Optimization and Simulation

Introduction to simulation

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Outline



- 2 Causal effects
- 3 Uncertainty
- Beyond the mean
- 5 Simulation

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Modeling

System

• A system can be seen as a black box, modeled by

$$\mathsf{z}=\mathsf{h}(\mathsf{x},\mathsf{y},\mathsf{u})$$

- Example: a car
- x captures the state of the system (e.g. speed, position of other vehicles)
- y captures external influences (e.g. wind)
- *u* captures possible human controls on the system (e.g. acceleration/deceleration)
- z represents indicators of performance (e.g. oil consumption).

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Modeling

Decompose the complexity

- The model *h* is usually decomposed to reflect the interactions of the subsystems
- For example,
 - a car-following model captures the target speed of the driver,
 - an engine model derives the actual consumption as a function of the acceleration.

Simulation

- Captures the causal effects.
- Captures the uncertainty.

Simulation

Definition

the act of imitating the behavior of some situation or some process by means of something suitably analogous

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Outline



2 Causal effects

3 Uncertainty

Beyond the mean



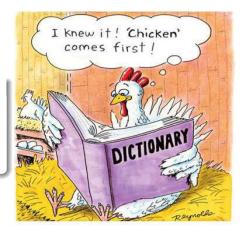
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Modeling

Causal effects

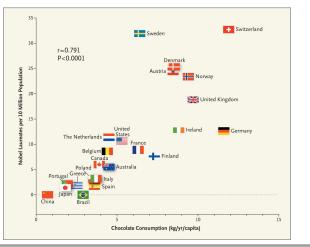
- Very important to identify the causal effects
- Failure to do so may generate wrong conclusions



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Data can be misleading

Chocolate Consumption, Cognitive Function, and Nobel Laureates



Source: [Messerli, 2012]

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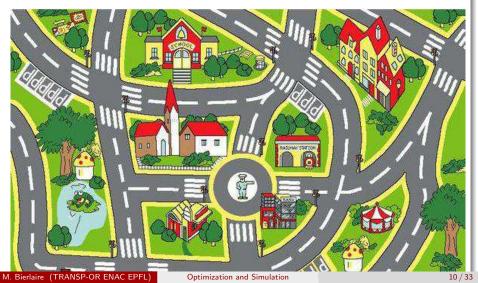
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Optimization and Simulation

Accidents in Kid City

- The mayor of Kid City has commissioned a consulting company
- Objective: assess the effectiveness of safety campaigns
- They propose to use simulation

Accidents in Kid City



Accidents in Kid City:

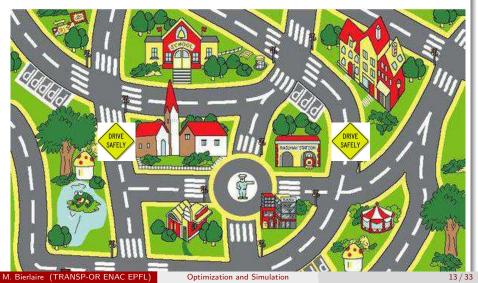


Optimization and Simulation

Accidents in Kid City



Accidents in Kid City



Accidents in Kid City:



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Optimization and Simulation

Two major flaws

- Causal effects are not modeled
- Simulation performed with only one draw

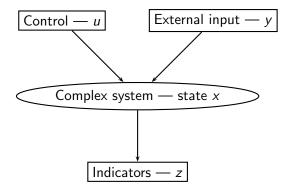
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Simulation: what it is not



Simulation: what it is not

$$z = h(x, y, u)$$

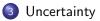


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Outline



2 Causal effects





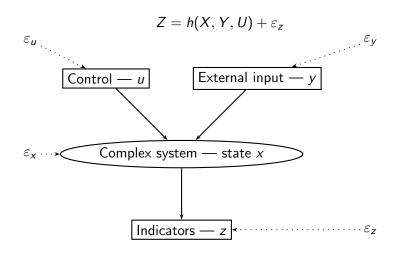
Simulation

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Uncertainty

Simulation



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Simulation

Propagation of uncertainty

$$Z = h(X, Y, U) + \varepsilon_z$$

• Given the distribution of X, Y, U and ε_z

• what is the distribution of Z?

Derivation of indicators

- Mean
- Variance
- Modes
- Quantiles

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Simulation

Sampling

- Draw realizations of X, Y, U, ε_z
- Call them $x^r, y^r, u^r, \varepsilon_z^r$
- For each r, compute

$$z^r = h(x^r, y^r, u^r) + \varepsilon_z^r$$

• z^r are draws from the random variable Z

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Statistics

@ MARK ANDERSON



"Numbers don't lie. That's where we come in."

Indicators

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- Mean: $E[Z] \approx \bar{Z}_R = \frac{1}{R} \sum_{r=1}^R z^r$
- Variance: $\operatorname{Var}(Z) \approx \frac{1}{R} \sum_{r=1}^{R} (z^r \overline{Z}_R)^2$.

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- Modes: based on the histogram
- Quantiles: sort and select

Important: there is more than the mean

Outline



- 2 Causal effects
- 3 Uncertainty
- 4 Beyond the mean

Simulation

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The mean



[Savage et al., 2012]

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The mean

The flaw of averages

[Savage et al., 2012]

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$\mathsf{E}[Z] = \mathsf{E}[h(X, Y, U) + \varepsilon_z] \neq h(\mathsf{E}[X], \mathsf{E}[Y], \mathsf{E}[U]) + \mathsf{E}[\varepsilon_z]$

 \dots except if *h* is linear.

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There is more than the mean



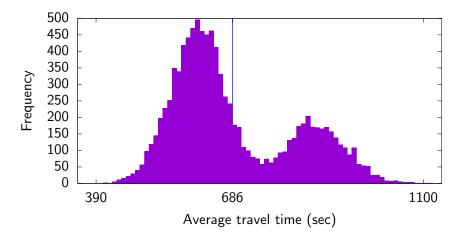
Example

- Intersection with capacity 2000 veh/hour
- Traffic light: 30 sec green / 30 sec red
- Constant arrival rate: 2000 veh/hour during 30 minutes

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- With 30% probability, capacity at 80%.
- Indicator: Average time spent by travelers

There is more than the mean



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Outline



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Pitfalls of simulation

Few number of runs

- Run time is prohibitive
- Tempting to generate partial results rather than no result

Focus on the mean

- The mean is useful, but not sufficient.
- For complex distributions, it may be misleading.
- Intuition from normal distribution (mode = mean, symmetry) do not hold in general.
- Important to investigate the whole distribution.
- Simulation allows to do it easily.

Challenges

- How to generate draws from Z?
- How to represent complex systems? (specification of *h*)
- How large *R* should be?
- How good is the approximation?

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Pseudo-random numbers

Definition

- Deterministic sequence of numbers
- which have the appearance of draws from a U(0,1) distribution

Typical sequence

$$x_n = a x_{n-1} \mod m$$

- This has a period of the order of m
- So, *m* should be a large prime number
- For instance: $m = 2^{31} 1$ and $a = 7^5$
- x_n/m lies in the [0, 1[interval

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Outline of the lectures

- Drawing from distributions
- Discrete event simulation
- Data analysis
- Variance reduction
- Markov Chain Monte Carlo

Reference

[Ross, 2012]

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