

# Gating as a management strategy for controlling pedestrian flows

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# Outline

- 1 Introduction
- 2 Proposed management strategies
  - Gating
  - Flow separators
- 3 Results
  - Gating results
  - Flow separators results
- 4 Conclusion & next steps



# Introduction



# Context

Pedestrians suffer from congestion just as vehicles do:

- increased travel time,
- excessive density.

Which in turn can make you:

- be late for your job interview,
- despise traveling in public,
- miss you **connecting train** or plane,
- ...

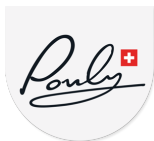
# Context

Higher capacity & faster PT services, to serve higher demand.



# Context

Some of the services available at the Lausanne (CH) train station...





# Motivation

- Lack of comfort, hazardous situations
- How to ensure a satisfactory level-of-service & safety?
  - Decrease pedestrian demand (counter productive !)
  - Spread the load over time & space
  - Influence pedestrian's routes
  - ...
- Simulation is needed to address the complexity of the problem

**Goal: Integrate management strategies specific to pedestrian traffic within a Dynamic Traffic Management System (DTMS).**



# Framework

fig/framework.pdf





# Strategies

What specific measures can be considered to impact dynamics:

- Adjustments to the PT schedule
- Control access to specific areas  $\Rightarrow$  **gates**
- Change link travel time  $\Rightarrow$  moving walkways
- Prevent counter flow  $\Rightarrow$  **flow separators**
- Attract pedestrians to specific locations



# Existing strategies

## Pedestrian management

- Little research on specific strategies.
- Some static measures (design) have been studied.

## Road traffic management

- Ramp metering
- Perimeter control
- Variable message signs
- Traffic lights
- ...



# Proposed management strategies



# Proposed strategies

## Gating

Prevent excess travel time in junctions.

## Flow separators

Avoid counter flow in corridors.



# Proposed management strategies

## Gating



# Objective

At corridor intersections, highly disordered flows takes place.



Prevent too many individuals from crossing the intersection simultaneously (qualitative). → Prevent increase in travel time.



Measure pedestrian density (quantitative). → How ?



# Measurement

Some possibilities for measuring density:

## Pedestrian accumulation

- snapshot

## Voronoi based

- snapshot

## Edie's definition

- average over time



# Measurement

Some possibilities for measuring density:

## Pedestrian accumulation

- snapshot
- sensitive to delimited area

## Voronoi based

- snapshot
- expensive to compute

## Edie's definition

- average over time
- sensitive to delimited area





# Measurement

Some possibilities for measuring density:

## Pedestrian accumulation

- snapshot
- sensitive to delimited area
- provides average values

## Voronoi based

- snapshot
- expensive to compute
- provides individual values
- aggregation may be required

## Edie's definition

- average over time
- sensitive to delimited area
- provides average values
- strong physical interpretation



# Measurement

The indicator used is the following:

For a density threshold  $\bar{\rho}$ ,  
for a given snapshot taken at time  $t$ ,  
count the number of individuals where  $\rho_i(t) > \bar{\rho}$ .

This gives a pedestrian-centric measurement (nearly) independent of any “zone”.



# Setup

The level-of-service must be measured and controlled inside area A.

fig/gating-zone.pdf



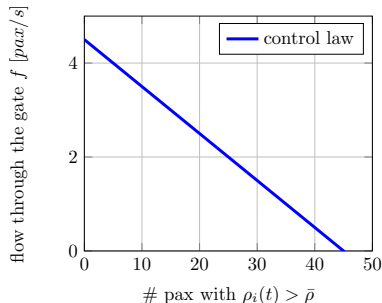
# Control law

## Parameters

- density threshold:  $\bar{\rho}$
- uncontrolled flow:  $f(0)$
- cut off value:  $f(?) = 0$

## Calibration based on:

- fundamental diagram
- distribution of individual densities





# Proposed management strategies

## Flow separators



# Objective

Head-on-head “collisions” induce significant extra travel time.



Reduce this counter-flow to a minimum.



Dynamically allocate part of the available corridor width to each direction.



# Setup

fig/flow-separator-figure.pdf



Width available for each direction is proportional to flows:

$$w_{AB} = \begin{cases} w \cdot f_{min,AB}, & \text{if } \frac{\sum q_{in,A}}{\sum q_{in,A} + \sum q_{in,B}} \leq f_{min,AB} \\ w \cdot f_{max,AB}, & \text{if } \frac{\sum q_{in,A}}{\sum q_{in,A} + \sum q_{in,B}} \geq f_{max,AB} \\ w \cdot \frac{\sum q_{in,A}}{\sum q_{in,A} + \sum q_{in,B}}, & \text{otherwise} \end{cases}$$





# Results



# Case study setup

## Gating

- crossed shaped junction
- demand pattern:
  - sinusoidal for two directions
  - uniform for other two

## Flow separators

- straight corridor
- shifted sine-shaped flows



## Case study setup

- Disaggregate pedestrian motion model: NOMAD.
- Graph-based route choice (but no significant role here).
- Multiple simulations runs.

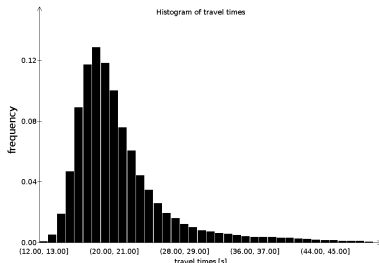


# Results

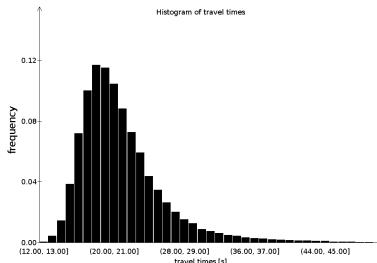
## Gating results



# Travel times



(a) Without gating



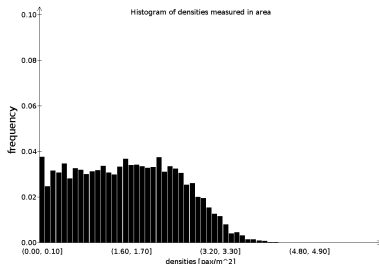
(b) With gating

No significant difference in mean travel time: 21.04s VS 21.18s

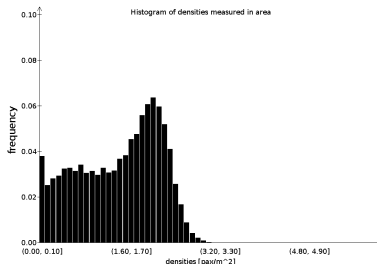
Reduction in travel time variance: 5.16s  $\rightarrow$  4.41s (−14%)



# Average density



(a) Without gating



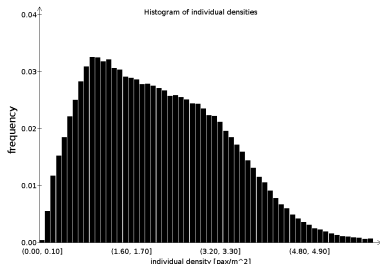
(b) With gating

## Decrease of

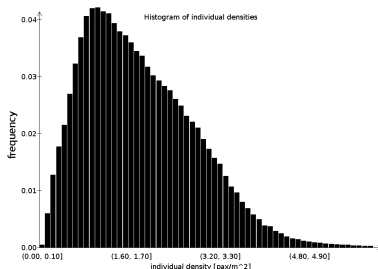
- mean density:  $1.57 \text{ pax/m}^2 \rightarrow 1.42 \text{ pax/m}^2$  ( $-9.5\%$ )
- density variance:  $0.93 \text{ pax/m}^2 \rightarrow 0.72 \text{ pax/m}^2$  ( $-22\%$ )



# Individual density



(a) Without gating



(b) With gating

## Decrease of

- mean density:  $2.18 \text{ pax/m}^2 \rightarrow 1.82 \text{ pax/m}^2$  ( $-16\%$ )
- density variance:  $1.22 \text{ pax/m}^2 \rightarrow 1.02 \text{ pax/m}^2$  ( $-16\%$ )



## Improvements

- less risk of gridlock.
- better level-of-service in the junction.

without increasing travel time.

## Open questions:

- shape of the control law ?
- parameter calibration ?
- can travel time be improved ?



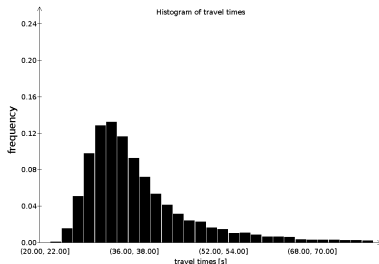


# Results

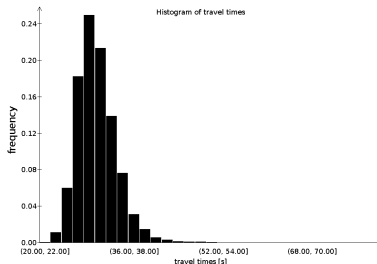
## Flow separators results



# Travel times



(a) Without flow separators



(b) With flow separators

## Significant improvement in

- mean travel time:  $37.86s \rightarrow 30.31s$  ( $-19\%$ )
- travel time variance:  $9.94s \rightarrow 3.39s$  ( $-66\%$ )



# Conclusion & next steps

## Conclusions

- Integration of two pedestrian control strategies in a DTMS.
- Gating improves the level-of-service and helps prevent gridlock.
- Flow separators significantly improves the travel time.

## Next steps

1. Investigate more complex control laws.
2. Model predictive control.
3. Simulation based optimization.
4. Dynamic control of accelerated moving walkways.



Thank you for your attention !

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