Decison-Aid Methodologies in Transportation Optimization Exercise 6

Tomáš Robenek

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Quay Crane Scheduling Problem

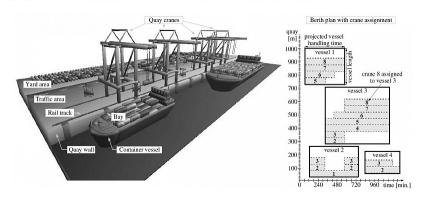


Figure: source:

http://prodlog.wiwi.uni-halle.de/forschung/container/?lang=en





How it looks like

- http://www.youtube.com/watch?v=a1clxIUzwBY
- http://www.youtube.com/watch?v=xWTZTwL-hzY
- http://www.youtube.com/watch?v=wlPQcJhbLIY



Model

- presented in the lecture
- minimize the handling time of the vessels
- constraints to cover:
 - handling of the vessel is finished, when all the cranes finished their work
 - time it takes to complete a bay
 - a bay is handled exactly by one crane
 - a bay is completed in one run, i.e. the crane is not allowed to complete half of a bay, work on another bay and then come back to complete it
 - overtaking of cranes not allowed (rail)
 - overtaking of inactive cranes
 - the first and the last crane, can not be pushed out of the rail



- you need to solve several instances
- some are more difficult to solve than the others, hence following time limit is set (10 min):

```
execute
{
     cplex.tilim = 600;
}
```

References





Yan Wang and Kap Hwan Kim, *A quay crane scheduling algorithm considering the workload of yard cranes in a container yard*, J. Intell. Manuf. **22** (2011), no. 3, 459–470.



