## Two-stage column generation

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# Outline

- Introduction
- Motivation
- VRP with Discrete Split Delivery
- Two-stage column generation
- Variable elimination
- Conclusion





Introduction

### Context

Dantzig-Wolfe (DW) reformulation of combinatorial problems

### Novel idea

Develop a framework in which a combinatorial problem is solved starting from a partial compact formulation, with the same approach used in column generation (CG) for the restricted extensive formulation, obtaining a partial restricted master problem.

The partial restricted master problem is called later on Partial Master Problem (PMP).





Algorithm 1: Two-stage column generation

#### repeat

#### repeat

| generate variables for partial master problem (CG1)
until until optimal PMP ;
generate variables for partial compact problem (CG2)
until until optimal MP ;





Many problems exhibit a compact formulation with many variables (possibly an exponential number) which results in an unmanageable associated pricing problem, when the extensive formulation is obtained through DW.

In particular we have identified the following real-world problems:

- TBAP with QC Assignment in maritime container terminals
- VRP with Discrete Split Delivery
- Field Technician Scheduling Problem
- Routing helicopters for crew exchanges on off-shore locations





TBAP with QC assignment in container terminals

Giallombardo, Moccia, Salani & Vacca (2008)

Problem description

- Tactical Berth Allocation Plan (TBAP): assignment and scheduling of ships to berths;
- Quay-Cranes (QC) assignment: a QC profile (number of QCs per shift) is assigned to each ship;
- feasible profiles can vary in length (number of shifts dedicated to the ship) and in size (number of QCs dedicated to the ship in each active shift);
- time windows on ship arrival and on berth availabilities.

### Objective

• Maximize the value of chosen profiles.





Ceselli, Righini & Salani (2007), Nakao & Nagamochi (2007)

**Problem description** 

- variant of VRP with split delivery;
- each customer demand is represented by one or more orders which consist of a set of items;
- demand can be split (discretized) but items cannot;
- some combinations of items are not allowed because of incompatibilities between items and vehicles, items and locations, etc.

### Objective

• Minimize the total travel costs.





# Field Technician Scheduling Problem

Xu & Chiu (2001)

### **Problem description**

- different types of jobs which require different skills;
- each technician is specialized in a field with certain skills;
- time windows on job starting and completion;
- assignment problem (jobs to technicians) + scheduling problem, where the duration of a job depends on the assignment.

### Objective

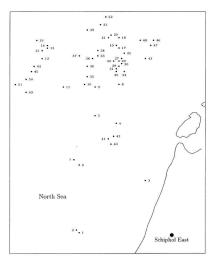
• Maximize the number of jobs completed within a time frame.





# Crew exchanges on off-shore locations

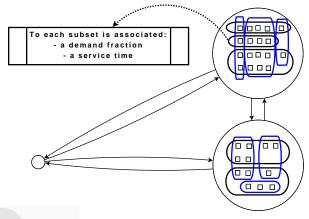
### Sierksma & Tijssen (1998)







# Modeling







- G = (V, E) complete graph with  $V = \{0\} \cup N$ ,  $(c_{ij}, t_{ij}) \forall (i, j) \in E$ ;
- *N* : set of customers {1,...,*n*};
- K : set of vehicles (capacity Q);

• 
$$R$$
 : set of items;  $R = \bigcup_{i \in N} R_i, R_i \cap R_j = 0 \ \forall i \neq j, i, j \in N;$ 

- C : set of combinations of items;  $C = \bigcup_{i \in N} C_i, \ C_i \cap C_j = \emptyset \ \forall i \neq j, \ i, j \in N;$
- $e_c^r$ : 1 if item  $r \in R$  is in combination  $c \in C$ ;
- $t_c$ : service time of combination  $c \in C$  with  $t_c \leq \sum_{r \in c} t_r$ ,  $t_c \geq t_r \ \forall r \in c$ ;
- $q_c$  : size of combination  $c \in C$ ;
- $[a_i, b_i]$ : time window for customer  $i \in N$ .





#### **Decision variables**

$$\begin{aligned} x_{ij}^k &= \begin{cases} 1 & \text{if arc } (i,j) \in E \text{ is used by vehicle } k \in K; \\ 0 & \text{otherwise.} \end{cases} \\ y_c^k &= \begin{cases} 1 & \text{if vehicle } k \in K \text{ delivers combination } c \in C; \\ 0 & \text{otherwise.} \end{cases} \end{aligned}$$

 $T_i^k$ : time when vehicle  $k \in K$  arrives at customer  $i \in N$ 

#### Constraints

- Flow and precedence constraints
- Demand-satisfaction constraints
- Time-windows constraints
- Capacity constraints





**Extensive formulation** 

$$\min \sum_{p \in P} c_p \lambda_p \tag{1}$$

$$\sum_{p \in P} e_p^r \lambda_p = 1 \qquad \forall r \in R$$
(2)

$$\sum_{p \in P} \lambda_p \le |\mathcal{K}| \tag{3}$$

$$\lambda_{p} \geq 0 \qquad \forall p \in P$$
 (4)

where:

- P : set of feasible sequences;
- *e<sup>r</sup><sub>p</sub>*: 1 if item *r* ∈ *R* is delivered in sequence *p* ∈ *P* and 0 otherwise;
- $c_p$  : cost of sequence  $p \in P$ .





**Pricing problem** 

$$p^{*} = \arg\min_{p \in P} \{\tilde{c}_{p}\} = \arg\min_{p \in P} \{c_{p} - \sum_{r \in R} \pi_{r} e_{p}^{r} - \pi_{0}\} \quad (5)$$

#### **Network formulation**

- elementary resource constrained shortest path problem (ERCSPP)
- one node for each variable  $y_c$





### Algorithm

- start with a subset of variables  $y_c$  in C' (heuristic);
- compute a bound of the reduced cost for variables  $y_c \notin C'$ ;
- add the most profitable variable;
- iterate.





### Advantages

- the pricing problem is easier to solve
- possibly many sub-optimal compact variables are left out from the formulation

#### Drawbacks

• we don't obtain a valid lower bound





### Possible solution to LB computation

Add some ad-hoc artificial variables  $y_c^{art}$  to the partial compact formulation.

In particular, we create artificial super-optimal subset of items by combining variables  $y_c$  not yet in the partial compact formulation such that:

- they cover the maximum number of items;
- with the minimum service time;
- with the minimum total size.





Given an integer linear program (IP) with an upper bound UB, with objective min  $c^T x$  and constraints  $Ax \ge b, x \in \mathbb{Z}_+^n$ , let  $\pi$  be a feasible solution to the dual of the linear programming relaxation of (IP).

### Theorem (Nemhauser & Wolsey, 1988)

If the reduced cost of a non-negative integer variable exceeds a given optimality gap, the variable must be zero in any optimal integer solution. In other words:

$$\tilde{c}_e = (c - \pi A)_e > UB - \pi b \implies x_e = 0$$
 (6)





### Theorem (Irnich et al., 2007)

If the minimum reduced cost of all path variables of a DW master problem containing arc (i,j) exceeds a given optimality gap, no path that contains arc (i,j) can be used in an optimal solution. Hence, the arc (i,j) can be eliminated. In other words:

$$\min_{P \in \mathcal{F}_{ij}^{st}} \tilde{c}_P(\pi) > UB - \pi b \implies x_{ij} = 0$$
(7)

where  $\mathcal{F}_{ii}^{st}$  is the set of feasible s - t paths containing arc (i, j).





Let the restricted master problem (MP) be defined on the whole set C and let the partial restricted master problem (PMP) be defined on a subset of combinations  $C' \subset C$ .

Let UB be an upper bound for both MP and PMP, let LB be a lower bound for MP and LB' be a lower bound for PMP, with  $LB' \ge LB$ .

Let  $\pi$  be a feasible dual solution to MP and  $\pi'$  be a feasible dual solution to PMP.

#### We define the following quantities:

$$Ib_{c} = LB + \min_{p \in \mathcal{F}_{c}} \tilde{c}_{p} = LB + \min_{p \in \mathcal{F}_{c}} \{c_{p} - \sum_{r \in R} e_{p}^{r} \pi_{r}^{*} - \pi_{0}^{*}\}$$
(8)

$$Ib'_{c} = LB' + \min_{\rho \in \mathcal{F}'_{c}} \tilde{c}_{\rho} = LB' + \min_{\rho \in \mathcal{F}'_{c}} \{c_{\rho} - \sum_{r \in R} e_{\rho}^{r} \pi_{r}^{**} - \pi_{0}^{**}\}$$
(9)

where:

- $\mathcal{F}_c = \{ \text{ (subset of) feasible sequences in } P = P(C) : y_c = 1 \}$
- $\mathcal{F}'_c = \{ \text{ (subset of) feasible sequences in } P = P(C') : y_c = 1 \}$





#### Variable elimination

$$lb_c > UB \implies y_c = 0$$
 in optimal MP (over C)  
 $lb'_c > UB \implies y_c = 0$  in optimal PMP (over C')

### Question

#### Can variable elimination in PMP be extended to MP?

	PMP	MP
А	true	true
В	true	false
С	false	true
D	false	false





#### Facts

- PMP is contained in MP
- *LB*′ ≥ *LB*

### Conjecture

$$lb_c' \ge lb_c$$
 (10)

- Conjecture true  $\implies$  (C) never occurs.
- Unfortunately (B) is possible.





# Compact variable generation

#### Algorithm 2: y<sub>c</sub> - Compact variable generation

```
repeat
           repeat
                        generate variables for partial master problem (CG1)
           until until optimal PMP ;
           repeat
                       \hat{y}_{c} = \min_{y_{c} \in C \setminus C'} \{ (c_{ki} + c_{ij} - c_{kj} | k \neq j, c \in C_{i}) - \sum_{r} e_{c}^{r} \pi_{r} \}
                       if \min_{p \in \mathcal{F}'_{C' \cup C}} \{ \tilde{c}_p \} < 0 then
                                   add column p and \hat{y}_c to C'
                        else
                                   if \min_{p \in \mathcal{F}'_{\mathcal{C}}} \{ \tilde{c}_p \} \le UB - LB then
                                               add \hat{y}_c to C'
                                   else
                                              \begin{array}{l} \text{if } \min_{\substack{\rho \in \mathcal{F}'_{\mathcal{C} \cup \mathcal{Y}_{\mathcal{C}}^{art}}} \{\tilde{c}_{\rho}\} > UB - LB \text{ then} \\ | & \text{fix variable } \hat{y}_{\mathcal{C}} \text{ to } 0 \end{array}
                                               else
                                                          add \hat{y}_c to C'
                                                end
                                    end
                        end
           until until some y_c has been added to C' or C \setminus C' = \emptyset;
until until all y_c are either in C' or fixed to 0;
```





- Exact algorithm for the Discrete SDVRP based on Branch&Price
- Pricing solved using bi-directional dynamic programming with DSSR
- Estimation of  $lb'_c$  via dynamic programming with DSSR
- Not sophisticated branching rules: vehicles first, arcs next
- No massive pricing, No additional cuts at master level





# Preliminary results (qualitative)

- Instances derived from Solomon data set for the VRPTW (few **manually** generated instances)
- Instances with sub-optimal compact variables are correctly detected
- (+) The overall pricing time has been reduced
- (+) The number of generated columns has been reduced as well
- (-) The method is sensitive to initialization
- (?) Even with no eliminated compact variables the overall number of generated columns is smaller





Two stage column generation:

- Methodology to accelerate an overall B&P algorithm via generation of compact formulation variables
- Useful when the compact formulation exhibits a large number of variables, but **not only**

Outlook:

• Full validation of the model

**CTW** is a great conference, we had feedback **before** the talk! (apparently) There is a better method to estimate  $lb'_c$ , see you next year!



