

# Conception, development, installation and evaluation of a real time evacuation assistant for complex buildings

Workshop on Pedestrian Models  
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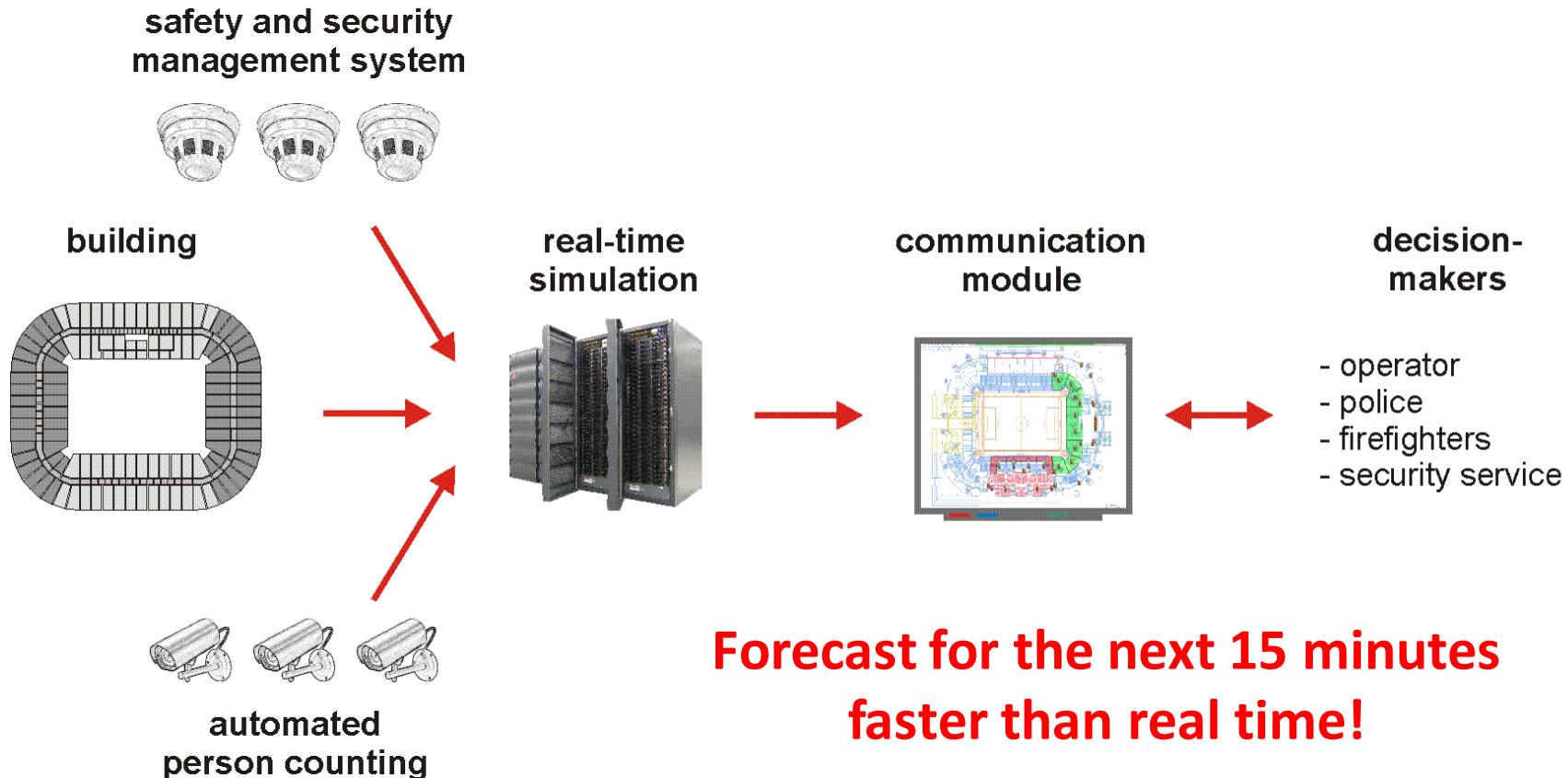
# Overview

- Motivation and framework
- Design and installation
- Modelling
- Evaluation / Validation
- Outlook

## Motivation and framework

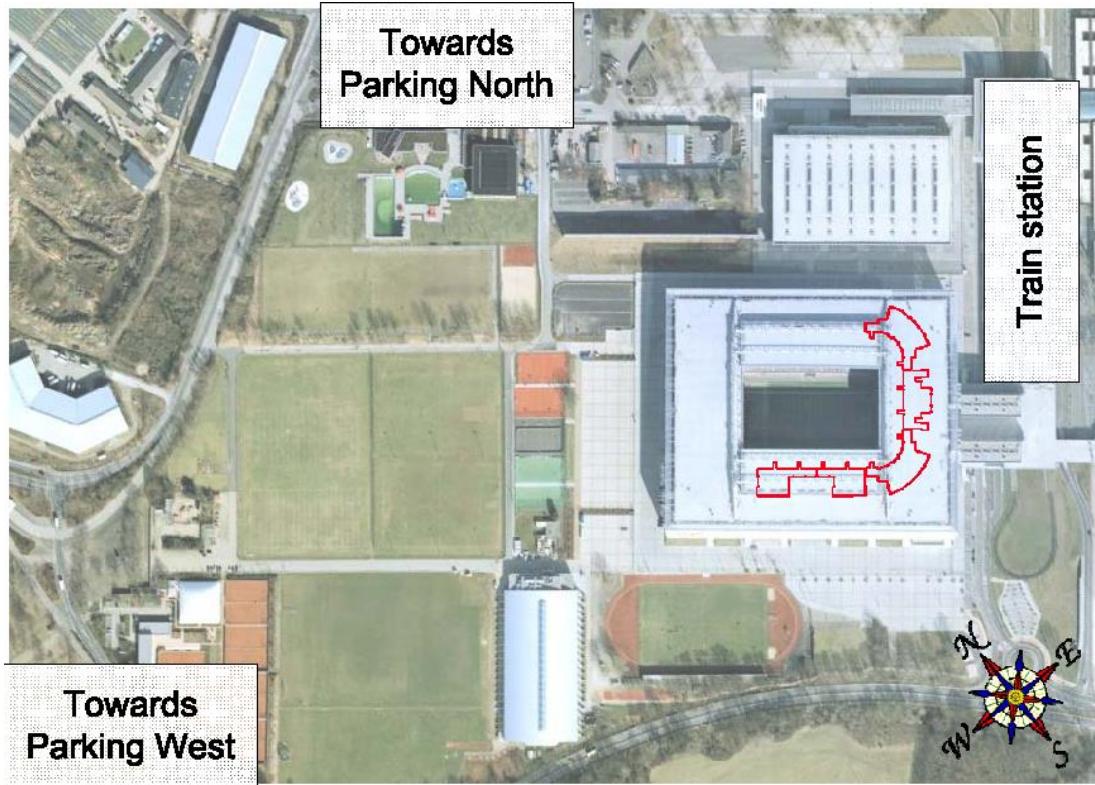
- Improving safety at mass events
  - Monitoring of pedestrian streams
  - Forecast of congestions
- Collection of empirical data
- Information management in crisis
  - Integration of different data sources
  - Dissemination of information

# Concept of the evacuation assistant



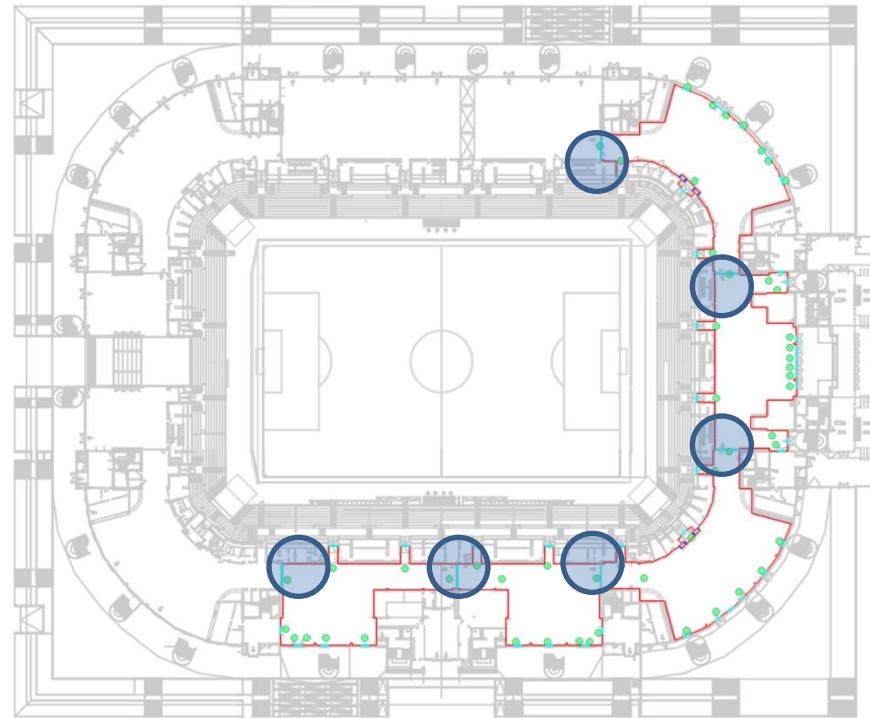
# Location

Multifunction arena in Düsseldorf, Germany with a total capacity of ~60000 seats

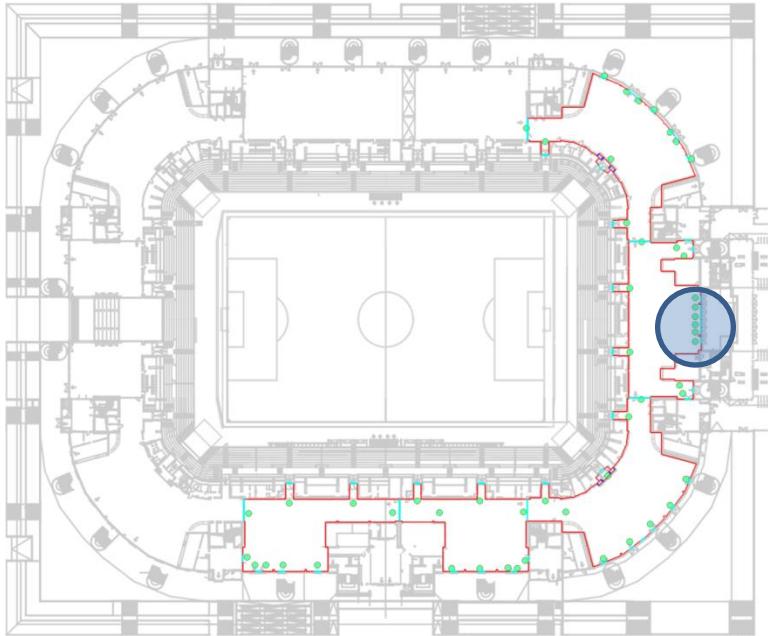


# Automatic person counting system

- Mono/Stereo cameras installed by Vitracom AG
- Observation area divided in 15 sections
- Each camera monitors a counting line (exit)
- The passing direction is taken in to account
  - Backward/forward
- Number of person passing each counting line in a specified direction in one minute granularity
- Pedestrians' trajectories not considered

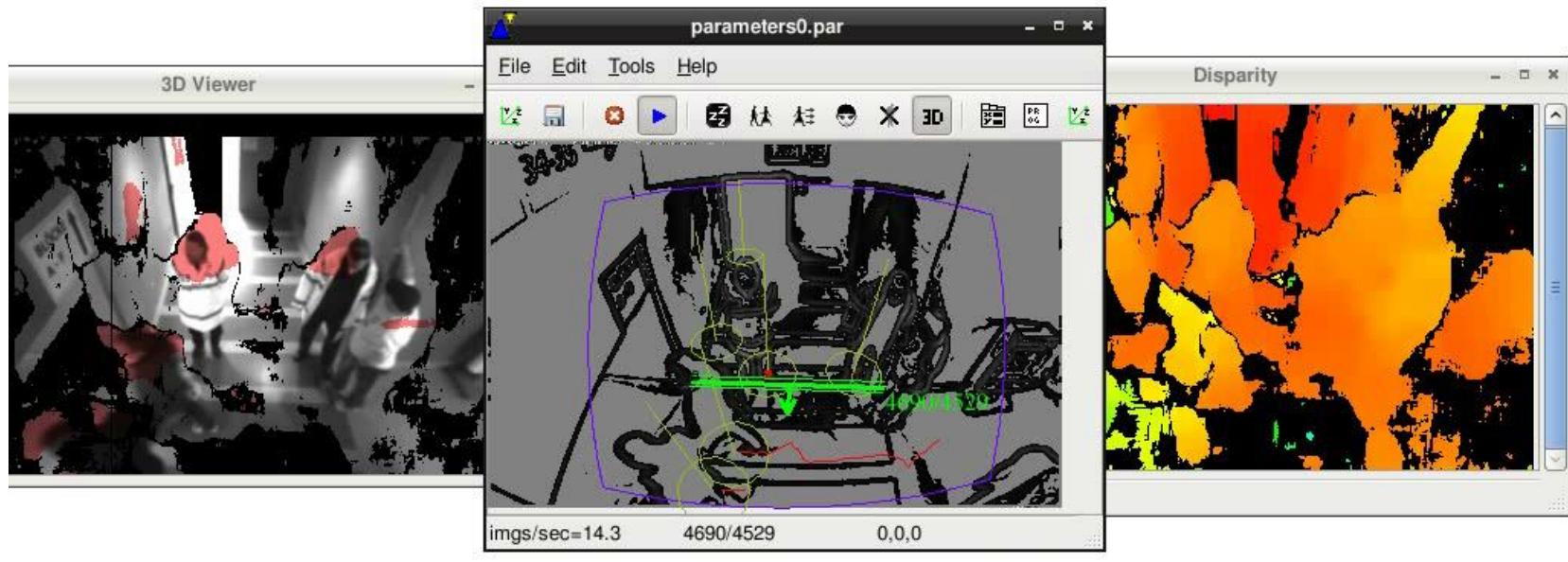


# Automatic person counting system



\*Courtesy Vitracom AG

# Data processing

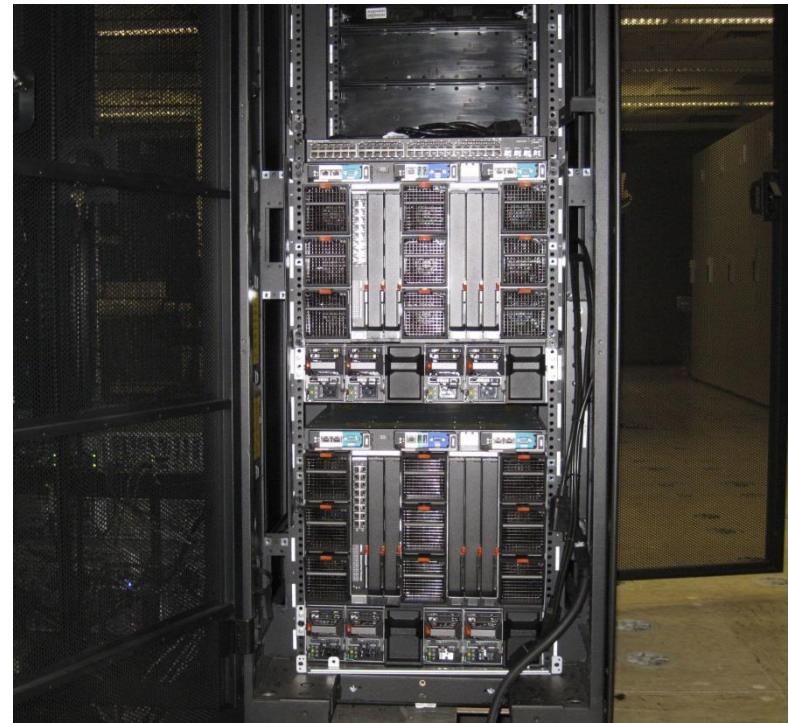


Only the number of pedestrians passing the counting line is given out

\*Courtesy Vitracom AG

# Simulation cluster

- Cluster for real time simulation and processing of the data
- 312 cores



# Communication module



# Modelling

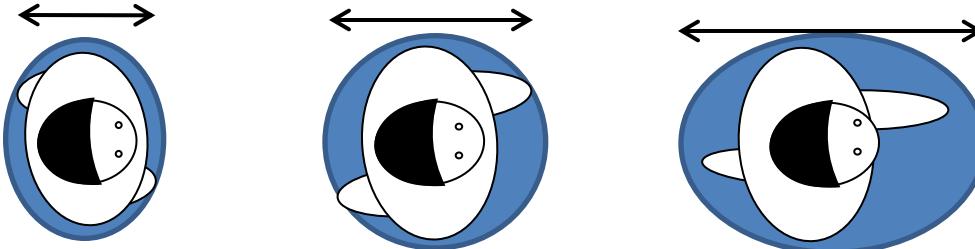
# Generalized Centrifugal Force Model

- Equation of motion

$$m_i \ddot{\vec{R}_i} = \vec{F}_i = \vec{F}_i^{\text{drv}} + \sum_{j \in \mathcal{N}_i} \vec{F}_{ij}^{\text{rep}} + \sum_{w \in \mathcal{W}_i} \vec{F}_{iw}^{\text{rep}}$$

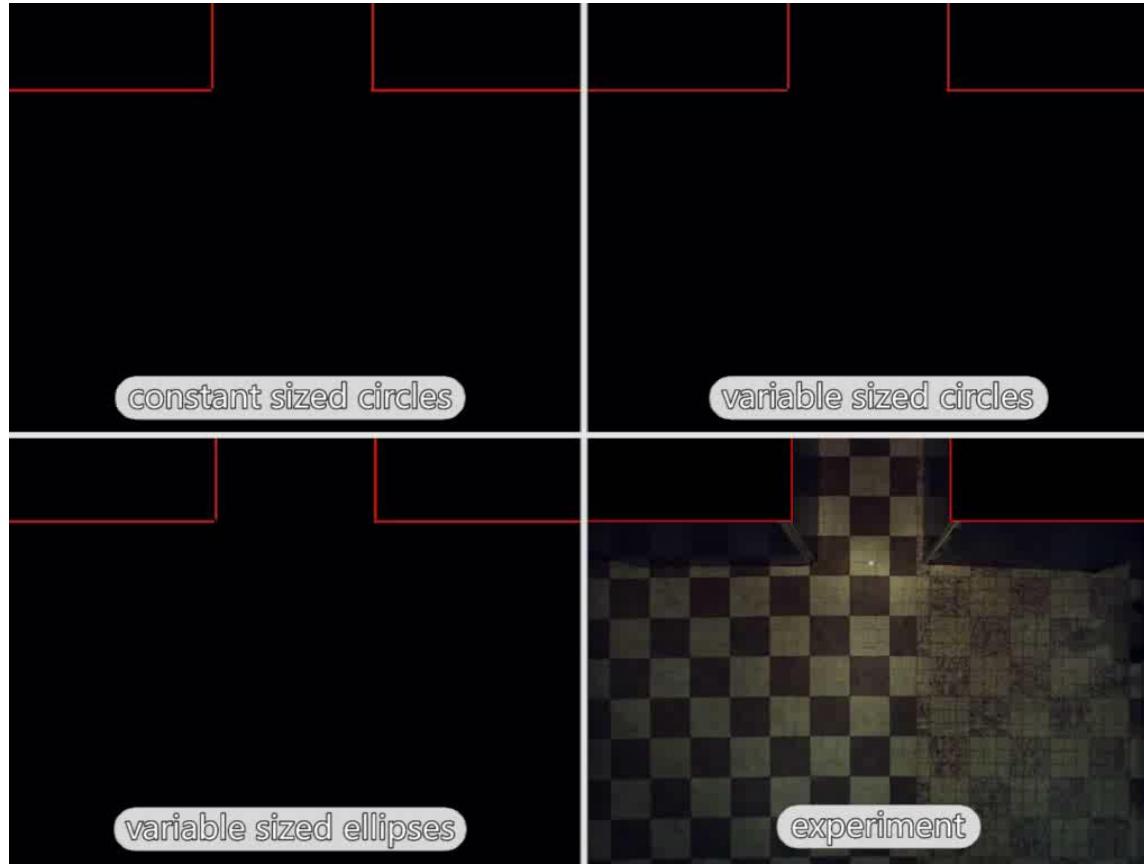
- Velocity dependent space requirement

$$d(v) = a + b \cdot v$$

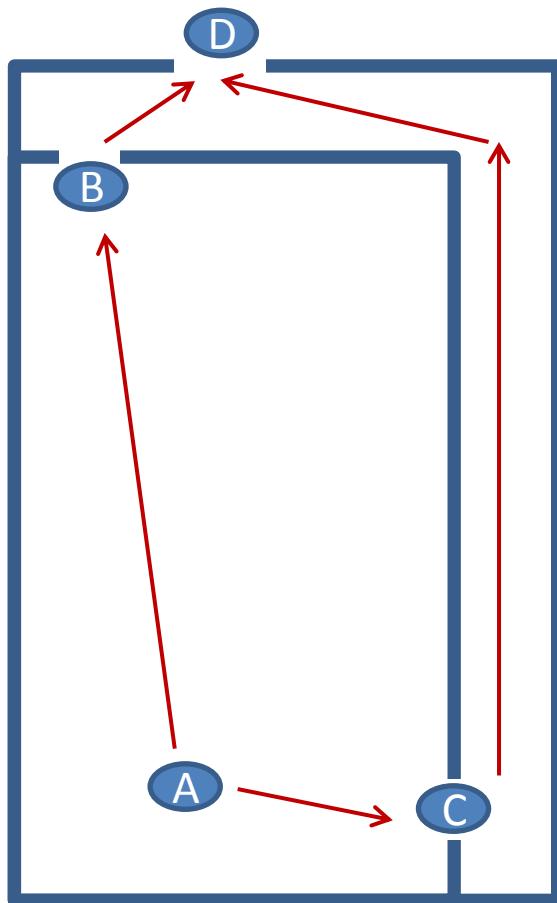


"Generalized centrifugal force model for pedestrian dynamics", Chraibi et al, Physical Review E 82, 046111 (2010)

# Simulation with specific target (the exit)



# Route choice



# Quickest path based on visibility

- Travel time

$$t(\vec{x}_i, \vec{n}_j) = \begin{cases} \frac{\|\vec{x}_i - \vec{x}_j\|}{\|\vec{v}_i\|} + \frac{\|\vec{x}_j - \vec{n}_j\|}{\|\vec{v}_{ja}\|}, & \text{if a reference } \vec{x}_j \text{ was found} \\ \frac{\|\vec{x}_i - \vec{n}_j\|}{\|\vec{v}_i\|}, & \text{if } \vec{n}_j \text{ is free} \end{cases}$$

$\vec{v}_{ja}$  is the average velocity of the reference over the observation time

The change is taken if the  $cba$  is greater than a given threshold

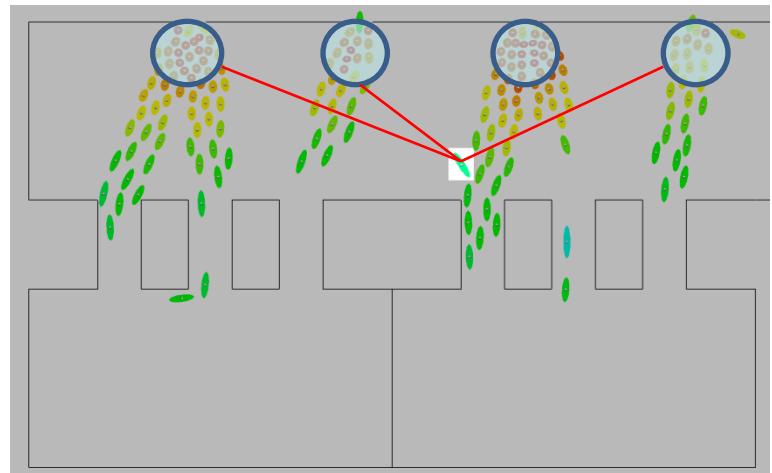
- Gain

$$g(\vec{x}_i, \vec{n}_j) = \frac{1}{t(\vec{x}_i, \vec{n}_j)}$$

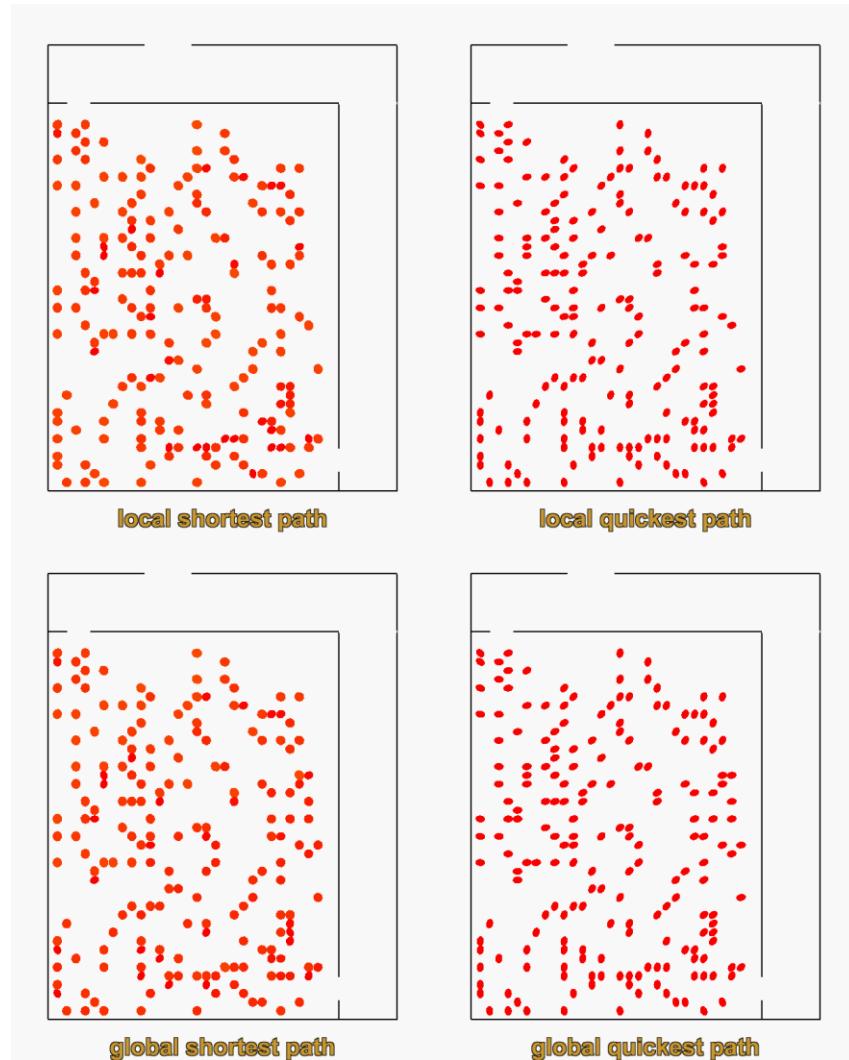
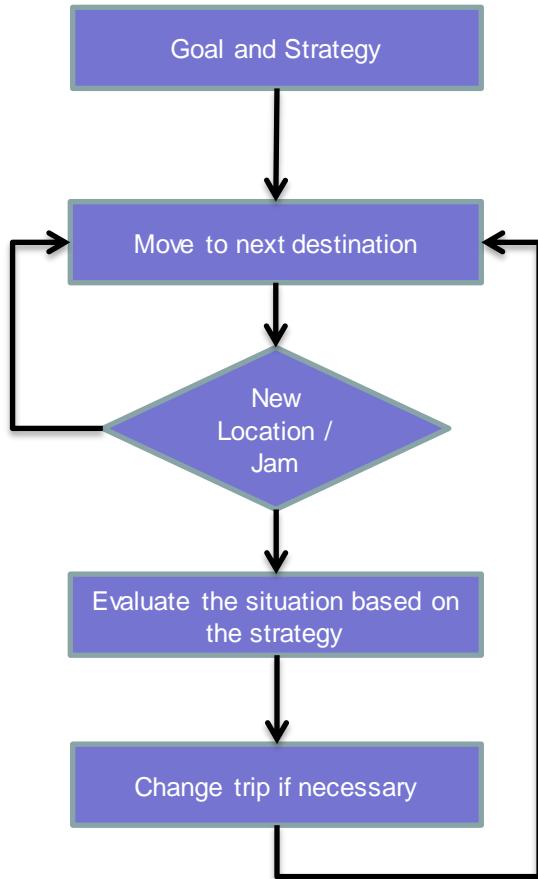
$g_1$  is the actual choice

- Cost benefit analysis

$$cba(g_1, g_2) = \frac{g_1 - g_2}{g_1 + g_2}$$

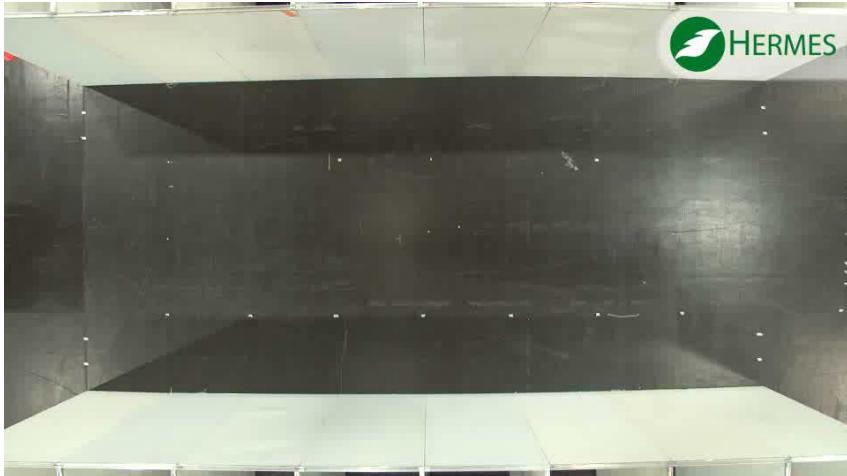


# Business logic

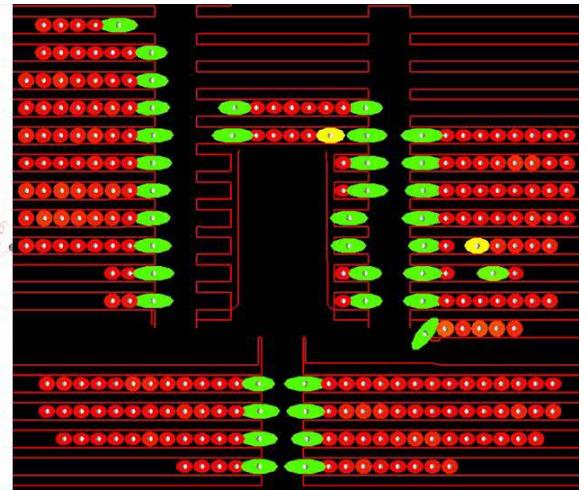
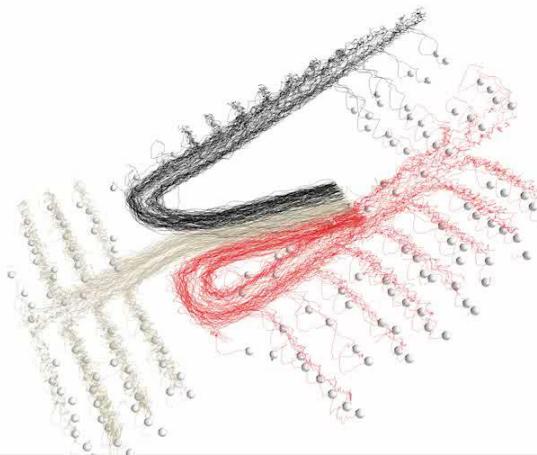


# Validation

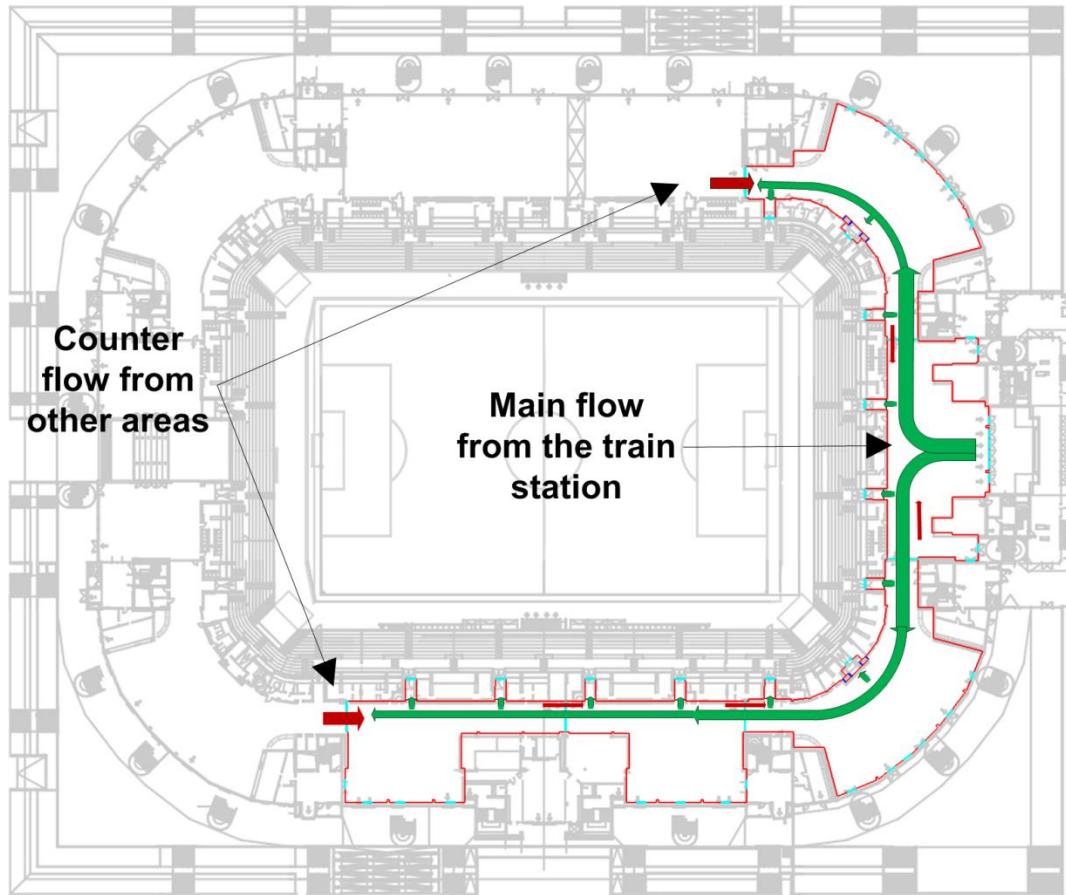
# Experiments



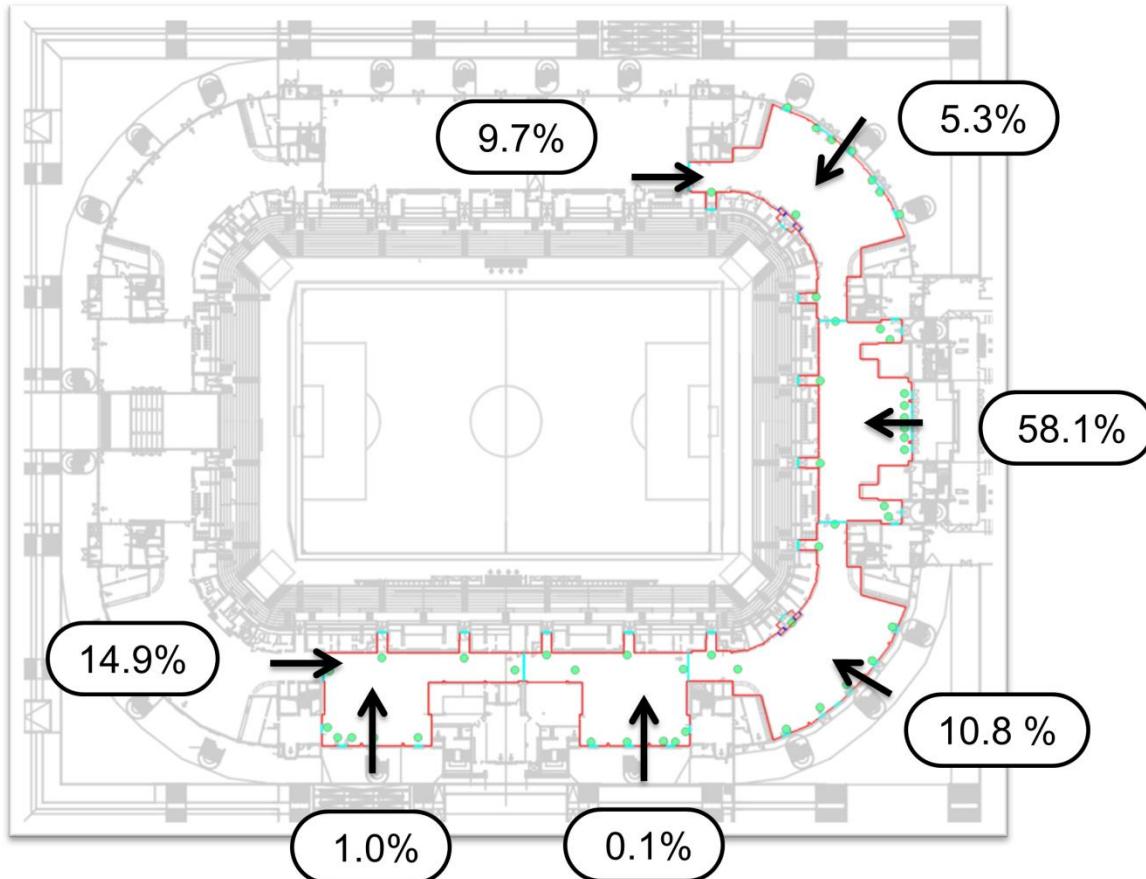
# Analysis and simulation



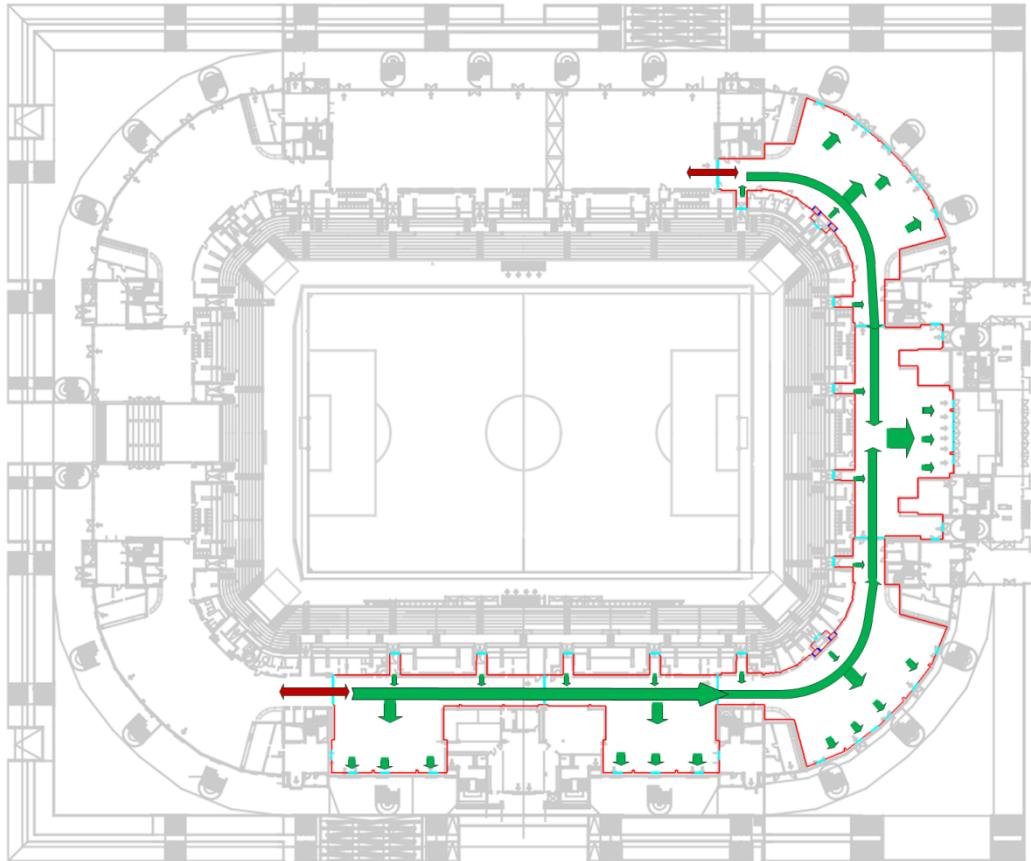
## Route choice: beginning of the event



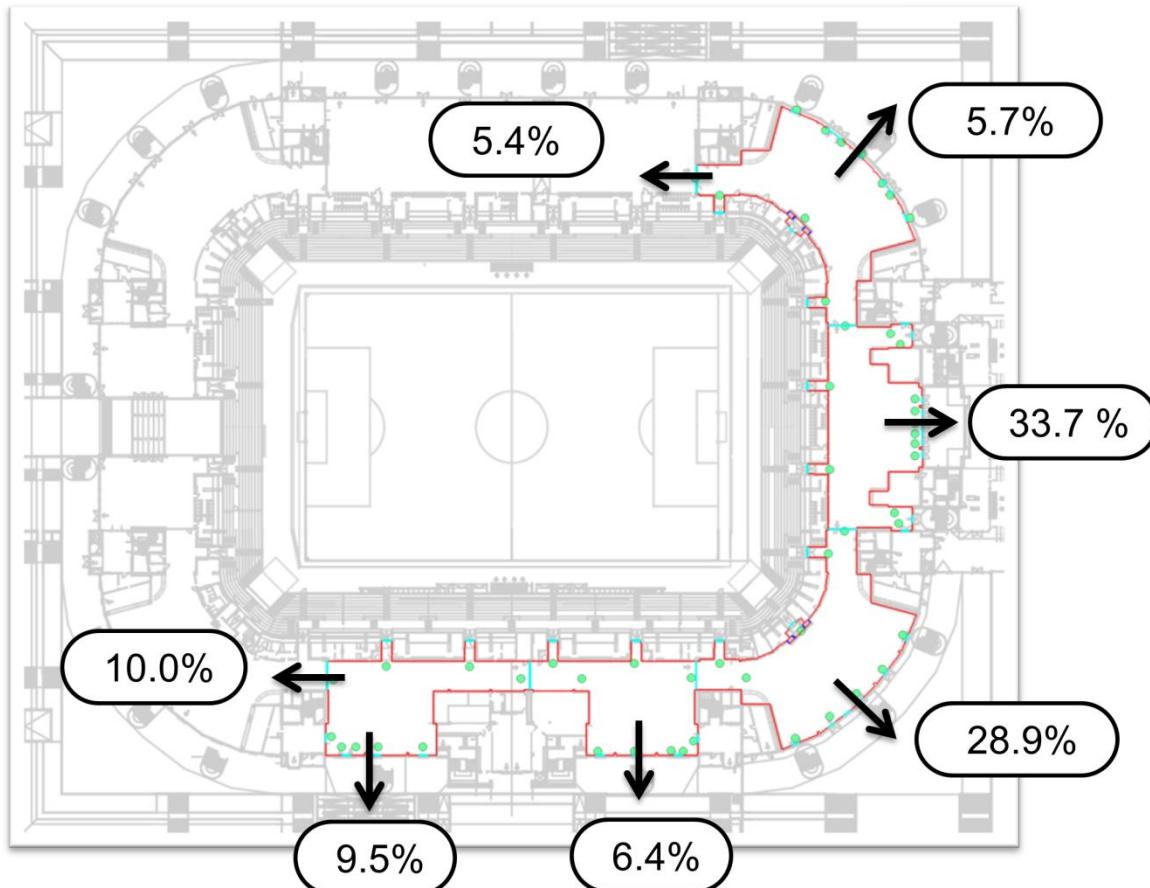
## Route choice: beginning of the event



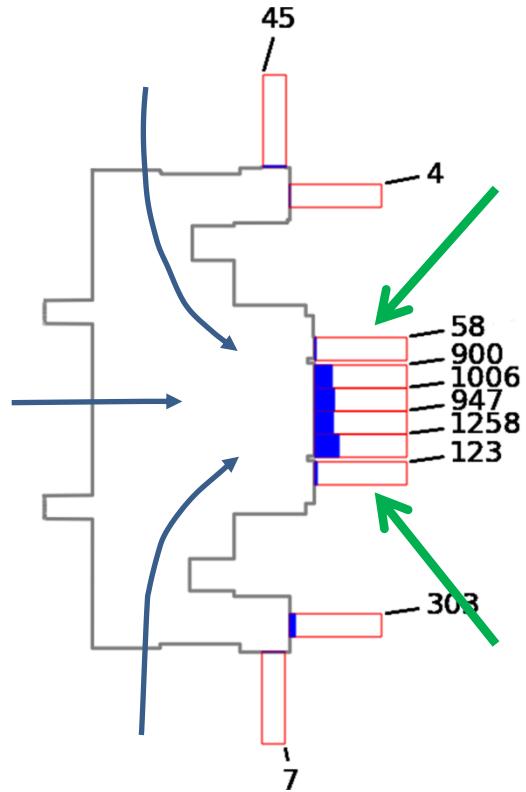
## Route choice: end of the event



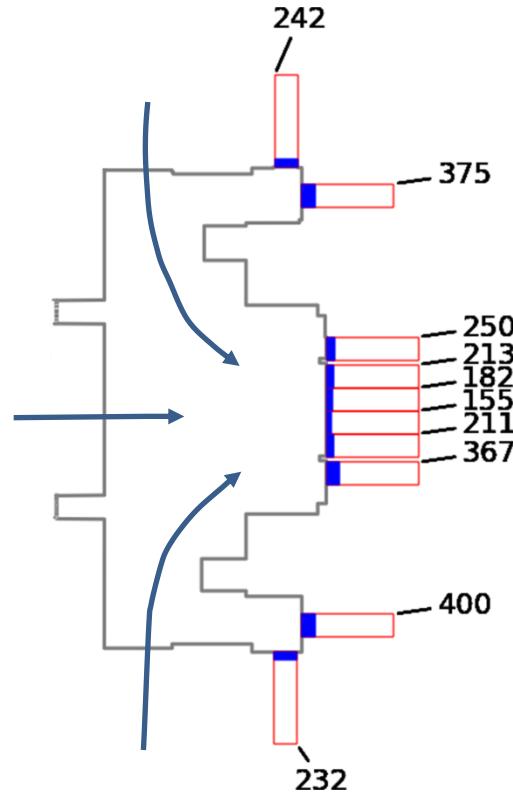
## Route choice: end of the event



# Individual exit selection

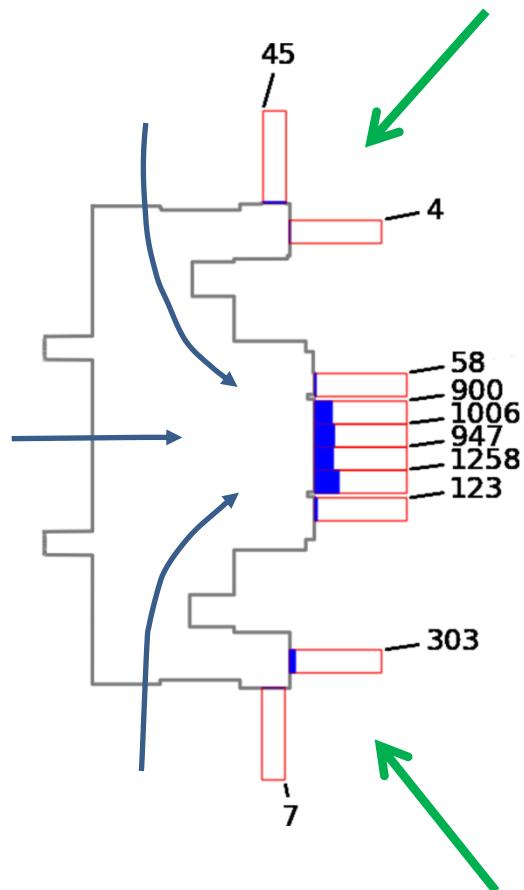


Observation

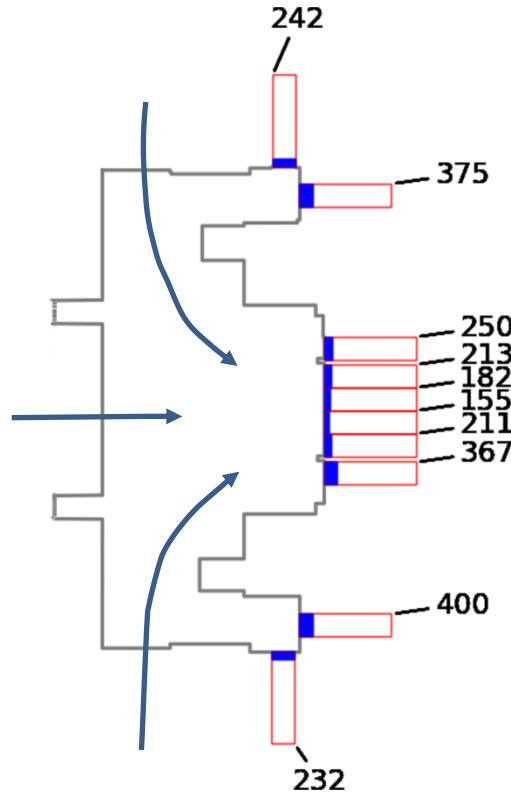


Simulation  
(evacuation)

## Not perceived doors ?



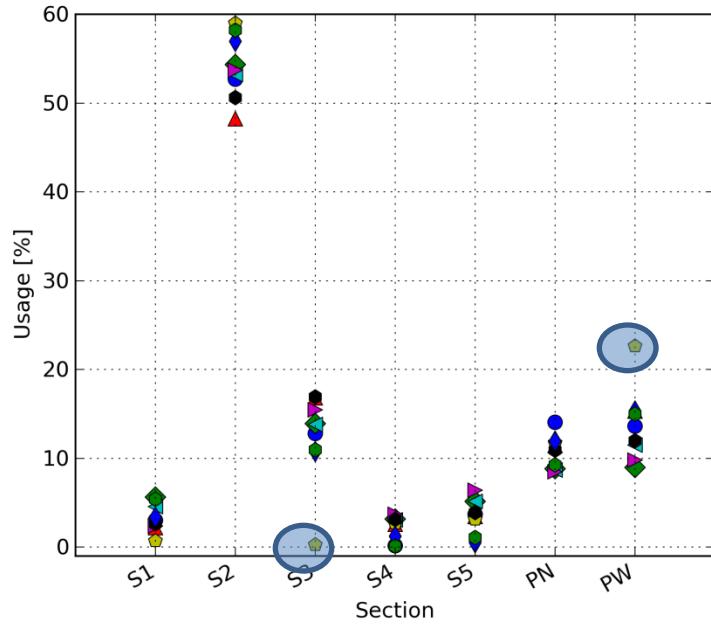
**Observation**



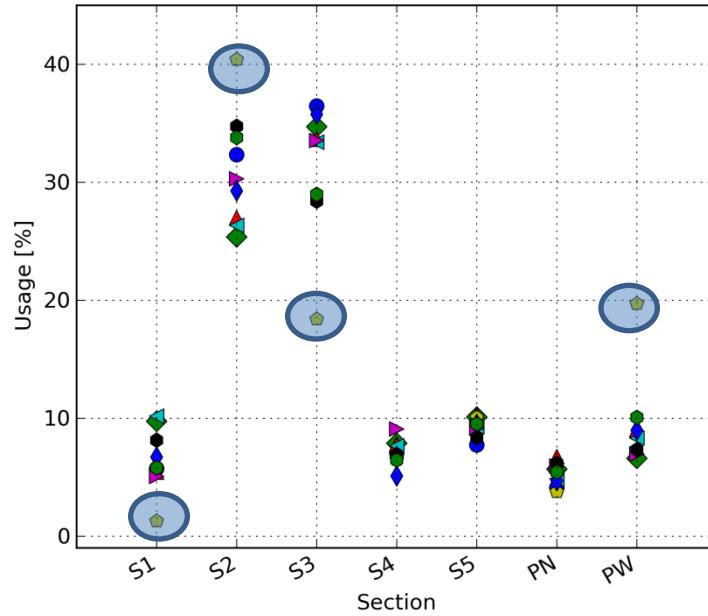
**Simulation  
(evacuation)**

# Comparison across different games

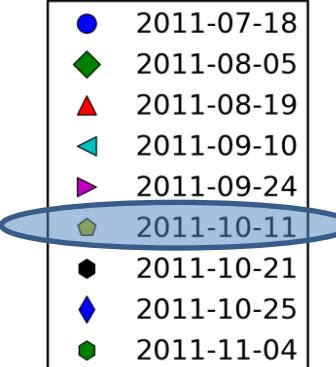
Arrival



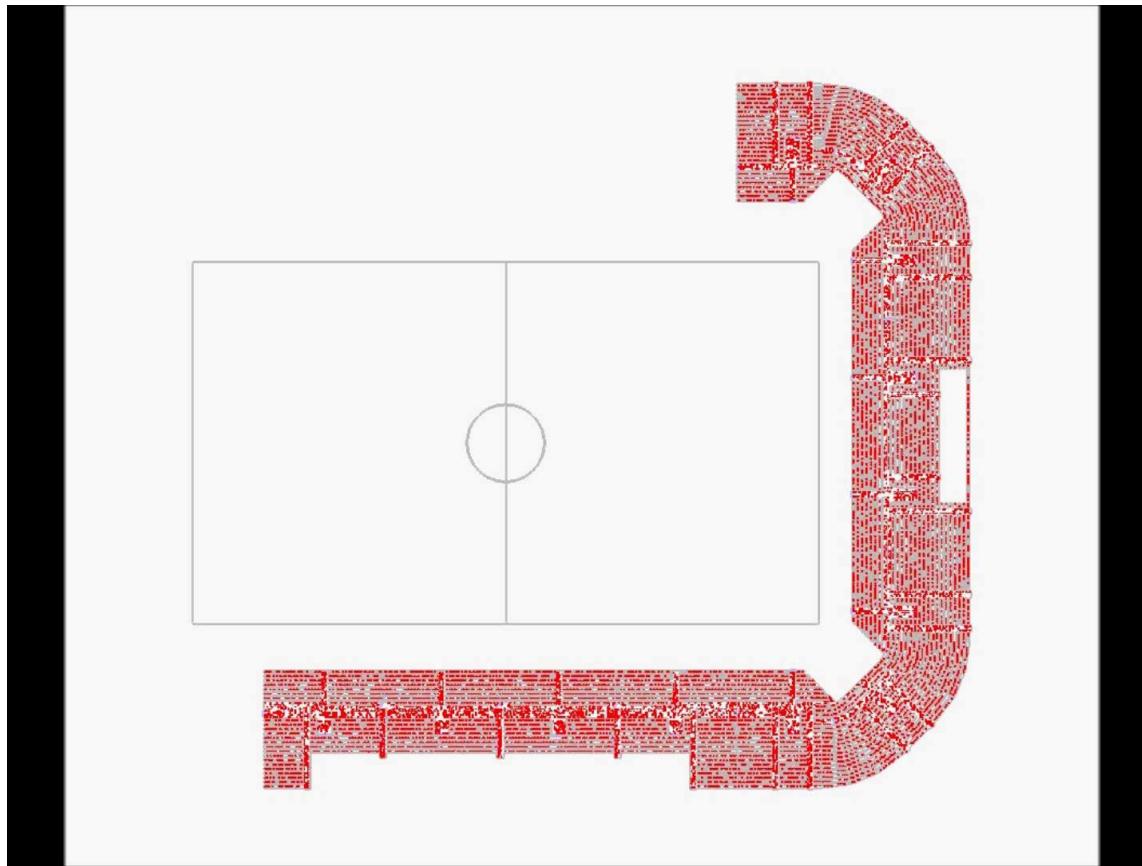
Departure



- Local game
  - Similar behaviour for the same group (supporters of the local team)
- National game
  - Different behaviour (heterogeneity of supporters)



# Simulation



## Summary and outlook

- Evacuation assistant for large events with emphasis on validation
- Designed for evacuation and tested on routine clearing where the behavior, especially the route choice pattern is different
- The interpretation of the results is always specific to the context (evacuation type, game type, audience, ...)
- Extension of the existing models, for instance with perception