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# Introduction to simulation

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# Modeling

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- A system can be seen as a black box, modeled by

$$y = h(x, u)$$

- Example: a car
- $x$  captures the state of the system (e.g. speed, position of other vehicles)
- $u$  captures possible human controls on the system (e.g. acceleration/deceleration)
- $y$  represents indicators of performance (e.g. oil consumption).

# Modeling

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- The model  $f$  is usually decomposed to reflect the interactions of the subsystems
- For example,
  - a car-following model captures the target speed of the driver,
  - an engine model derives the actual consumption as a function of the acceleration.
- In practice, such a model is never representing accurately the reality.

# Modeling

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- Uncertainty is captured by random variables

$$Y = h(X, U, \varepsilon)$$

where  $X$ ,  $U$ ,  $\varepsilon$  and  $Y$  are random variables.

- We are interested in the distribution of  $Y$ .
- When  $f$  is complex (that is, a combination of many models),
  - the distribution of  $Y$  is complex,
  - even if the distributions of  $X$ ,  $U$  and  $\varepsilon$  are simple.

# Modeling

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- Assume for the sake of simplicity that all r.v. are continuous
- Denote  $Z$  the random vector  $(X, U, \varepsilon)$
- Distribution of  $Y$ :

$$f_Y(y) = \int_z f_Y(y|Z = z) f_Z(z) dz.$$

- In general, no analytical formula is available for  $f_Y$
- When the dimension of  $Z$  is large, numerical integration is not an option.
- Solution: Monte-Carlo integration

# Monte-Carlo integration

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Compute

$$I = \int_0^1 f(x) dx$$

If  $\varepsilon \sim U(0, 1)$ , then

$$I = E[f(\varepsilon)]$$

If  $r_1, \dots, r_k$  are  $k$  independent draws from  $\varepsilon$ , then

$$I = \lim_{k \rightarrow \infty} \frac{1}{k} \sum_{i=1}^k f(r_i).$$

Requires only to evaluate  $f$ .

**Monte-Carlo integration**

Intuitive example: estimation of  $\pi$

# Monte-Carlo integration

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$$f_Y(y) = \int_z f_Y(y|Z = z) f_Z(z) dz.$$

- Idea of simulation:
  - Draw  $R$  realizations of  $Z$ :  $z_1, \dots, z_R$ .
  - Approximate:

$$f_Y(y) = \int_z f_Y(y|Z = z) f_Z(z) dz \approx \frac{1}{R} \sum_{r=1}^R 1(h(z_r) = y).$$

# Challenges

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- How to generate draws from  $Z$ ?
- How to represent complex systems? (specification of  $h$ )
- How large  $R$  should be?
- How good is the approximation of the integral?



# Pseudo-random numbers

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- Deterministic sequence of numbers
- which have the appearance of draws from a  $U(0, 1)$  distribution

Typical sequence:

$$x_n = ax_{n-1} \text{ modulo } m$$

- This has a period of the order of  $m$
- So,  $m$  should be a large prime number
- For instance:  $m = 2^{31} - 1$  and  $a = 7^5$
- $x_n/m$  lies in the  $[0, 1[$  interval

# Outline

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- Drawing from distributions
- Discrete event simulation
- Data analysis
- Variance reduction
- Markov Chain Monte Carlo