



Random Sampling of Alternatives for Route Choice Modeling

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Outline

- Introduction
- Stochastic path enumeration approach
- Sampling of alternatives
- Numerical results
- Conclusions

Introduction

- Route choice problem

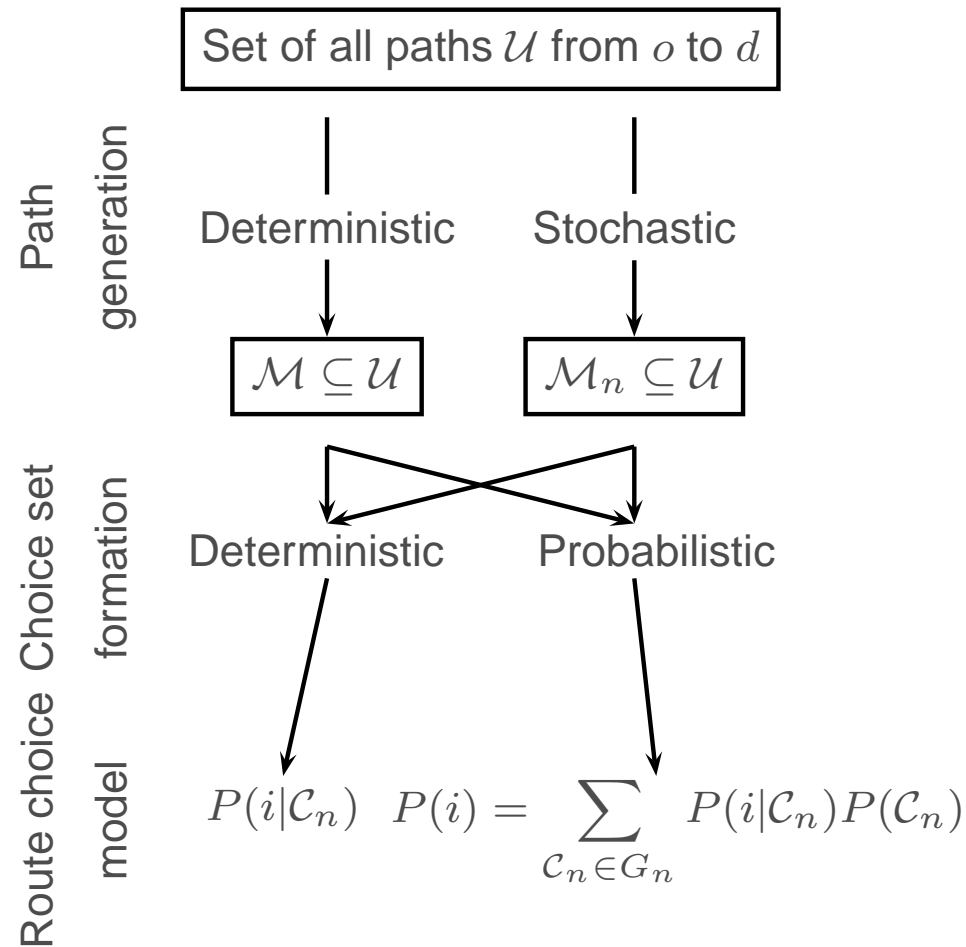
*Given a transportation **network** composed of nodes, links, origin and destinations. For a given transportation mode and **origin-destination pair**, which is the chosen **route**?*

- Discrete choice modeling framework

- Issue

Universal choice set very large, individual specific choice set unknown

Introduction



Introduction

- Underlying assumption in existing approaches: the actual choice set is generated
- Empirical results suggest that this is not always true
- Our approach:
 - True choice set = universal set \mathcal{U}
 - Too large
 - Sampling of alternatives

Sampling of Alternatives

- Multinomial logit model (e.g. Ben-Akiva and Lerman, 1985):

$$P(i|\mathcal{C}_n) = \frac{q(\mathcal{C}_n|i)P(i)}{\sum_{j \in \mathcal{C}_n} q(\mathcal{C}_n|j)P(j)} = \frac{e^{V_{in} + \ln q(\mathcal{C}_n|i)}}{\sum_{j \in \mathcal{C}_n} e^{V_{jn} + \ln q(\mathcal{C}_n|j)}}$$

\mathcal{C}_n : set of sampled alternatives

$q(\mathcal{C}_n|j)$: probability of sampling \mathcal{C}_n given that j is the chosen alternative

Importance Sampling of Alternatives

- Attractive paths have higher probability of being sampled than unattractive paths
- Path utilities must be corrected in order to obtain unbiased estimation results

MNL Route Choice Models

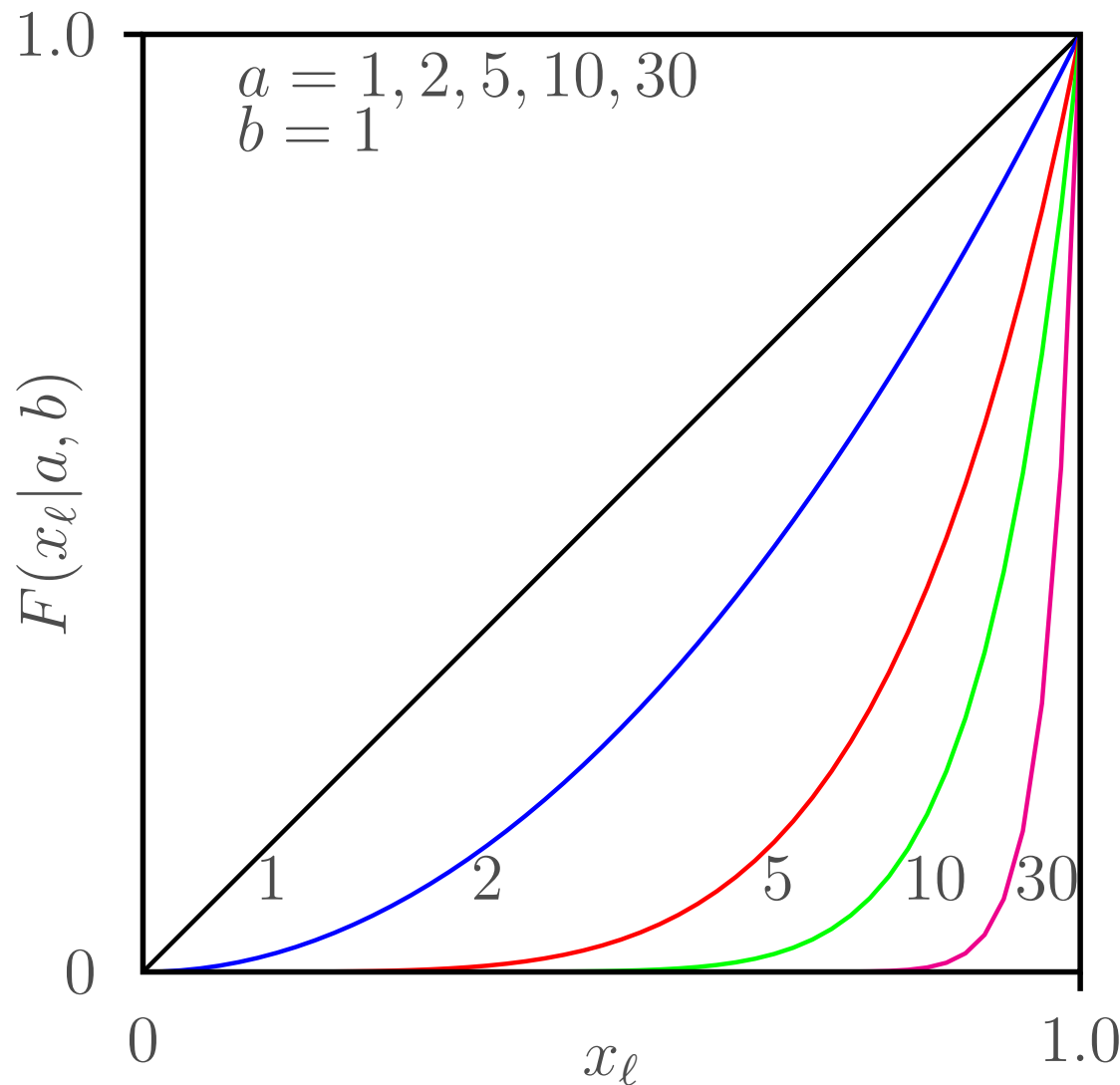
- Path Size Logit (Ben-Akiva and Ramming, 1998 and Ben-Akiva and Bierlaire, 1999) and C-Logit (Caschetta et al. 1996)
- Additional attribute in the deterministic utilities capturing correlation among alternatives
- These attributes should reflect the true correlation structure
- Hypothesis: attributes should be computed based on all paths (or as many as possible)

Stochastic Path Enumeration

- Flexible approach that can be combined with various algorithms, here a biased random walk approach
- The probability of a link ℓ with source node v and sink node w is modeled in a stochastic way based on its distance to the shortest path
- Kumaraswamy distribution, cumulative distribution function $F(x_\ell|a, b) = 1 - (1 - x_\ell^a)^b$ for $x_\ell \in [0, 1]$.

$$x_\ell = \frac{SP(v, d)}{C(\ell) + SP(w, d)}$$

Stochastic Path Enumeration



Stochastic Path Enumeration

- Probability for path j to be sampled

$$q(j) = \prod_{\ell=(v,w) \in \Gamma_j} q((v,w) | \mathcal{E}_v)$$

- Γ_j : ordered set of all links in j
- v : source node of j
- \mathcal{E}_v : set of all outgoing links from v
- In theory, the set of all paths \mathcal{U} may be unbounded. We treat it as bounded with size J .

Sampling of Alternatives

- Following Ben-Akiva (1993)
- Sampling protocol
 1. A set $\tilde{\mathcal{C}}_n$ is generated by drawing R paths with replacement from the universal set of paths \mathcal{U}
 2. Add chosen path to $\tilde{\mathcal{C}}_n$
- Outcome of sampling: $(\tilde{k}_1, \tilde{k}_2, \dots, \tilde{k}_J)$ and $\sum_{j=1}^J \tilde{k}_j = R$

$$P(\tilde{k}_1, \tilde{k}_2, \dots, \tilde{k}_J) = \frac{R!}{\prod_{j \in \mathcal{U}} \tilde{k}_j!} \prod_{j \in \mathcal{U}} q(j)^{\tilde{k}_j}$$

- Alternative j appears $k_j = \tilde{k}_j + \delta_{cj}$ in $\tilde{\mathcal{C}}_n$

Sampling of Alternatives

- Let $\mathcal{C}_n = \{j \in \mathcal{U} \mid k_j > 0\}$

$$q(\mathcal{C}_n|i) = q(\tilde{\mathcal{C}}_n|i) = \frac{R!}{(k_i - 1)! \prod_{\substack{j \in \mathcal{C}_n \\ j \neq i}} k_j!} q(i)^{k_i-1} \prod_{\substack{j \in \mathcal{C}_n \\ j \neq i}} q(j)^{k_j} = K_{\mathcal{C}_n} \frac{k_i}{q(i)}$$

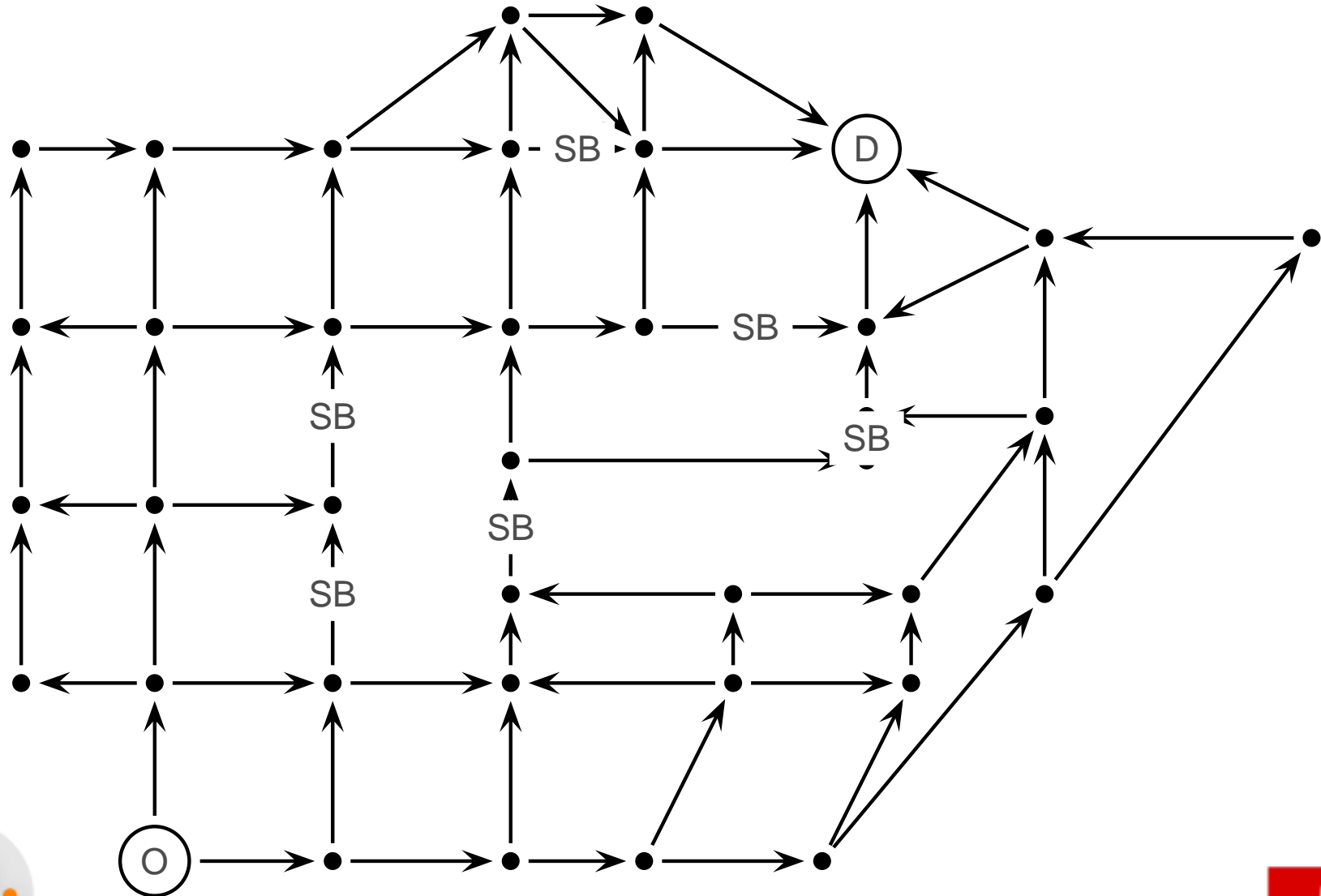
$$K_{\mathcal{C}_n} = \frac{R!}{\prod_{j \in \mathcal{C}_n} k_j!} \prod_{j \in \mathcal{C}_n} q(j)^{k_j}$$

$$P(i|\mathcal{C}_n) = \frac{e^{V_{in} + \ln\left(\frac{k_i}{q(i)}\right)}}{\sum_{j \in \mathcal{C}_n} e^{V_{jn} + \ln\left(\frac{k_j}{q(j)}\right)}}$$

Numerical Results

- Estimation of models based on synthetic data generated with a postulated model
- Evaluation of
 - Sampling correction
 - Path Size attribute
 - Biased random walk algorithm parameters

Numerical Results



Numerical Results

- True model: Path Size Logit

$$U_j = \beta_{PS} PS_j^{\mathcal{U}} + \beta_L \text{Length}_j + \beta_{SB} \text{SpeedBumps}_j + \varepsilon_j$$

$$\beta_{PS} = 1, \beta_L = -0.3, \beta_{SB} = -0.1$$

ε_j distributed Extreme Value with scale 1 and location 0

$$PS_j^{\mathcal{U}} = \sum_{\ell \in \Gamma_j} \frac{L_\ell}{L_j} \frac{1}{\sum_{p \in \mathcal{U}} \delta_{\ell p}}$$

- 3000 observations

Numerical Results

- Four model specifications

		Sampling Correction	
		Without	With
Path	\mathcal{C}	$M_{PS(\mathcal{C})}^{\text{NoCorr}}$	$M_{PS(\mathcal{C})}^{\text{Corr}}$
Size	\mathcal{U}	$M_{PS(\mathcal{U})}^{\text{NoCorr}}$	$M_{PS(\mathcal{U})}^{\text{Corr}}$

$$PS_i^{\mathcal{U}} = \sum_{\ell \in \Gamma_i} \frac{L_\ell}{L_i} \frac{1}{\sum_{j \in \mathcal{U}} \delta_{\ell j}}$$

$$PS_{in}^{\mathcal{C}} = \sum_{\ell \in \Gamma_i} \frac{L_\ell}{L_i} \frac{1}{\sum_{j \in \mathcal{C}_n} \delta_{\ell j}}$$

Numerical Results

- Model $M_{PS(\mathcal{C})}^{\text{NoCorr}}$:

$$V_{in} = \mu \left(\beta_{PS} PS_{in}^{\mathcal{C}} - 0.3 \text{Length}_i + \beta_{SB} \text{SpeedBumps}_i \right)$$

- Model $M_{PS(\mathcal{C})}^{\text{Corr}}$:

$$V_{in} = \mu \left(\beta_{PS} PS_{in}^{\mathcal{C}} - 0.3 \text{Length}_i + \beta_{SB} \text{SpeedBumps}_i + \ln\left(\frac{k_i}{q(i)}\right) \right)$$

- Model $M_{PS(\mathcal{U})}^{\text{NoCorr}}$:

$$V_{in} = \mu \left(\beta_{PS} PS_{in}^{\mathcal{U}} - 0.3 \text{Length}_i + \beta_{SB} \text{SpeedBumps}_i \right)$$

- Model $M_{PS(\mathcal{U})}^{\text{Corr}}$:

$$V_{in} = \mu \left(\beta_{PS} PS_{in}^{\mathcal{U}} - 0.3 \text{Length}_i + \beta_{SB} \text{SpeedBumps}_i + \ln\left(\frac{k_i}{q(i)}\right) \right)$$

Numerical Results

	True PSL	$M_{PS(c)}^{\text{NoCorr}}$ PSL	$M_{PS(c)}^{\text{Corr}}$ PSL	$M_{PS(u)}^{\text{NoCorr}}$ PSL	$M_{PS(u)}^{\text{Corr}}$ PSL
$\hat{\beta}_L$ fixed	-0.3	-0.3	-0.3	-0.3	-0.3
$\hat{\mu}$	1	0.182	0.724	0.141	0.994
Standard error		0.0277	0.0226	0.0263	0.0286
t-test w.r.t. 1		-29.54	-12.21	-32.64	-0.2
$\hat{\beta}_{PS}$	1	1.94	0.411	-1.02	1.04
Standard error		0.428	0.104	0.383	0.0474
t-test w.r.t. 1		2.20	-5.66	-5.27	0.84
$\hat{\beta}_{SB}$	-0.1	-1.91	-0.226	-2.82	-0.0867
Standard error		0.25	0.0355	-6.58	0.0238
t-test w.r.t. -0.1		-7.24	-3.55	0.41	0.56

Numerical Results

	True PSL	$M_{PS(c)}^{\text{NoCorr}}$ PSL	$M_{PS(c)}^{\text{Corr}}$ PSL	$M_{PS(u)}^{\text{NoCorr}}$ PSL	$M_{PS(u)}^{\text{Corr}}$ PSL
Final Log-likelihood		-6660.45	-6082.53	-6666.82	-5933.98
Adj. Rho-square		0.018	0.103	0.017	0.125

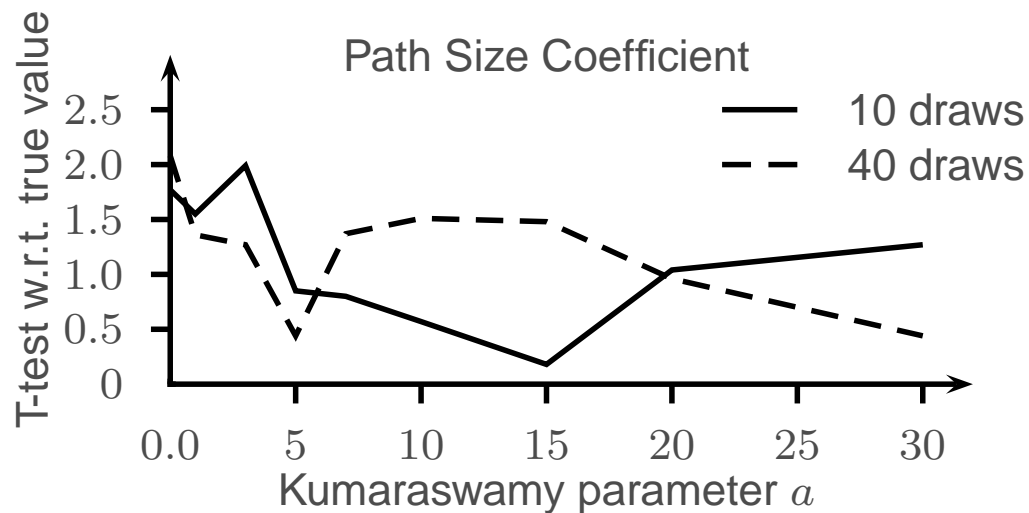
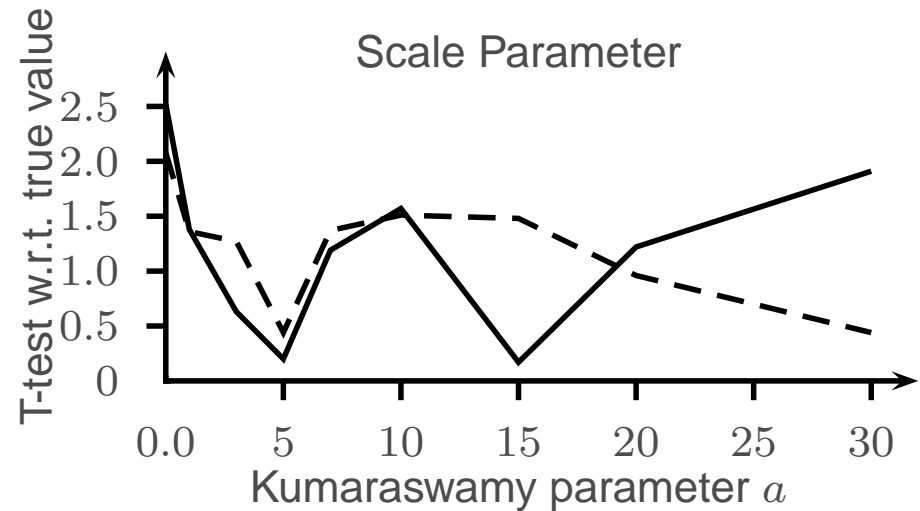
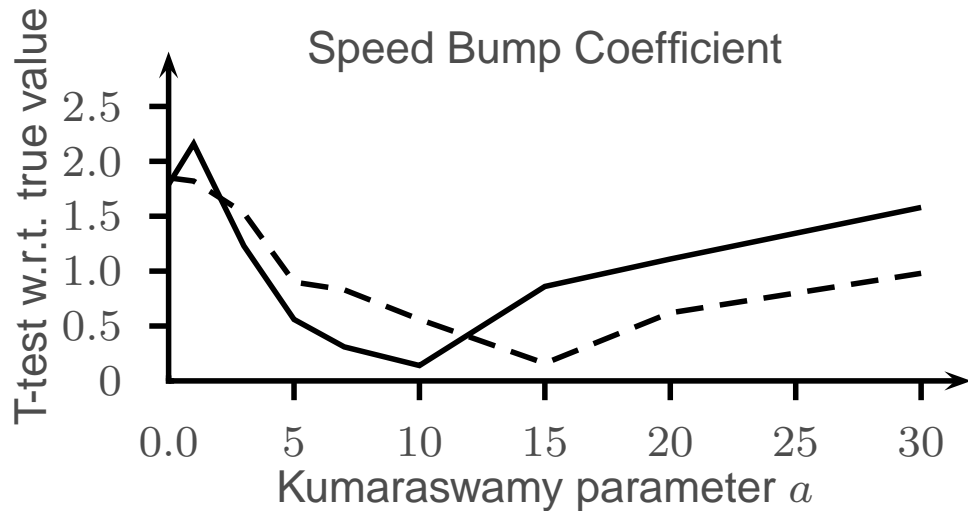
Null Log-likelihood: -6784.96, 3000 observations

Algorithm parameters: 10 draws, $a = 5$, $b = 1$, $C(\ell) = L_\ell$

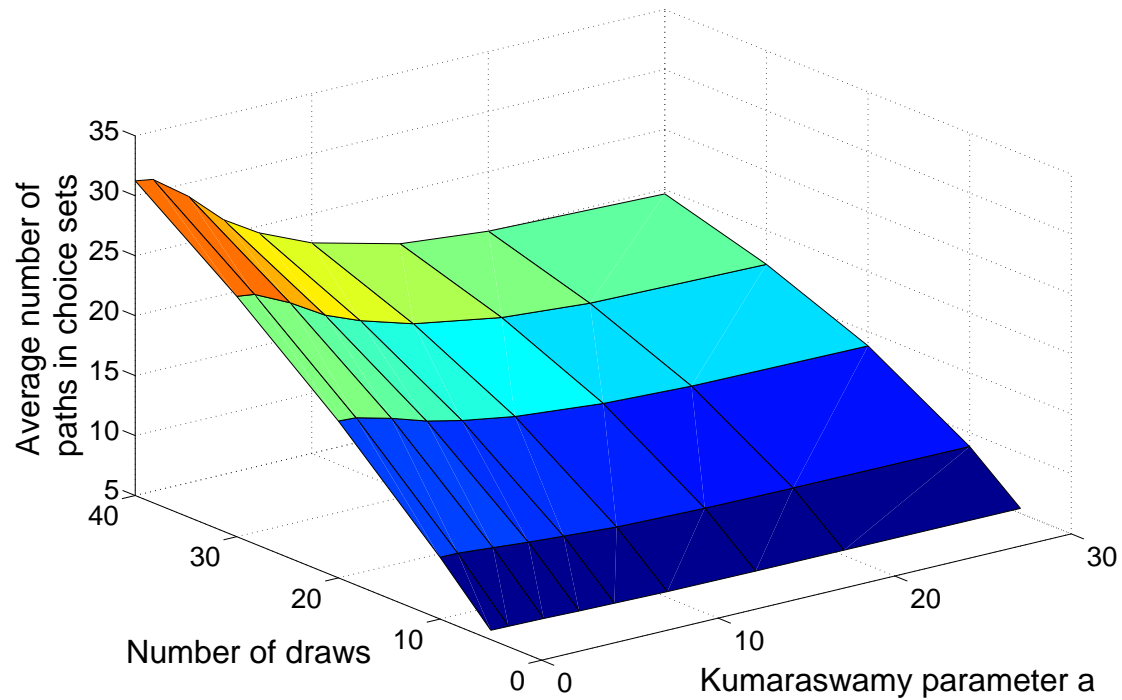
Average size of sampled choice sets: 9.66

BIOGEME (Bierlaire, 2007 and Bierlaire, 2003) has been used for all model estimations

Numerical Results



Numerical Results



Conclusions

- New point of view on choice set generation and route choice modeling
- Path generation is considered an importance sampling approach
- We present a path generation algorithm and derive the corresponding sampling correction
- Path Size should be computed based on true correlation structure
- Numerical results are very promising