Choice with multiple alternatives -5.2Specification of the deterministic part

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Box-Cox transforms

The Box-Cox transform of a positive variable x, introduced by Box and Cox (1964), is defined as

$$x(\lambda) = \begin{cases} \frac{x^{\lambda} - 1}{\lambda} & \text{if } \lambda \neq 0\\ \log x & \text{if } \lambda = 0. \end{cases}$$
(1)

Note that

$$\lim_{\lambda \to 0} \frac{x^{\lambda} - 1}{\lambda} = \log x, \tag{2}$$

so that $x(\lambda)$ is continuous [Verify]. It can be embedded in the specification of a utility function:

$$V_{in} = \beta_k x_{ink}(\lambda) + \cdots, \qquad (3)$$

where both β_k and λ are estimated from data. Such a specification is not linear-in-parameters. Its flexibility allows to let the data tell if the variable is involved in a linear way ($\lambda = 1$), a logarithmic way ($\lambda = 0$) or as a power law.

If the variable x may take negative values, Box and Cox (1964) propose to shift it before the transform is applied:

$$x(\lambda, \alpha) = \begin{cases} \frac{(x+\alpha)^{\lambda} - 1}{\lambda} & \text{if } \lambda \neq 0\\ \log(x+\alpha) & \text{if } \lambda = 0, \end{cases}$$
(4)

where $\alpha > -x$.

There are other ways to impose the positivity of the argument of the transform. For instance, Manly (1976) suggests to use an exponential:

$$x(\lambda) = \begin{cases} \frac{e^{x\lambda} - 1}{\lambda} & \text{if } \lambda \neq 0\\ x & \text{if } \lambda = 0, \end{cases}$$
(5)

while John and Draper (1980) propose to use the absolute value:

$$x(\lambda) = \begin{cases} \operatorname{sign}(x) \frac{(|x|+1)^{\lambda}-1}{\lambda} & \text{if } \lambda \neq 0\\ \operatorname{sign}(x) \log(|x|+1) & \text{if } \lambda = 0. \end{cases}$$
(6)

A more complex transform has been proposed by Yeo and Johnson (2000):

$$x(\lambda) = \begin{cases} \frac{(x+1)^{\lambda}-1}{\lambda} & \text{if } \lambda \neq 0, x \ge 0;\\ \log(x+1) & \text{if } \lambda = 0, x \ge 0;\\ \frac{(1-x)^{2-\lambda}-1}{\lambda-2} & \text{if } \lambda \neq 2, x < 0;\\ -\log(1-x) & \text{if } \lambda = 2, x < 0. \end{cases}$$
(7)

Plenty of references are available in the literature. We refer the reader to Sakia (1992) for a review, and to Zarembka (1990) for a discussion in terms of model specification.

References

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