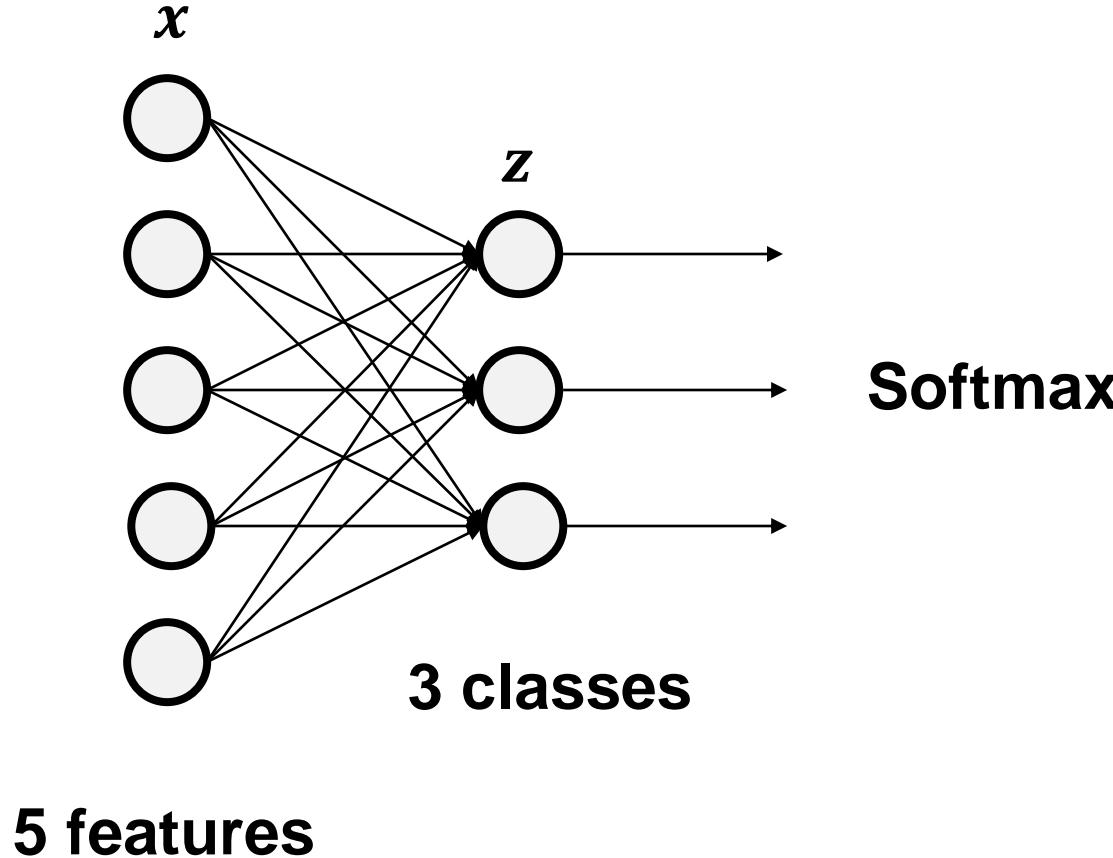
Regularisation

- L1 regularisation shrinks less important parameters to zero
 - Feature selection?
- L2 regularisation penalises larger parameters more

Regularisation

- C and choice of regularisation (L1/L2) are **hyperparameters**
- Larger C , more regularisation (higher bias, lower variance)

Logistic regression



Homework

Notebook 2: Logistic regression