Fast Algorithms for Capacitated Continuous Pricing with Discrete Choice Demand Models

Tom Haering Fabian Torres Michel Bierlaire

Transport and Mobility Laboratory School of Architecture, Civil and Environmental Engineering Ecole Polytechnique Fédérale de Lausanne

2nd EPFL Symposium on Transportation Research, Barcelona 5-7 February 2024



Outline

Introduction

- Methodology
- Experimental Results
- Conclusions





TH, FT, MB (EPFL)

Fast Algorithms for the capacitated CPP

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ June 22, 2023

CPP

The Continuous Pricing Problem (CPP)

CPP

- Supplier offers J products for sale. Goal: determine optimal price for each product to maximize total profit.
- There always exists an opt-out option (competition, etc).
- Demand for each product is modeled using a discrete choice model (DCM).

DCM

• For every **costumer** *n* and **product** *i* a stochastic **utility** *U*_{*in*} is defined, which depends on **socio-economic** characteristics of the individual and attributes of the products (e.g. the price).



CPP

The Continuous Pricing Problem (CPP)

Utility

• **Utility** of alternative *i* for costumer *n*:

$$U_{in} = \sum_{k \neq p} \beta_k x_{ink} + \beta_p p_i + \varepsilon_{in}$$

- β_k : parameters (exogenous)
- *x_{ink}* : attributes (exogenous)
- *p_i* : price of alternative *i*
- ε_{in} : stochastic error term



CPP

The Continuous Pricing Problem (CPP)

Probability

• **Probability** that costumer *n* chooses alternative *i*:

$$\mathsf{P}_n(i) = \mathbb{P}(U_{in} \geq U_{jn} \ \forall j \in J)$$

• Logit ($\varepsilon_{in} \sim \text{i.i.d. Gumbel}(0, 1)$):

$$P_n(i) = \frac{e^{V_{in}}}{\sum_{j \in C_n} e^{V_{jn}}}$$

Mixed Logit (Logit + $\beta_k \sim F(\beta_k | \theta)$): •

$$P_n(i) = \int \frac{e^{V_{in}(\beta_{kn})}}{\sum_{j \in C_n} e^{V_{jn}(\beta_{kn})}} f(\beta_k | \theta) d\beta_k$$

TH, FT, MB (EPFL)

▲□▶ ▲□▶ ▲ヨ▶ ▲ヨ▶ ヨヨ ののの

Literature

Integrating Logit into ...

- Facility location [Mai and Lodi, 2017, Ljubić and Moreno, 2018]
- Revenue Management [Shen and Su, 2007, Korfmann, 2018]
- Railway Timetabling [Cordone and Redaelli, 2011, Robenek et al., 2018]

Integrating Nested Logit into...

- Toll setting [Wu et al., 2012]
- Pricing [Gallego and Wang, 2014]

Integrating Mixed Logit into...

- School location [Haase and Müller, 2013]
- Toll setting [Gilbert et al., 2014]
- Pricing [Marandi and Lurkin, 2020, van de Geer and den Boer, 2022]

Literature

Integrating general DCM into optimization problems

- Formulation as a mixed-integer-linear program (MILP) using Monte-Carlo simulation [Paneque et al., 2021]
- Heuristic based on Lagrangian decomposition and grouping of scenarios [Paneque et al., 2022]
- Heuristic based on Benders decomposition (w/out capacity constraints) [Haering et al., 2022]
- Exact method based on spatial Branch-and-Bound and Benders decomposition (w/out capacity constraints) [Haering et al., 2023]

So are we done?

• No. We want to go faster. In general. And include capacity constraints.

Outline

- Introduction
- Methodology
- Experimental Results
- Conclusions





TH, FT, MB (EPFL)

Fast Algorithms for the capacitated CPP

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ June 22, 2023

Base layer: Monte Carlo Simulation

• Simulate *R* scenarios (draws), each with deterministic utilities *U*_{inr}:

$$U_{inr} = \sum_{k \neq p} \beta_k x_{ink} + \beta_p p_i + \varepsilon_{inr} \quad \forall n \in \mathcal{N}, i \in C_n, r \in \mathcal{R}$$
$$= c_{inr} + \beta_p p_i \qquad \forall n \in \mathcal{N}, i \in C_n, r \in \mathcal{R}$$





Breakpoints

Breakpoints

- **Don't worry**. We're not doing *complicated* decomposition methods or actual *math*.
- Instead we will use the simple idea of decision making breakpoints.





10 / 27

4 E b

→ ∃ →

Breakpoints: Illustration

- 1 customer, 1 controlled price + opt-out
- Breakpoint p
 ₁:



Breakpoints: Illustration II

- 3 customers, 1 controlled price + opt-out
- Numbers: how many customers are captured



Breakpoint Exact Algorithm (BEA) [Haering et al., 2023]

Simplified:

For all possible orderings of prices $p_1 \leq p_2 \leq \cdots \leq p_J$ do:

- Introduce the **cheapest** alternative 1.
- Compute the breakpoints p
 ₁^s (from U_{0s} = U_{1s}) for all simulated customers s.
- Iterate over all breakpoints \overline{p}_1^s , highest to lowest. For each \overline{p}_1^s , fix $p_1 = \overline{p}_1^s$ and do:
 - Introduce alternative 2. Now compute the breakpoints p
 ₂^s (from max(U_{0s}, U_{1s}) = U_{2s}).
 - Iterate over all breakpoints \overline{p}_2^s , highest to lowest. For each \overline{p}_2^s , fix $p_2 = \overline{p}_2^s$ and do:
 - Introduce alternative **3**. ...
 - Once all prices are fixed, compute profit

Keep the price combination with highest profit!

BFA

- Very fast for one or two alternatives, then it rapidly breaks down.
- Complexity $O(J!(NR)^J log(NR))$ exponential in number of alternatives 1
- Our new contributions:
 - 1. Extend BEA to include capacity constraints
 - 2. Introduce Breakpoint Heuristic Algorithm (BHA) to solve high-dimensional problems much faster (and with high accuracy!)



Extending the BEA

Capacity constraints

 Need to compute breakpoints from not only max(U_{0s},..., U_{(i-1)s},) = U_{is}) but from all U_{js} = U_{is} separately, due to people no longer always choosing highest utility alternative.





Breakpoint Exact Algorithm with Capacities (BEAC)

For all possible orderings of prices $\{p_1, p_2, \dots, p_J\}$ do:

- Introduce the **cheapest** alternative 1.
- Compute the breakpoints p
 ₁^s (from U_{0s} = U_{1s}) for all simulated customers s.
- Iterate over all breakpoints \overline{p}_1^s . For each \overline{p}_1^s , fix $p_1 = \overline{p}_1^s$ and do:
 - Introduce alternative **2**. Now compute the breakpoints $\overline{p}_{02}^{s}, \overline{p}_{12}^{s}$ (from $U_{0s} = U_{2s}$ and $U_{1s} = U_{2s}$).
 - Iterate over all breakpoints \overline{p}_{x2}^{s} . For each, fix $p_{2} = \overline{p}_{x2}^{s}$ and do:
 - Introduce alternative 3. ...
 - Once all prices are fixed, compute capacitated profit

Keep the price combination with highest profit!

Computing the capacitated profit

- Having to compute the profit for each price combination is computationally expensive, but:
- It adds flexibility as to how we evaluate the profit
- We propose three different strategies:
 - 1. Based on an exogenous priority queue
 - 2. Supplier controls access and assigns people in such a way that maximizes total profit
 - 3. Same as 2. but now we want to minimize profit. Finding the price such that the worst-case profit is highest = **robust optimization**



Breakpoint Heuristic Algorithm (BHA)

- 1. Choose starting point for the heuristic, ex. $p^* = \left(\frac{p_i^L + p_i^U}{2}\right)_{i \in C}$.
- 2. $o^* = \text{compute_objective_function}(p^*)$.
- 3. Set j = 1.
- Fix the bounds to be = p* except for alternative j and solve this simplified problem using the BEA / BEAC. If the resulting (p̂, ô) is better than (p*, o*), set p* = p̂, o* = ô.
- 6. Set j = j + 1 and repeat from step 4. If j = J then set j = 1.
- 7. Terminate after no improvement is found over J iterations.
- ... i.e., a **coordinate descent** (ascent).

BHA extended via dynamic line search (DLS)

Idea: escape local optima by adding small controlled perturbations in starting point.

- Base point = solution from BHA.
- Change one coordinate by δ and start BHA from there.
- If the BHA converges to a better solution than the best known, make it the **new base point**.
- Iterate through all coordinates.
- Gradually increase the search distance δ along each direction until a maximal step size is reached.

<<p>A 目 > A 目 > A 目 > 目 = のQQ

Outline

- Introduction
- Methodology
- Experimental Results
- Conclusions





TH, FT, MB (EPFL)

Fast Algorithms for the capacitated CPP

June 22, 2023

Case Study

Parking space operator [lbeas et al., 2014]

- Alternatives: Paid-Street-Parking (PSP), Paid-Underground-Parking (PUP) and Free-Street-Parking (FSP).
- Optimize prices for PSP and PUP, FSP is the **opt-out** alternative.
- **Socio-economic characteristics**: trip origin, vehicle age, driver income, residence area.
- **Product attributes**: access time to parking, access time to destination, and parking fee (price).
- Choice model is a **Mixed Logit**, $\beta_{\text{fee}}, \beta_{\text{time_parking}} \sim \mathcal{N}(\mu, \sigma)$.



Results

Table 1: Test 1: MILP vs. BEAC in the capacitated case

			MIL	Р	BEAC		
Ν	R	J	Time (s)	Profit	Time (s)	Profit	
50	2	2	4.17	27.61	0.43	27.61	
50	5	2	46.95	26.51	1.72	26.51	
50	10	2	180.85	27.06	11.42	27.06	
50	25	2	3119.66	27.08	169.08	27.08	
50	50	2	>5 hours	\geq 25.15	1272.68	26.85	
50	100	2	>25 hours	\geq 25.11	9928.57	26.85	
50	250	2	>45 hours	\geq 23.45	>45 hours	\geq 25.00	

TH, FT, MB (EPFL)

June 22, 2023

Results

Table 2: Test 3: BHA and DLS vs. B&BD and BEA in the uncapacitated case

			B&BD		BEA		BHA		DLS	
Ν	R	J	Time (s)	Profit	Time (s)	Profit	Time (s)	Profit	Time (s)	Profit
20	100	4	12478	10.40	>24 hours	≥9.81	0.00	10.40	0.14	10.40
20	200	4	29213	10.40	>24 hours	≥ 10.40	0.01	10.40	0.41	10.40
20	300	4	$>\!\!24~{\rm hours}$	≥ 10.38	$>\!\!24$ hours	≥ 10.13	0.02	10.24	0.64	10.24
20	400	4	>24 hours	\geq 9.81	>24 hours	≥9.42	0.05	10.26	0.78	10.26
20	500	4	$>\!\!24~{\rm hours}$	\geq 10.01	$>\!\!24~{\rm hours}$	≥ 9.67	0.13	10.24	1.37	10.24

Results

Table 3: Test 4: BHA and DLS vs. MILP and BEAC in the capacitated case

			MILP		BEAC		BHA		DLS	
Ν	R	J	Time (s)	Profit	Time (s)	Profit	Time (s)	Profit	Time (s)	Profit
50	2	2	4.17	27.61	0.43	27.61	0.22	27.61	1.03	27.61
50	5	2	46.95	26.51	1.72	26.51	0.32	26.46	5.91	26.51
50	10	2	180.85	27.06	11.42	27.06	0.58	27.05	20.34	27.06
50	25	2	3119.66	27.08	169.08	27.08	3.40	27.05	129.66	27.08
50	50	2	>5 hours	≥ 25.15	1272.68	26.85	8.31	26.53	559.04	26.85
50	100	2	>25 hours	≥ 25.11	9928.57	26.85	51.77	26.72	2791.28	26.85
50	250	2	>45 hours	≥23.45	>45 hours	≥25.00	455.37	26.66	15867.67	26.71
50	10	4	$>\!\!10$ hours	≥22.21	$>\!\!10$ hours	≥25.41	7.08	26.78	527.34	26.83
50	50	4	>20 hours	≥ 22.19	>20 hours	≥27.00	166.21	27.00	7234.88	27.00
50	100	4	>45 hours	≥20.50	>45 hours	≥24.86	866.97	26.67	34050.57	26.67
50	200	4	$>\!\!72 \text{ hours}$	\geq 20.32	$>\!\!72 \text{ hours}$	\geq 24.79	2762.39	26.70	106286.13	26.70

TH, FT, MB (EPFL)

June 22, 2023

<ロ> <四> <日> <日> <日> <日> <日> <日> <日</p>

Outline

- Introduction
- Methodology
- Experimental Results
- Conclusions





Conclusions

- Exact method: BEAC \approx 20 times faster than MILP
- Heuristic: BHA \approx 100-5000 times faster than MILP with capacities
- Heuristic: BHA several orders of magnitudes times faster than MILP and B&BD without capacities
- BHA optimality gaps < 0.2%.
- DLS finds **global optimum**, but **too inefficient**. Alternatives should be explored.



Thank you for your attention!



TH, FT, MB (EPFL)

Fast Algorithms for the capacitated CPP

June 22, 2023

Appendix

Table 4: Utility parameters reported	ed in [lbeas et al., 2014]
Parameter	Value
ASC _{FSP}	0.0
ASC _{PSP}	32.0
ASC _{PUP}	34.0
Fee (€)	$\sim \mathcal{N}(-32.328, 14.168)$
Fee PSP - low income (\in)	-10.995
Fee PUP - low income (€)	-13.729
Fee PSP - resident (€)	-11.440
Fee PUP - resident (€)	-10.668
Access time to parking (min)	$\sim \mathcal{N}(-0.788, 1.06)$
Access time to destination (min)	-0.612
Age of vehicle $(1/0)$	4.037
Origin $(1/0)$	-5.762

TH, FT, MB (EPFL)

Fast Algorithms for the capacitated CPP

MILP formulation [Paneque et al., 2021]

$$\begin{split} \max_{p,\omega,U,h} \frac{1}{R} \sum_{r \in \mathcal{R}} \sum_{n \in \mathcal{N}} \sum_{i \in C_n} p_i \omega_{inr} & (o) \\ \text{s.t.} & \\ \sum_{i \in C_n \cup \{0\}} \omega_{inr} = 1 & \forall n \in \mathcal{N}, r \in \mathcal{R} & (\mu_{nr}) \\ h_{nr} = c_{0nr} \omega_{0nr} + \sum_{i \in C_n} U_{inr} \omega_{inr} & \forall n \in \mathcal{N}, r \in \mathcal{R} & (\zeta_{nr}) \\ h_{nr} \ge c_{0nr} & \forall n \in \mathcal{N}, r \in \mathcal{R} & (\alpha_{0nr}) \\ h_{nr} \ge U_{inr} & \forall i \in C_n, n \in \mathcal{N}, r \in \mathcal{R} & (\alpha_{inr}) \\ U_{inr} = c_{inr} + \beta_p^{in} p_i & \forall i \in C_n, n \in \mathcal{N}, r \in \mathcal{R} & (\kappa_{inr}) \\ \omega \in \{0, 1\}^{(J+1)NR} & \\ p \in [p_1^L, p_1^U] \times \ldots \times [p_J^L, p_J^U] \\ U, h \in \mathbb{R}^{JNR}, \mathbb{R}^{NR} \end{split}$$

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Breakpoint Exact Algorithm (BEA) [Haering et al., 2023]

Algorithm 1: Breakpoint Exact Algorithm (BEA) to solve the CPP

Result: optimal solution p^* and profit o^* for CPP. $p_i^* \leftarrow 0 \quad \forall j \in \{1, \ldots, J\}$ $o^* \leftarrow 0$ for s in S do $p_{s_i} \leftarrow 0 \quad \forall j \in \{1, \ldots, J\}$ $h_{nr}^{s_1} \leftarrow c_{0nr} \quad \forall (n,r) \in \mathcal{N} \times \mathcal{R}$ $\eta_{nr} \leftarrow 0 \quad \forall (n,r) \in \mathcal{N} \times \mathcal{R}$ $(\hat{p}, \hat{o}) \leftarrow \texttt{enumerate}(s, p, h^{s_1}, \eta, 1)$ if $\hat{o} > o^*$ then $p^* \leftarrow \hat{p}; \ o^* \leftarrow \hat{o};$ end end

return (p^*, o^*)

Recursive enumeration function within BEA

Algorithm 2: Recursive enumeration function within BEA

```
Function enumerate (s, p, h^{s_j}, \eta, j):
       p_{s_i} \leftarrow p_{s_i}^U
       \vec{p}_{s_j}^{nr} \leftarrow \frac{h_{nr}^{\gamma} - c_{s_jnr}}{\beta_n^{s_n^{\gamma}}} \quad \forall (n, r) \in \mathcal{N} \times \mathcal{R}
       \mathcal{N}_1 \leftarrow \{(n,r) | \bar{p}_{\epsilon}^{nr} \ge p_{\epsilon}^U \}
       \mathcal{N}_2 \leftarrow \{(n, r) | \max\{p_{s_j}^L, p_{s_{j-1}}\} < \bar{p}_{s_j}^{nr} < p_{s_j}^U\}
        \begin{array}{c} h_{nr}^{\tilde{s}_{j+1}} \leftarrow h_{nr}^{\tilde{s}_{j}} \quad \forall (n,r) \in \mathcal{N} \times \mathcal{R} \setminus \mathcal{N}_{1} \\ h_{nr}^{\tilde{s}_{j+1}} \leftarrow c_{s_{i}nr} + \beta_{p}^{s_{j}n} p_{s_{i}}^{U} \quad \forall (n,r) \in \mathcal{N}_{1} \end{array} 
        \eta_{nr} \leftarrow p_{s_i}^U \quad \forall (n, r) \in \mathcal{N}_1
        o^* \leftarrow \sum_{n \in N}^{j} \sum_{r \in R} \eta_{nr}
        p^* \leftarrow \overline{p}
       Sort the elements of N_2 so that \bar{p}_{s_i}^{n_1r_1} \ge \bar{p}_{s_i}^{n_2r_2} \ge \cdots \ge \bar{p}_{s_i}^{n_{|N_2|}r_{|N_2|}}
       if j \leq J - 1 then
              for i \in \{1, ..., |N_2|\} do
                         p_{si} \leftarrow \bar{p}_{si}^{n_i r_i}
                          h_{nr}^{s_{j+1}} \leftarrow c_{s_inr} + \beta_p^{s_jn} p_{s_i} \quad \forall (n, r) \in \{(n_1, r_1), \dots, (n_i, r_i)\} \cup N_1
                         \eta_{nr} \leftarrow p_{s_i} \quad \forall (n, r) \in \{(n_1, r_1), \dots, (n_i, r_i)\} \cup \mathcal{N}_1
                         (\hat{p}, \hat{o}) \leftarrow \text{enumerate}(s, p, h^{s_{j+1}}, n, i+1)
                          if \hat{o} > o^* then
                             o^* \leftarrow \hat{o}
                                 p^* \leftarrow \hat{p}
                         end
                end
        end
        else
             \tilde{o} \leftarrow o^* - \sum_{(n,r) \in N_1} \eta_{nr}
                for i \in \{1, ..., |N_2|\} do
                         \tilde{o} \leftarrow \tilde{o} - \eta_{n;r}
                          p_{s_i} \leftarrow \bar{p}_{s_i}^{n_i r_i}
                          o \leftarrow \tilde{o} + (|\mathcal{N}_1| + i)p_s
                          if o > o^* then
                                  o^* \leftarrow o
                                  p^* \leftarrow p
                         end
                 end
                return (p^*, o^*)
        end
end
```

TH, FT, MB (EPFL)

Capacity constraints

$$\begin{split} \omega_{inr} &\leq y_{inr} & \forall i \in \mathcal{C}_n, \in \mathcal{N}, r \in \mathcal{R} \\ \sum_{m=1}^n \omega_{imr} &\leq (c_i - 1)y_{inr} + \\ &(n - 1)(1 - y_{inr}) & \forall i \in \mathcal{C}_n, n > c_i \in \mathcal{N}, r \in \mathcal{R} \\ \sum_{m=1}^n \omega_{imr} &\geq c_i(1 - y_{inr}) & \forall i \in \mathcal{C}_n, n > 1 \in \mathcal{N}, r \in \mathcal{R} \end{split}$$



5/14

EPFL

Compute Objective Value with Priority Queue

Function

```
compute_objective_value_with_priority_queue(p, c, prio_queue):
     \varsigma \leftarrow (0)_{i \in C}
     for idx \in prio_queue do
           u \leftarrow [U_{idx}^i \text{ for } i \in C]
           a \leftarrow \text{sort}(u, \text{descending})
           \varphi \leftarrow \mathsf{false}
           i \leftarrow 1
           while j \leq C - 1 and !\varphi do
                 if \varsigma_{a_j} \leq c_{a_j} - 1 then
                       \dot{\varsigma}_{a_i} \neq 1
                       \varphi \leftarrow \mathsf{true}
                 end
                 else
                   | i + = 1
                 end
           end
     end
     o \leftarrow \sum_{i \in C} \varsigma_i \cdot p_i
     return o
end
```

ELE SQC

Compute Objective Value with Capacities (profit max/min)

```
Function compute_objective_value_with_capacities(p, c; max):
      s \leftarrow \text{sortperm}(p)
      \varsigma \leftarrow (0)_{i \in C}
      A \leftarrow \{\}
      for idx \in \mathcal{N} \times \mathcal{R} do
            u \leftarrow [U_{idx}^i \text{ for } i \in C]
            a \leftarrow \text{sort}(u, \text{descending})
          A \leftarrow A \cup \{a\}
      if max then
            A \leftarrow \text{sort}(A, \text{ascending})
      else
        | A \leftarrow sort(A, descending)
      while |A| \ge 1 do
            \pi \leftarrow A_{11}
            A \leftarrow A \setminus \{A_1\}
            if \pi > 1 then
                  \varsigma_{s_{next,pref}} += 1
                  if \varsigma_{s_{next,pref}} = c_{s_{next,pref}} then
Remove all entries \pi from A
                         if max then
                               A \leftarrow \text{sort}(A, \text{ascending})
                         else
                            A \leftarrow \text{sort}(A, \text{descending})
      o \leftarrow \sum_{i \in C} \varsigma_i \cdot p_i
      return o
```

TH, FT, MB (EPFL)

⇒ ↓ ≡ ↓ ≡ ⊨ √ Q ∩

Table 5: Test 2: Priority queue vs. Max profit vs. Robust Optimization

			BEA	С	BEAC	-M	BEAC-R	
Ν	R	J	Time (s)	Profit	Time (s)	Profit	Time (s)	Profit
50	2	2	0.43	27.61	0.44	28.81	0.45	27.61
50	5	2	1.72	26.51	1.78	28.44	1.82	26.46
50	10	2	11.42	27.06	12.88	28.3	12.98	27.01
50	25	2	169.08	27.08	197.23	28.58	189.28	27.06
50	50	2	1272.68	26.85	1513.44	28.61	1523.89	26.85
50	100	2	9928.57	26.85	12093.8	28.57	12494.13	26.85
50	250	2	$>\!\!45~{\rm hours}$	\geq 25.00	$>\!\!45~{\rm hours}$	$\geq \! 26.63$	$>\!\!45~{\rm hours}$	\geq 24.34

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Bibliography I



Cordone, R. and Redaelli, F. (2011).

Optimizing the demand captured by a railway system with a regular timetable.

Transportation Research Part B: Methodological, 45(2):430–446.

 Gallego, G. and Wang, R. (2014).
 Multiproduct price optimization and competition under the nested logit model with product-differentiated price sensitivities.
 Operations Research, 62(2):450–461.

Gilbert, F., Marcotte, P., and Savard, G. (2014). Mixed-logit network pricing.

Computational Optimization and Applications, 57:105–127.



EPFL

(4回) (三) (三) (三) (三) (○) (○)

Bibliography II



Haase, K. and Müller, S. (2013).

Management of school locations allowing for free school choice. *Omega*, 41(5):847–855.

Haering, T., Bongiovanni, C., and Bierlaire, M. (2022).

A benders decomposition for maximum simulated likelihood estimation of advanced discrete choice models.

In Proceedings of the 22nd Swiss Transport Research Conference (STRC).

Haering, T., Legault, R., Torres, F., Ljubic, I., and Bierlaire, M. (2023).

Exact algorithms for continuous pricing with advanced discrete choice demand models.

(4回) (三) (三) (三) (三) (○) (○)

Bibliography III

Technical Report TRANSP-OR 231211, Transport and Mobility Laboratory, Ecole Polytechnique Fédérale de Lausanne, Lausanne, Switzerland.

Ibeas, A., Dell'Olio, L., Bordagaray, M., and Ortúzar, J. d. D. (2014).
 Modelling parking choices considering user heterogeneity.
 Transportation Research Part A: Policy and Practice, 70:41–49.

Korfmann, F. (2018).

Essays on Advanced Discrete Choice Applications. PhD thesis, Staats-und Universitätsbibliothek Hamburg Carl von Ossietzky.

Ljubić, I. and Moreno, E. (2018).

Outer approximation and submodular cuts for maximum capture facility location problems with random utilities. ERANSPER Journal of Operational Research, 266(1):46–56.

TH, FT, MB (EPFL)

Bibliography IV



Mai, T. and Lodi, A. (2017).

Solving large-scale competitive facility location under random utility maximization models.

In Technical Report. CERC, Polytechnique Montréal, Canada.

Marandi, A. and Lurkin, V. (2020).

An exact algorithm for the static pricing problem under discrete mixed logit demand.

arXiv preprint arXiv:2005.07482.

Paneque, M. P., Bierlaire, M., Gendron, B., and Azadeh, S. S. (2021). Integrating advanced discrete choice models in mixed integer linear optimization.

Transportation Research Part B: Methodological, 146:26–49. RANSP-OR

Bibliography V

- Paneque, M. P., Gendron, B., Azadeh, S. S., and Bierlaire, M. (2022). A lagrangian decomposition scheme for choice-based optimization. *Computers & Operations Research*, 148:105985.
- Robenek, T., Azadeh, S. S., Maknoon, Y., de Lapparent, M., and Bierlaire, M. (2018).
 Train timetable design under elastic passenger demand.
 Transportation research Part b: methodological, 111:19–38.
- Shen, Z.-J. M. and Su, X. (2007).

Customer behavior modeling in revenue management and auctions: A review and new research opportunities.

Production and operations management, 16(6):713–728.



June 22, 2023

Bibliography VI

- van de Geer, R. and den Boer, A. V. (2022). Price optimization under the finite-mixture logit model. *Management Science*, 68(10):7480–7496.
- Wu, D., Yin, Y., Lawphongpanich, S., and Yang, H. (2012). Design of more equitable congestion pricing and tradable credit schemes for multimodal transportation networks. *Transportation Research Part B: Methodological*, 46(9):1273–1287.

